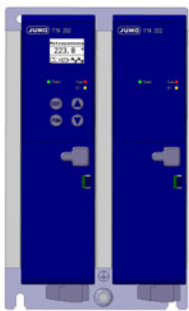
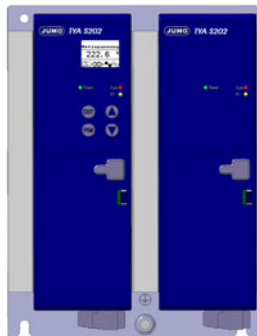


JUMO TYA S202

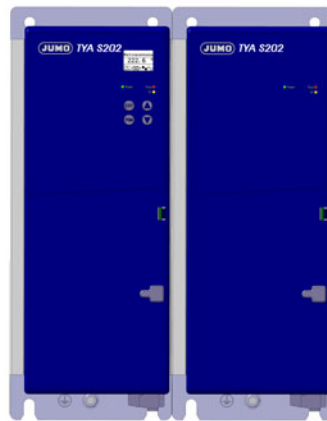
Thyristor power controller
in a three-phase economy circuit



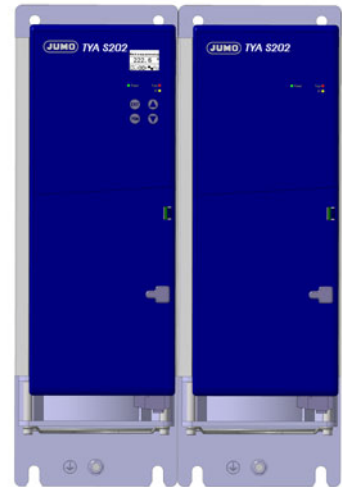
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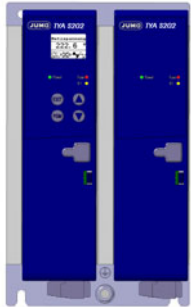
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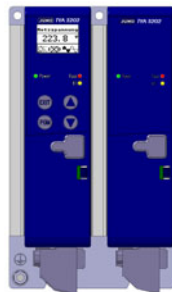
709066/X-01-150
709066/X-01-200



709066/X-01-250



709066/X-01-32



709066/X-01-020

Operating Manual

70906600T90Z001K000



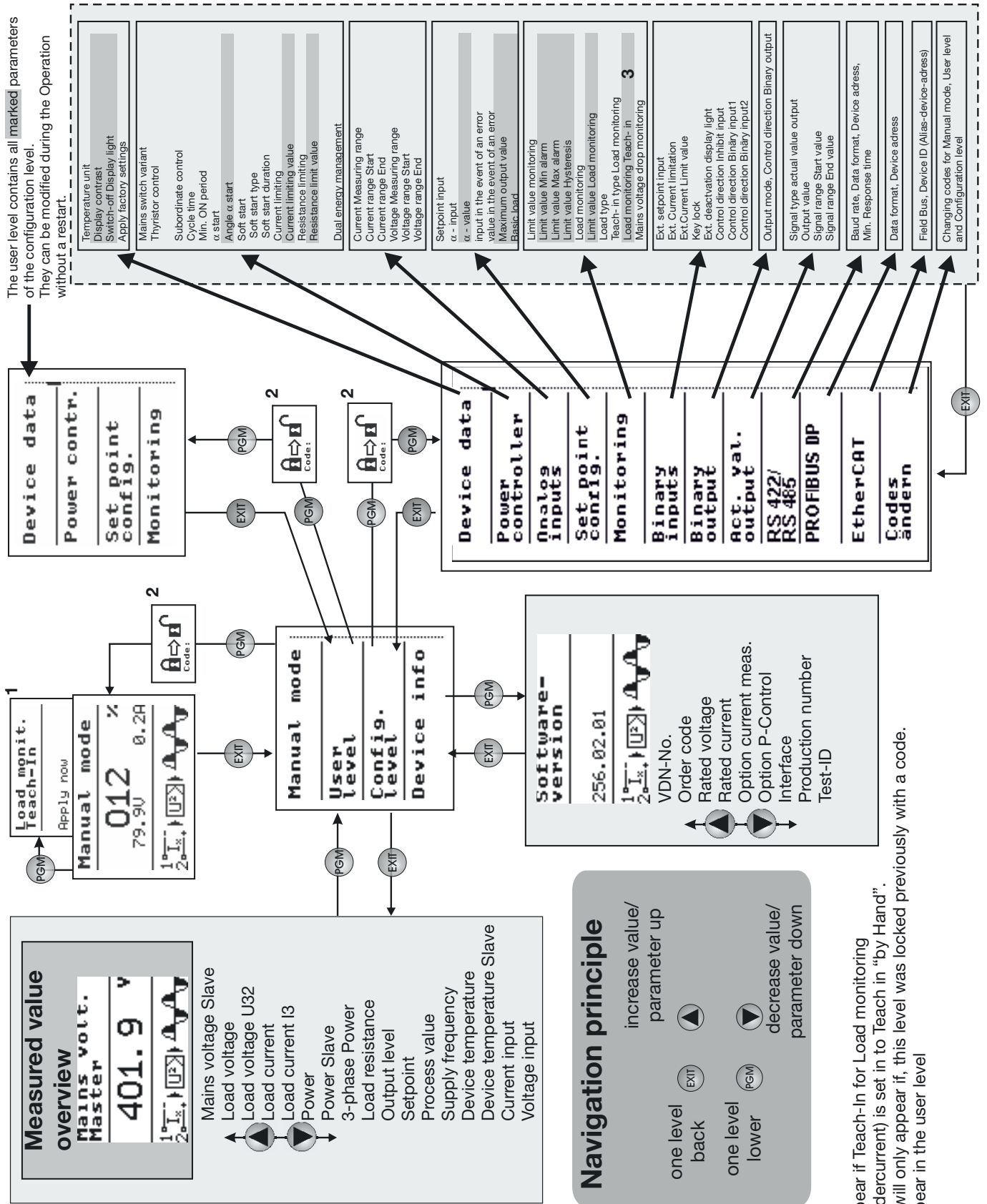
V2.00/EN/00709725/2021-06-11



All parameter settings are described in detail in the chapter "Configuration".

This operating overview shows all possible parameters of the device series.

Depending on the order specifications or current configuration, any parameters that are not required are hidden.



1. Will only appear if Teach-In for Load monitoring (Over- or Undercurrent) is set in to Teach in "by Hand".
2. Code-entry will only appear if, this level was locked previously with a code.
3. Will only appear in the user level

1	Introduction.....	9
1.1	Preface	9
1.2	Typographical conventions	10
1.2.1	Warning symbols	10
1.2.2	Note symbols	10
1.2.3	Performing an action	11
1.2.4	Display types	11
1.3	Order Details	12
1.3.1	Scope of delivery	12
1.3.2	Accessories	12
1.3.3	General accessories	13
1.4	Brief description	14
1.5	Standards, approvals, and conformity	15
2	Mounting	17
2.1	Important installation notes	17
2.1.1	Environmental influences	18
2.1.2	Filtering and interference suppression	19
2.1.3	Admissible load current depending on the ambient temperature and the site altitude	19
2.1.4	Wall mounting with screws (default)	21
2.1.5	Mounting on DIN rail (accessories)	24
2.2	Dimensions	25
2.2.1	Type 709066/X-0X-020-0X-XXX-XX	25
2.2.2	Type 709066/X-0X-032-0X-XXX-XX	26
2.2.3	Type 709066/X-0X-050-0X-XXX-XX	27
2.2.4	Type 709066/X-0X-100-0X-XXX-XX	28
2.2.5	Type 709066/X-0X-150-0X-XXX-XX Type 709066/X-0X-200-0X-XXX-XX	29
2.2.6	Type 709066/X-0X-250-0X-XXX-XX	30
2.2.7	Clearances (all types)	30
3	Electrical connection	31
3.1	Pluggable screw terminals with 20 A	31

contents

3.1.1	Type 709066/X-0X-20-0X-XXX-XX	31
3.2	Cable lugs and pluggable screw terminals from 32 A	32
3.2.1	Type 709066/X-0X-032-0X-XXX-XX Type 709066/X-0X-050-0X-XXX-XX	33
3.2.2	Type 709066/X-0X-100-0X-XXX-XX	35
3.2.3	Type 709066/X-0X-150-0X-XXX-XX Type 709066/X-0X-200-0X-XXX-XX	37
3.2.4	Type 709066/X-0X-250-0X-XXX-XX	38
3.3	Connection diagram	39
3.4	Switch-on sequence	41
3.4.1	Rotary current economic circuit Master-Slave for resistive loads in star-, delta connection or transformer loads (resistive-induktive)	41
4	Operation.....	43
4.1	Display after switching on the device	43
4.1.1	Display and control elements	44
4.1.2	Appearance of measured values	44
4.1.3	Meaning of the displayed measured values	45
4.1.4	Appearance in the configuration level	47
4.1.5	Appearance of error messages and special statuses	47
4.2	Operating level	48
4.2.1	Device data	48
4.2.2	Power controller	49
4.2.3	Setpoint value configuration	49
4.2.4	Monitoring	50
5	Configuration	53
5.1	Configuration level	53
5.1.1	Device data	54
	Language wizard active.....	54
	Temperature unit.....	54
	Display contrast	54
	Switch-off.....	54
	display lighting	54
	Apply default settings	54
5.1.2	Power controller	54
	Thyristor control.....	54

	Cycle time	55
	Min. ON period	55
	α start.....	55
	α start angle.....	55
	Soft start	55
	Soft start type	56
	Soft start duration	56
	Current limiting	56
	Dual energy management.....	57
5.1.3	Analog inputs	58
	Current measuring range	58
	Current measuring range, start.....	58
	Current measuring range, end	58
	Voltage measuring range	58
	Voltage measuring range, start.....	58
	Voltage measuring range, end.....	58
5.1.4	Setpoint value configuration	59
	Setpoint specification	59
	Input in the event of an error.....	59
	Value in the event of an error	59
	Base load	59
5.1.5	Monitoring	60
	Limit value monitoring.....	60
	Min. limit value alarm	60
	Max. limit value alarm	60
	Limit value hysteresis.....	61
	Load monitoring.....	61
	Limit value load monitoring.....	61
	Load type load monitoring	61
	Teach-In type load monitoring.....	61
	Monitoring of the mains voltage drop.....	61
5.1.6	Digital inputs	62
	Inhibit input control direction	62
5.1.7	Digital output	63
	Output mode.....	63
	Control direction, digital output	63
5.1.8	RS422/485	63
	Baud rate	64
	Data format	64
	Device address	64
	Min. response time	64
5.1.9	Changing codes	64
	Code, manual mode	64

contents

Code, operating level.....	64
Code, config. level	64
5.2 Configuration example	65
6 Special device functions	67
6.1 Detection of load faults	67
6.1.1 Teach-In	69
6.2 Manual mode	70
6.2.1 Setpoint specification in manual mode	70
6.2.2 Configuring Teach-In (prerequisite for Teach-In in manual mode)	70
6.2.3 Performing Teach-In in manual mode	71
6.3 Setpoint specification via potentiometer	72
6.4 Dual energy management	72
6.5 α start	74
6.6 Monitoring of the mains voltage drop	75
6.7 Firing pulse inhibit	75
6.8 Thyristor control logic (switch)	76
7 Setup program	77
7.1 Hardware	77
7.2 Compatible operating systems	77
7.3 Installation	78
7.4 Program start	80
7.5 Forgotten the code?	81
7.6 Changing the language of the device texts	82
8 Error messages and alarms.....	83
8.1 Binary signal for collective fault	86
8.2 Replacing a defective semiconductor fuse	87
8.2.1 Accessories: semiconductor fuses	88
8.2.2 Semiconductor fuses type 709066/X-0X-20... ..	88
8.2.3 Semiconductor fuses type 709066/X-0X-32... ..	89

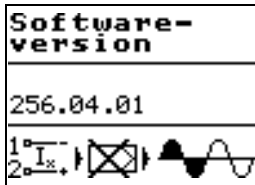
9	What to do, if	91
10	Technical data	93
10.1	Voltage supply, fan specifications at 250 A, load current	93
10.2	Galvanic isolation	93
10.3	Analog inputs (master only)	93
10.3.1	Display and measuring accuracy	94
10.4	Binary output (fault signal output master only)	94
10.5	General specifications	94
10.6	Approvals/approval marks	97

1.1 Preface



Read this operating manual before putting the device into service.

This operating manual is valid beginning with **device software version** [256.04.01].



Keep the operating manual in a place that is accessible to all users at all times.

Your comments are appreciated and may assist us in improving this operating manual.

Phone: +49 661 6003-727

Fax: +49 661 6003-508



The power controller produces the power that is needed at the analog input or in manual mode. Safety systems independent of the power controller must be installed. They should safely switch off the subsequent heating process in the event of excess temperatures.



The power controller may only be operated using original JUMO semiconductor fuses.

In the event of replacement, please check that the correct spare part has been used.



All necessary settings are described in this operating manual.

Manipulations not described in the operating manual or expressly forbidden will jeopardize your warranty rights.

If you have any problems, please contact the nearest branch office or the head office.

Service hotline

For technical questions

Phone support in Germany:

Phone: +49 661 6003-9135

Fax: +49 661 6003-881899

Email: service@jumo.net

Austria:

Phone: +43 1 610610

Fax: +43 1 6106140

Email: info@jumo.at

Switzerland:

Phone: +41 1 928 24 44

Fax: +41 1 928 24 48

Email: info@jumo.ch

1 Introduction



When accessing the inner parts of the device and returning device plug-in units, modules, or components, please observe the regulations according to DIN EN 61340-5-1 and DIN EN 61340-5-2 "Protection of electronic devices from electrostatic phenomena". Use only **ESD** packaging for shipment.

Please note that we cannot accept any liability for damage caused by ESD.

ESD=Electrostatic Discharge

1.2 Typographical conventions

1.2.1 Warning symbols

Caution



This symbol is used when **personal injury** may occur if the instructions are disregarded or not followed correctly!

Attention



This symbol is used when **damage to devices or data** may occur if the instructions are disregarded or not followed correctly!

ESD



This character is used if precautionary measures must be taken when handling **electrostatically sensitive components**.

Dangerous voltage



This symbol is used if dangerous voltages will cause an electric shock in the event of contact with live parts.

Hot surface, fire hazard



This symbol is used if burns can result from touching a hot surface.



Do not install any heat-sensitive components or devices close to the power controller.

1.2.2 Note symbols

Note



This symbol is used to draw your attention to a **particular issue**.

Reference



This symbol refers to **further information** in other manuals, chapters, or sections.

Footnote

abc¹

Footnotes are remarks that **refer to** specific parts of the text. Footnotes consist of two parts: An identification marking in the text, and the footnote text itself. The identification marking in the text is arranged as continuous superscript numbers.

1.2.3 Performing an action

Action

instruction

* Plug in the connector This symbol marks the description of a **required action**. The individual steps are marked by this asterisk

Vital text



READ THE DOCUMENTATION!

This symbol, which is attached to the device, indicates that the associated **device documentation must be observed**. This is necessary in order to recognize the nature of the potential danger and take the necessary measures to prevent it.

Command sequence

Config. level → Power controller → Operating mode Small arrows between words are designed to make it easier to find parameters in the configuration level.

1.2.4 Display types

Keys



Keys are displayed as symbols or text. Key combinations are represented by a plus sign.

1 Introduction

1.3 Order Details

The nameplate is affixed to the right-hand side of the housing.

(1) Basic type

709066	TYA S202 Three-phase thyristor power controller in three-phase economy circuit
--------	--

(2) Version

8	Standard with default settings
9	Customer-specific programming according to specifications

(3) National language of device texts

01	German (default setting)
02	English
03	French

(4) Load current

020	AC 20 A
032	AC 32 A
050	AC 50 A
100	AC 100 A
150	AC 150 A
200	AC 200 A
250	AC 250 A

(5) Partial load failure monitoring

00	None
01	Partial load failure monitoring

(6) Mains voltage^a

400	AC 400 V	-20 to +15 %, 48 to 63 Hz
460	AC 460 V	-20 to +15 %, 48 to 63 Hz
500	AC 500 V	-20 to +15 %, 48 to 63 Hz

(7) Interface

00	None
54	RS485/422
63	PROFINET

(1) / (2) - (3) - (4) - (5) - (6) - (7) **Order code**
 709066 / 8 - 01 - 100 - 01 - 400 - 00 **Order example**

a. Mains voltage = Voltage supply for control electronics (always select **phase voltage** L1-L2 from the three-phase supply)

1.3.1 Scope of delivery

1 operating manual
1 thyristor power controller in the version ordered
1:1 patch cable

1.3.2 Accessories

Item	Part no.
Setup program TYA 200 / TYA S200	00544869
USB cable A-connector B-connector 3 m	00506252

Installation kits:

Installation kit for DIN-rail 20 A TYA S202	00555172
Installation kit for DIN-rail 32 A TYA S202	00555527

Item	Part no.
Installation kit for DIN-rail 50 A TYA S202	00600097

1.3.3 General accessories

Semiconductor fuses A semiconductor fuse is fitted in the power controller to protect the thyristor module. The "Fuse LED" lights up red in the event of a fault.

⇒ Chapter 8.2 "Defekte Halbleitersicherung austauschen"

Item	Load current	Part no.
	$I_{nom.} = I_N$	
Super fast semiconductor fuse 40 A	$I_N = 20 \text{ A}$	00513108
Super fast semiconductor fuse 80 A	$I_N = 32 \text{ A}$	00068011
Super fast semiconductor fuse 80 A	$I_N = 50 \text{ A}$	00068011
Super fast semiconductor fuse 160 A	$I_N = 100 \text{ A}$	00081801
Super fast semiconductor fuse 350 A	$I_N = 150 \text{ A}$	00083318
Super fast semiconductor fuse 550 A	$I_N = 200 \text{ A}$	00371964
Super fast semiconductor fuse 550 A	$I_N = 250 \text{ A}$	00371964

1 Introduction

1.4 Brief description


Device	The JUMO TYA S202 is the slim version of the JUMO TYA 202 power controller. It switches resistive inductive loads using a three-phase current economy circuit in star or delta three-phase operation. The microprocessor-controlled power controller displays all parameters in an LCD display with background lighting. It can be operated using the 4 keys at the front.
Application	Thyristor power controllers are used where larger resistive and resistive inductive loads have to be switched (e.g. in thermal processing technology). The thyristor power controller consists of thyristors connected in anti-parallel, the insulated heat sink, and the control electronics.
Mounting	Thyristor power controllers up to a load current of 32 A can either be clipped to a 35 mm mounting rail or fitted to the wall on a mounting plate. Devices with a load current greater than 32 A can only be mounted on the wall.
Operating modes	<p>The power controller works in burst-firing operation. In burst-firing operation, the first half-wave can be optimally cut with an adjustable phase angle so that transformer loads can also be operated.</p> <p>It is possible to specify a base load or, depending on the device type, to set current limiting or resistance limitation for the load.</p> <p>To avoid high starting currents, a soft start can be set.</p>
Load types	<p>All resistive loads through to inductive loads are permitted.</p> <p>In the case of transformer loads, the nominal induction of 1.2 tesla must not be exceeded (value is 1.45 T in the case of mains overvoltage).</p>
Standards	The thyristor power controllers comply with VDE 0160 5.5.1.3 (5/88) and VDE 0106 Part 100 (3/83). The devices must be grounded as specified by the responsible energy supplier.
Advantages	<ul style="list-style-type: none">- Teach-In function for the detection of partial load failure- Network load optimization through dual energy management- Transmission of the setup data is possible even without voltage supply to the device (power supply via USB port)- Energy meter- Same design as the JUMO TYA 202 power control series

1.5 Standards, approvals, and conformity

Device properties are inspected on the basis of the Low Voltage Directive DIN EN 50178.

The EMC directive is inspected on the basis of DIN EN 61326-1.

	Standard
Electrical connection	DIN VDE 0100
Protection type IP20 built-in devices	DIN EN 60529
Climatic ambient conditions	Class 3K3
Air temperature and rel. humidity	DIN EN 60721-3-3
Storage temperature class 1K5	DIN EN 60721-3-1
Operating conditions Pollution degree Overvoltage category	DIN EN 50178 2 III
Test voltages	DIN EN 50178
Residual current circuit breaker	DIN EN 50178
Electromagnetic compatibility Interference emission Interference immunity	DIN EN 61326-1 Class A - only for industrial use Industrial requirement
Mechanical tests: Vibration test 3M2 Toppling test class 2M1	DIN EN 60068-2-6, DIN EN 60721-3-3 DIN EN 60068-2-31, DIN EN 60721-3-2
Labels, identification marking	DIN EN 50178, DIN EN 61010-1

Approvals	Standard	Type
	UL 508 (Category NRNT), pollution degree 2 C22.2 NO. 14-10 Industrial Control Equipment (Category NRNT7)	709066/X-XX-020-... Load current 20 A
	UL 508 (Category NRNT) C22.2 NO. 14-10 Industrial Control Equipment (Category NRNT7)	709066/X-XX-032... 709066/X-XX-050... 709066/X-XX-100... 709066/X-XX-150... 709066/X-XX-200... 709066/X-XX-250... Load current 32 to 250 A

Can be used for electrical circuits with a short-circuit current capacity of ≤ 100 kA (the admissible mains voltage must correspond to the nominal voltage of the thyristor controller).
For plant protection, a fuse up to class RK5 may be used.

CE conformity	Low Voltage Directives 2006/95/EC Marking Directives 93/68/EEC EMC Directives 2004/108/EC	
---------------	---	--

1 Introduction

Conformity	Standard
RoHS	2002/95/EC

2.1 Important installation notes

Safety regulations



- The choice of cable material, the installation, and the electrical connection of the device must conform to the requirements of VDE 0100 "Regulations on the Installation of Power Circuits with Nominal Voltages below AC 1000 V" or the appropriate local regulations.
- The electrical connection must only be carried out by qualified personnel.
- An isolating switch should be wired between the voltage supply and the device to be able to disconnect the device from the voltage supply on all poles prior to accessing the inner parts of the device.
- Inside the device, safety clearances meet the requirements for double insulation.
When mounting the connecting cable, ensure that the cables are fitted according to regulations and that the safety clearances are maintained.

Fuse protection



- Fuse protection of the voltage supply in accordance with the VDE regulations must be installed when wiring the voltage supply in the power section. The supply can also be protected with a circuit-breaker in the supply lead. The circuit-breaker must correspond to the power consumption of the power controller.
 - The connecting cables used for the terminals U1, U2, N/L2, V, and L1 must have an electric strength of AC 500 V.
 - For UL application, it must be ensured that the fuse for the supply protection of the control electronics is between 2 A and a maximum of 5 A. This also applies to the fan connection.
 - A semiconductor fuse is installed to protect the power controller in the event of a ground fault. In the event of a defect, these may only be replaced with original JUMO semiconductor fuses.
- ⇒ Chapter 8.2 "Defekte Halbleitersicherung austauschen"

Wiring

Control cables (SELV potential) must be routed so that they are isolated from cables with mains voltage potential. For supply protection, fuses (e.g. 2 A, Neozed type) must also be installed in the control circuit.

Master/slave 1:1 patch cable



Prior to startup, the enclosed 1:1 patch cable must be inserted into the master's X8 socket and connected to the slave device's X8 socket.

PE connection

- * A direct protection conductor connection must be provided between the PE connection terminal on the device and the PE conductor of the supply network.

The cross section of the PE conductor must be at least as large as the cross section of the voltage supply cables in the power section. In the event that the protection conductor is not a component of the supply cable or its encasement, the selected conductor cross section may not be less than 2.5 mm² (for mechanical protection) or not less than 4 mm² (if the protection conductor is not protected mechanically).

2 Mounting

⇒ See VDE 0100 Part 540

Testing

- * That the data on the nameplate (data, load current) corresponds to the data for the plant.
- * That the rotary electrical field has clockwise phasing if the economy circuit configuration is used.
- * That the configuration of the analog inputs, for example, corresponds to the wiring.
- * The analog input for the setpoint specification only needs to be connected to the master. The slave receives its information via the 1:1 patch cable. However, the slave power controller can be disconnected separately by means of its own inhibit input.

Load connection

- * The electronic switch (2 anti-parallel thyristors) is located between the U1 and U2 terminals.
- * Where possible, load cables and cables for control inputs should be routed so that they are isolated.
- * Connect the mains voltage - thyristor power controller - load in accordance with the connection diagram and check.

Phasing

The voltage supply of the control electronics and the load voltage must have the same phase.

Control inputs

The terminal strips for control connections (inputs and outputs) have been laid out for safe isolation from the mains voltage (SELV). To prevent the safe isolation from being impaired, ensure that all connected current circuits are also safely isolated. The required auxiliary supplies must be SELV voltages. The ground terminals X2_2/11 or X2_1/6 of the master and slave must be connected to one another.

2.1.1 Environmental influences

Incorrect use

The device is not suitable for installation in potentially explosive areas.

Mounting site

The power controller must be installed in a fire-proof control cabinet. The cabinet should be vibration-free, free from aggressive media, and free from dust to prevent the ventilation slots from becoming blocked.

Climatic conditions

- Relative humidity: 5 to 85 %, no condensation (3K3 according to EN 60721)
- Ambient temperature range: 0 to 45 °C (3K3 according to EN 60721-3-3)
- Storage temperature range: -30 to +70 °C class 1K5

Avoid additional sources of heat

- Ensure that the ambient temperature at the installation site is not increased by other sources of heat or heat accumulation.
- Do not mount the power controller too close to the heating process (furnace)
- Avoid direct sunlight.

Power loss

Occurs as waste heat on the cooling body of the master and slave device and

must be dissipated at the mounting site (e.g. in the control cabinet) in accordance with the climatic conditions.

2.1.2 Filtering and interference suppression

To prevent radio-frequency interference, generated with a soft start in phase-angle operation for example, electrical apparatus and plants must have interference suppression implemented.

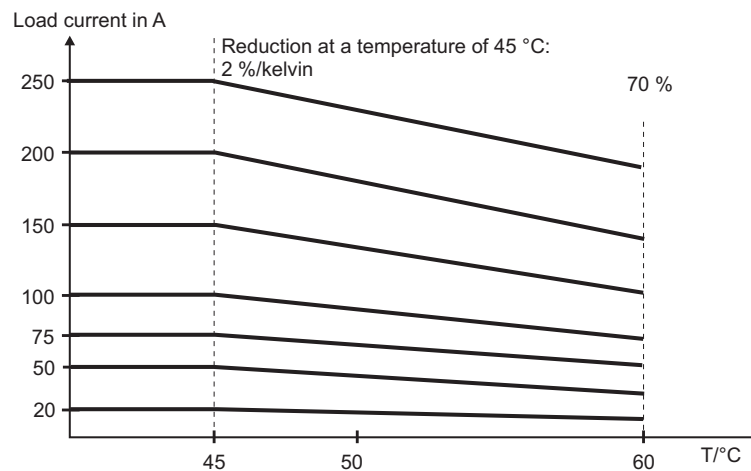
The control electronics of the thyristor power controller comply with the EMC requirements of EN 61326.

However, modules such as thyristor power controllers do not have any purpose by themselves. They only serve as a component function within a plant. Where applicable, the power controllers's entire load circuit must also have suitable interference suppression filters fitted by the plant provider.

There are a number of specialist companies that provide appropriate ranges of interference suppression filters to deal with any interference problems. These filters are normally supplied as complete modules that are ready to be connected.

2.1.3 Admissible load current depending on the ambient temperature and the site altitude

Ambient temperature



2 Mounting



Destruction through overheating:

In the event of operation at maximum load current over an extended period, the heat sink and its surroundings heat up.

For this reason, at ambient temperatures above 45 °C, the maximum load current must be reduced as shown in the image, as the thyristor module could otherwise be destroyed.

The master or slave device temperature shown on the display may not exceed 100 °C.

At a device temperature of >100 °C, the message "Warning - high temperature" is displayed.

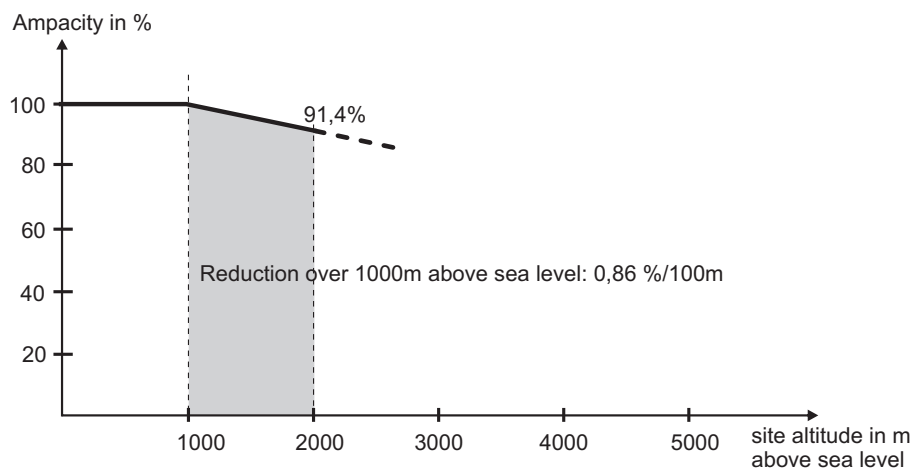
At a device temperature of >105 °C, the load current is gradually reduced by 10 % of the nominal current each time the temperature increases by one degree.

At a device temperature of >115 °C, the power controller current is completely switched off.

⇒ Chapter 8 "Fehlermeldungen und Alarme"

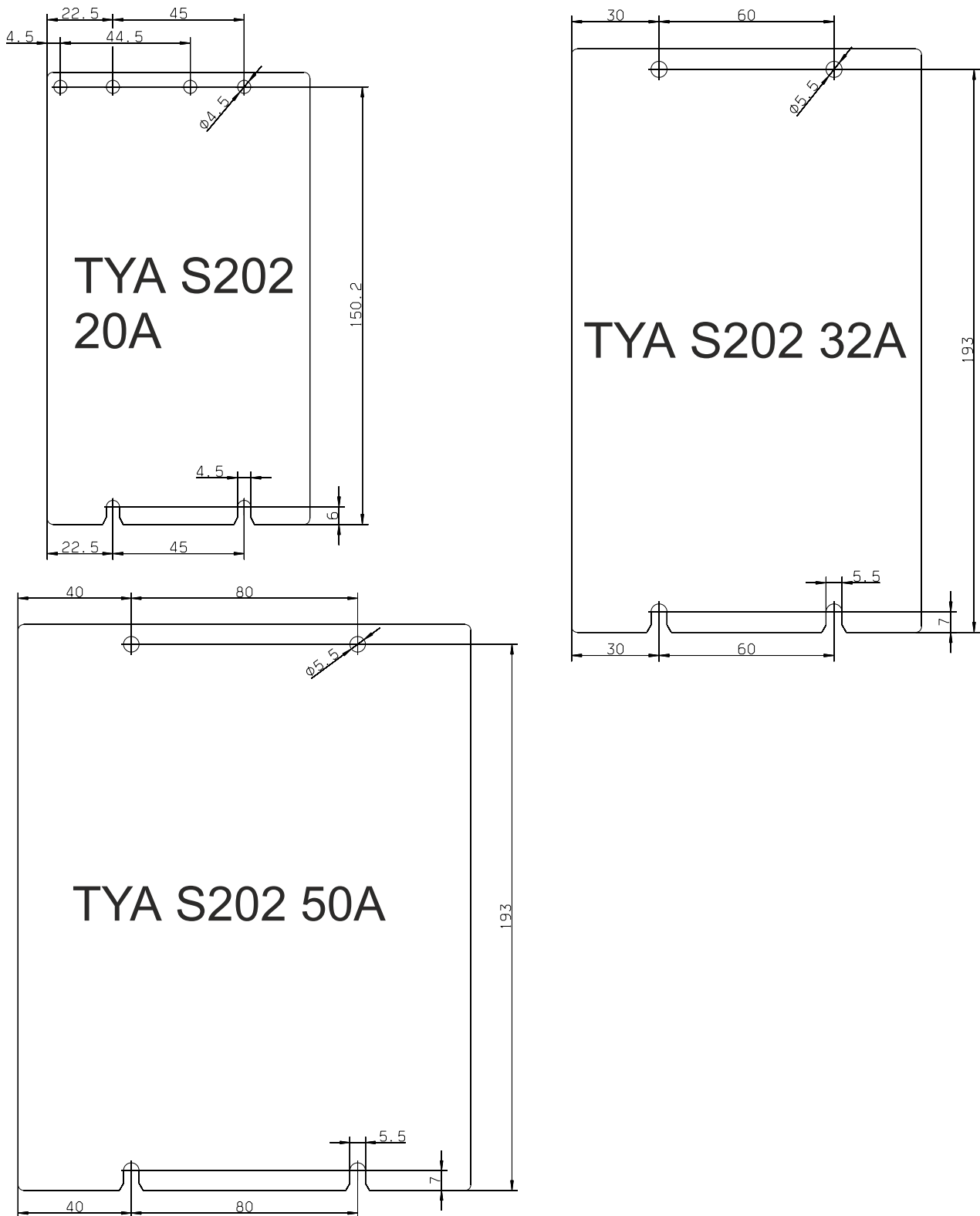
Site altitude

In the case of air cooling, it must be noted that the effectiveness of the cooling is reduced as the site altitude increases. As a result, the ampacity of the thyristor power controller decreases with such a cooler as the site altitude increases, as shown in the diagram.

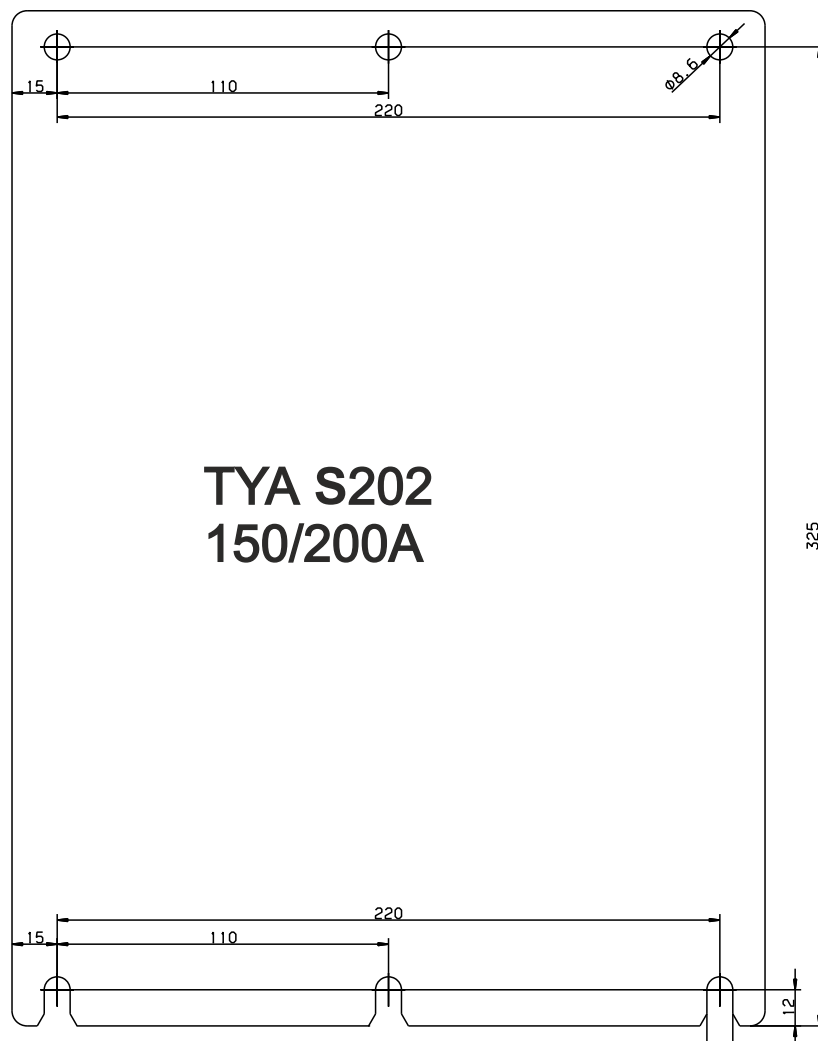
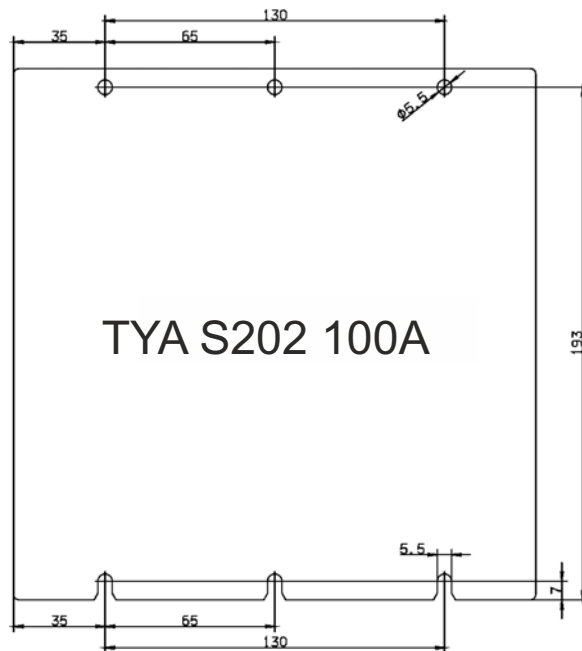


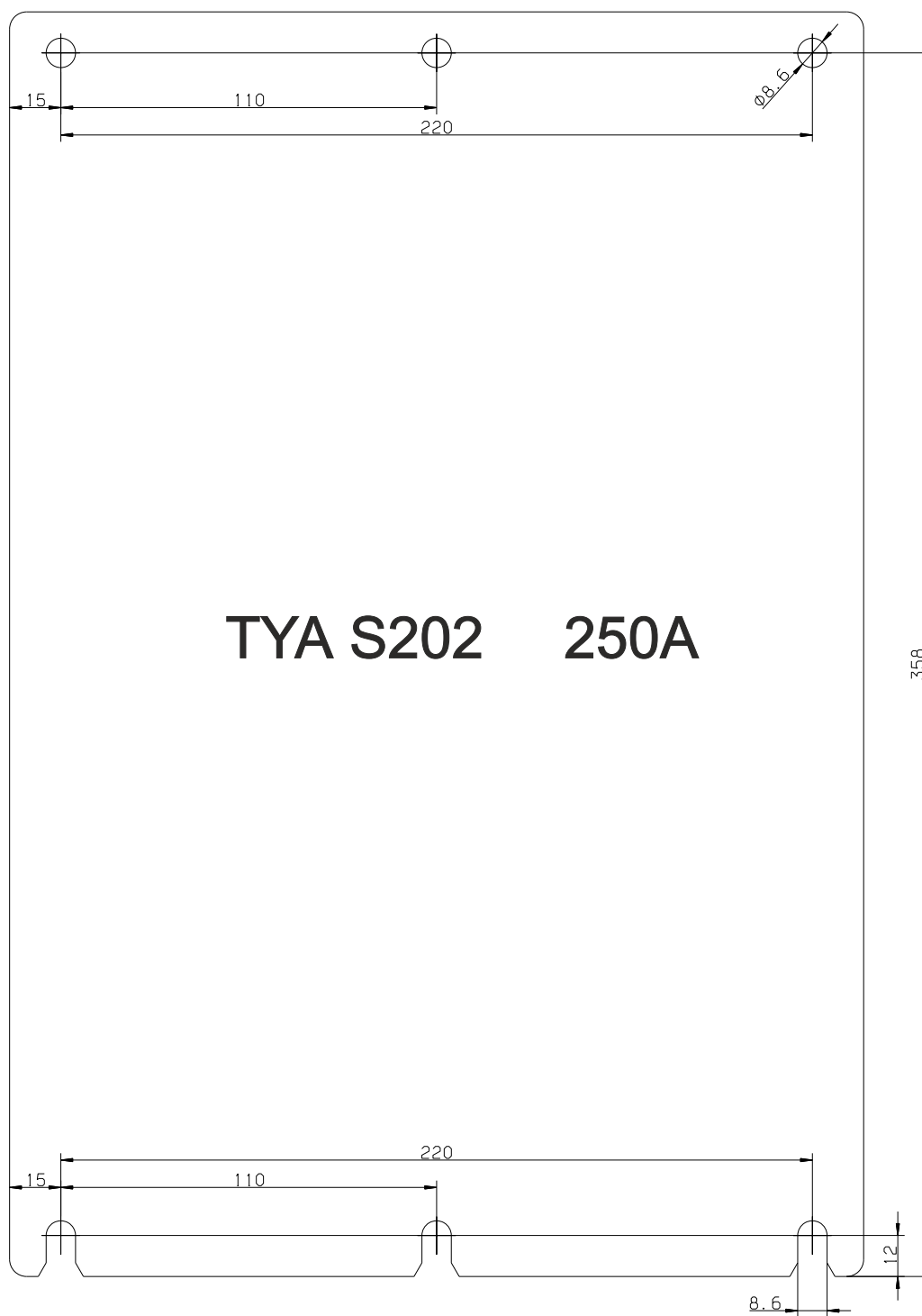
2.1.4 Wall mounting with screws (default)

Power controllers with a load current between 20 and 50 A are affixed to a fire-proof control cabinet wall with 4 screws. The left-hand hole is more easily accessible in the upper section. Power controllers with a load current between 100 and 250 A are affixed with 6 screws.



2 Mounting





2 Mounting

Hot surface



During operation, the power controller heats up to a maximum of 110 °C, depending on the load.

Ensure that the lamellae of the heat sink are vertically aligned to allow the heat to be dissipated through natural convection.



Fire hazard:

Do not install any heat-sensitive components or devices close to the power controller.



Integrated fan for 250 A power controller:

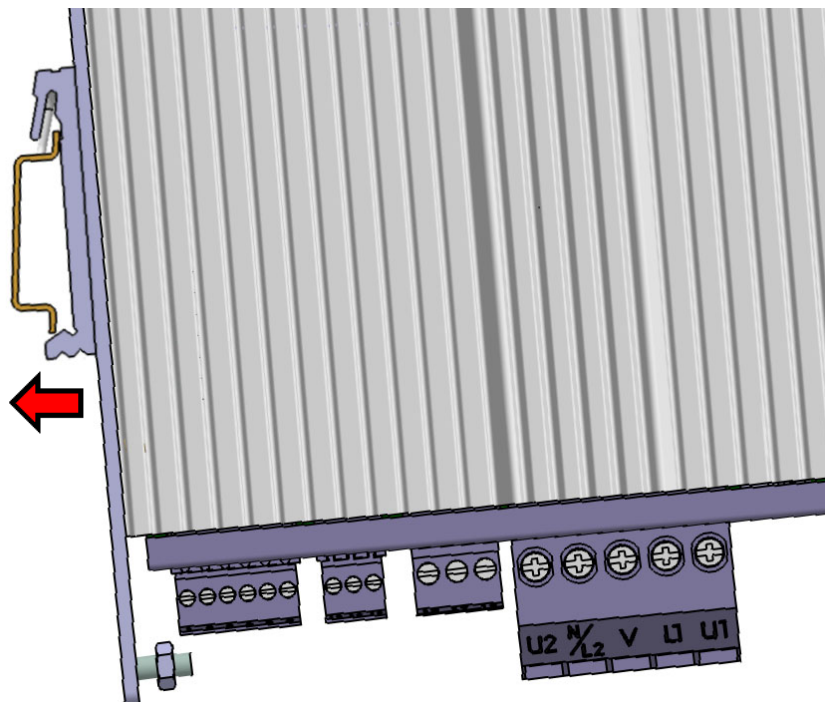
The intake air at the ventilation grid of the fan may not exceed a maximum inlet air temperature of 35 °C. Ensure that the inlet air for the built-in fans can be taken in from below and escape at the top without obstruction!

2.1.5 Mounting on DIN rail (accessories)

Power controllers up to 50 A can be affixed to a DIN rail using the corresponding accessories.

⇒ Chapter 1.3.3 "Allgemeines Zubehör"

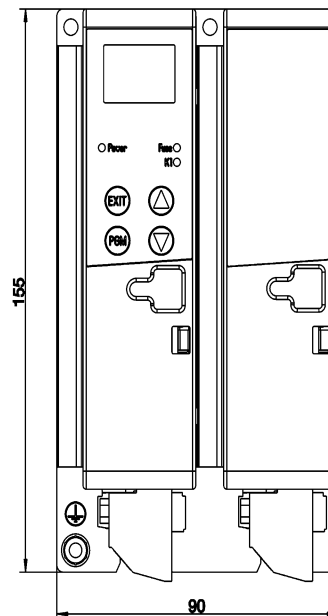
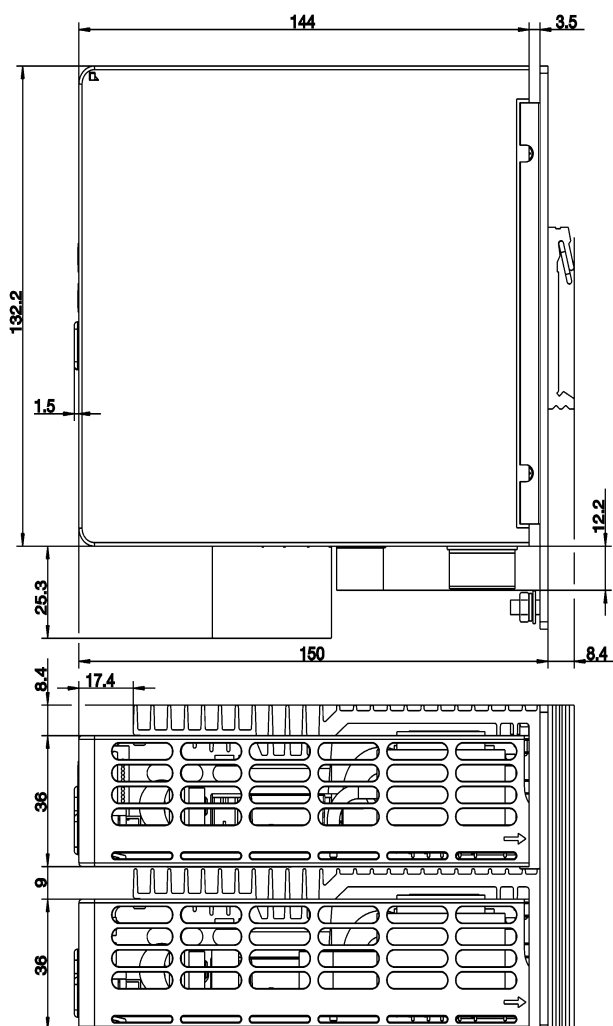
* Hook the spring saddle into the DIN rail from above.



* Swivel the power controller downward until the lug engages with the DIN rail with an audible click.

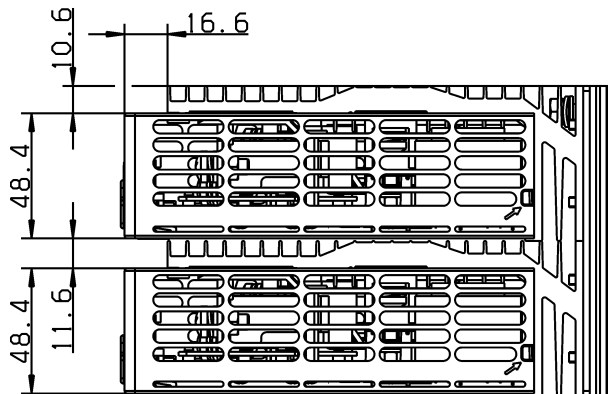
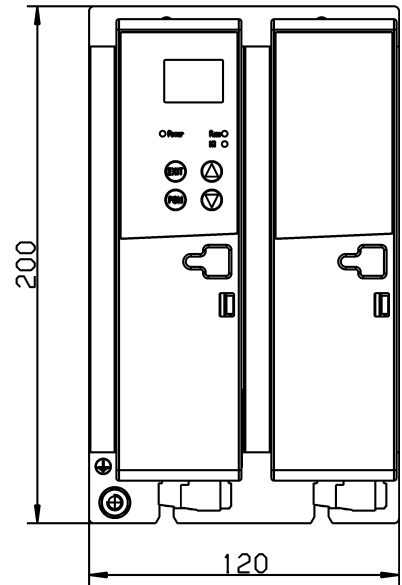
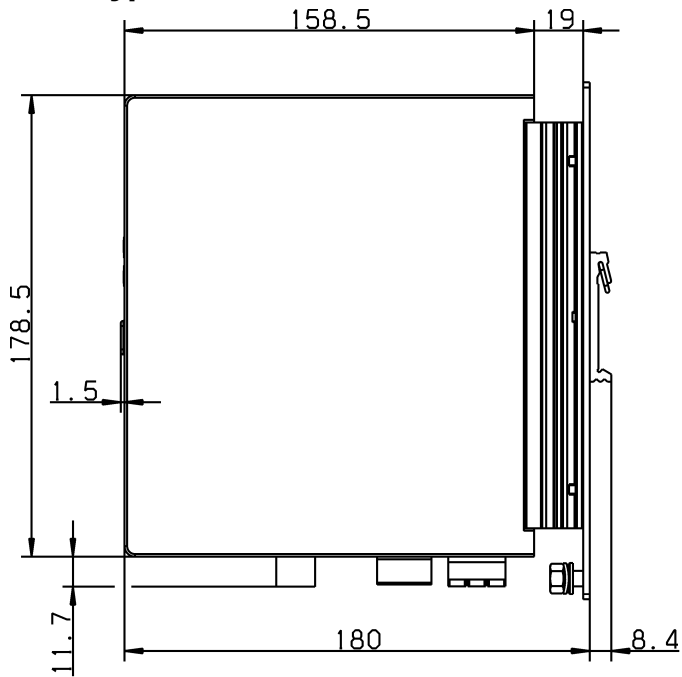
2.2 Dimensions

2.2.1 Type 709066/X-0X-020-0X-XXX-XX

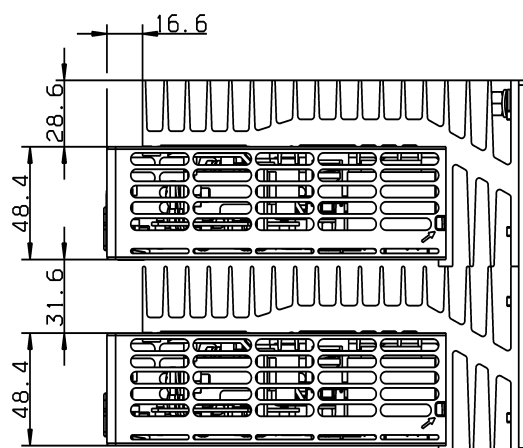
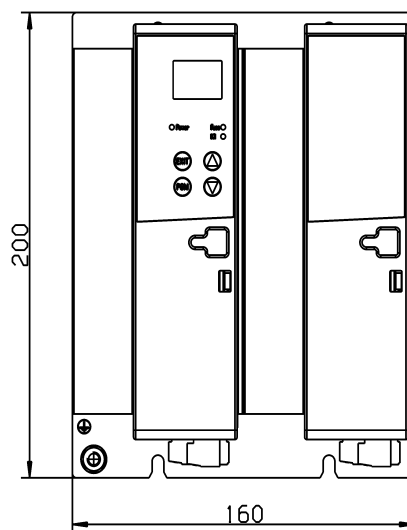
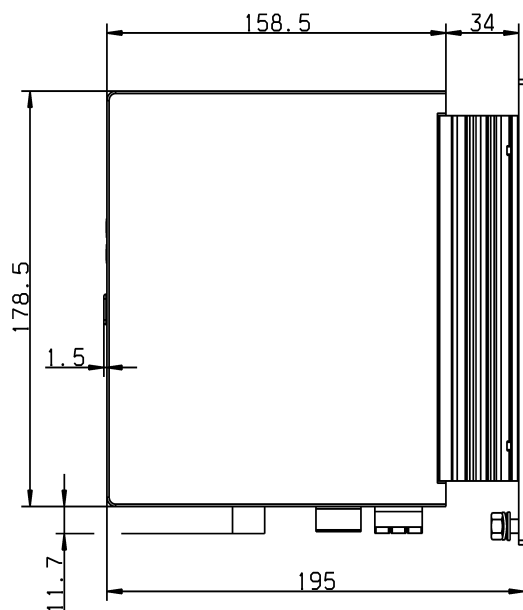


2 Mounting

2.2.2 Type 709066/X-0X-032-0X-XXX-XX

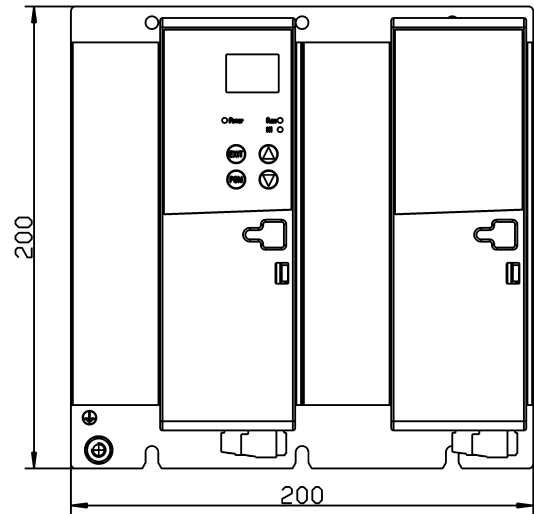
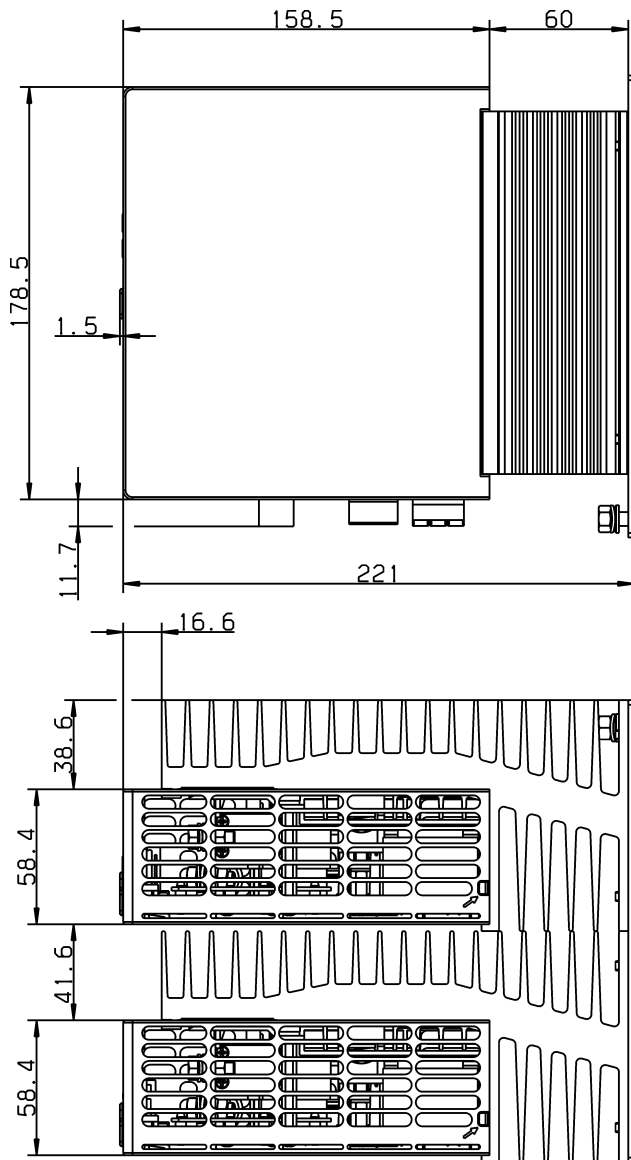


2.2.3 Type 709066/X-0X-050-0X-XXX-XX

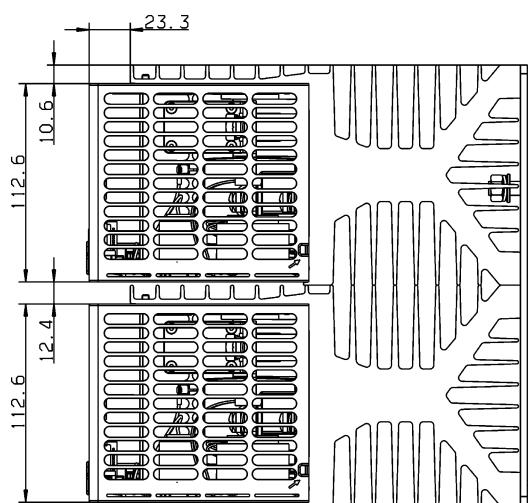
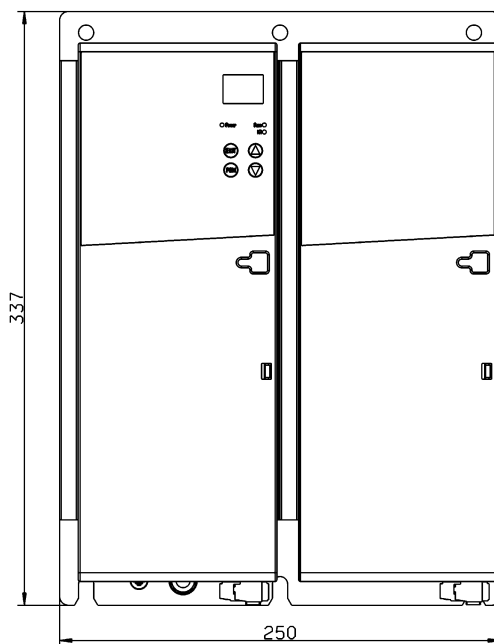
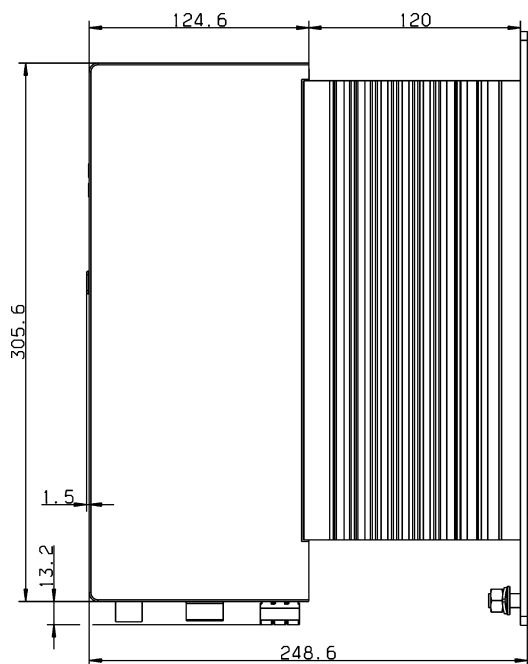


2 Mounting

2.2.4 Type 709066/X-0X-100-0X-XXX-XX

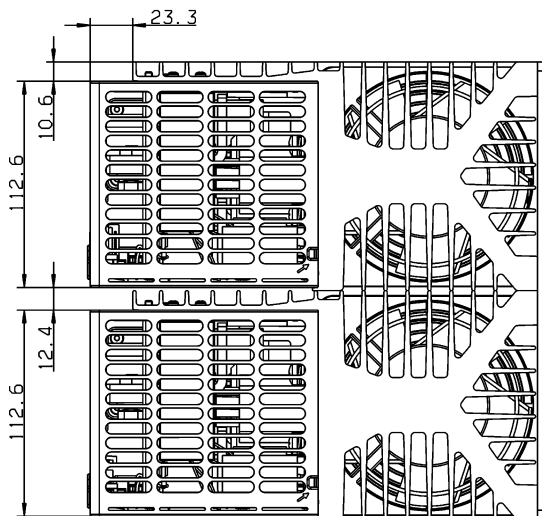
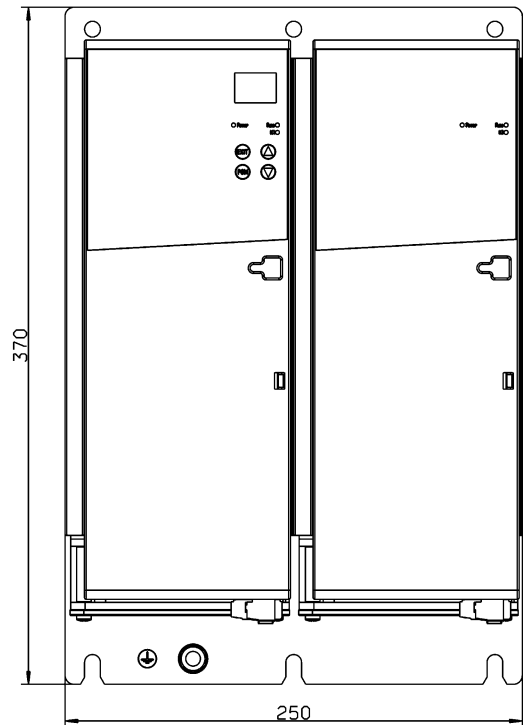
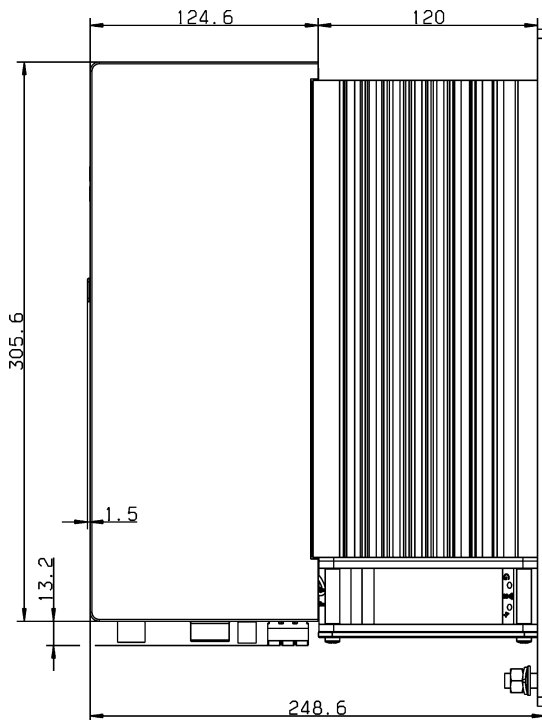


2.2.5 Type 709066/X-0X-150-0X-XXX-XX Type 709066/X-0X-200-0X-XXX-XX



2 Mounting

2.2.6 Type 709066/X-0X-250-0X-XXX-XX



2.2.7 Clearances (all types)

- * Allow a clearance of 10 cm from the floor.
- * Allow a clearance of 15 cm from the ceiling.
- * When fitted next to each other, no spacing between the devices is required.

3 Electrical connection

Dangerous voltage



The electrical connection must only be carried out by qualified personnel! Dangerous voltages will cause an electric shock in the event of contact with live parts!

* Disconnect the plant from the mains voltage on all poles.

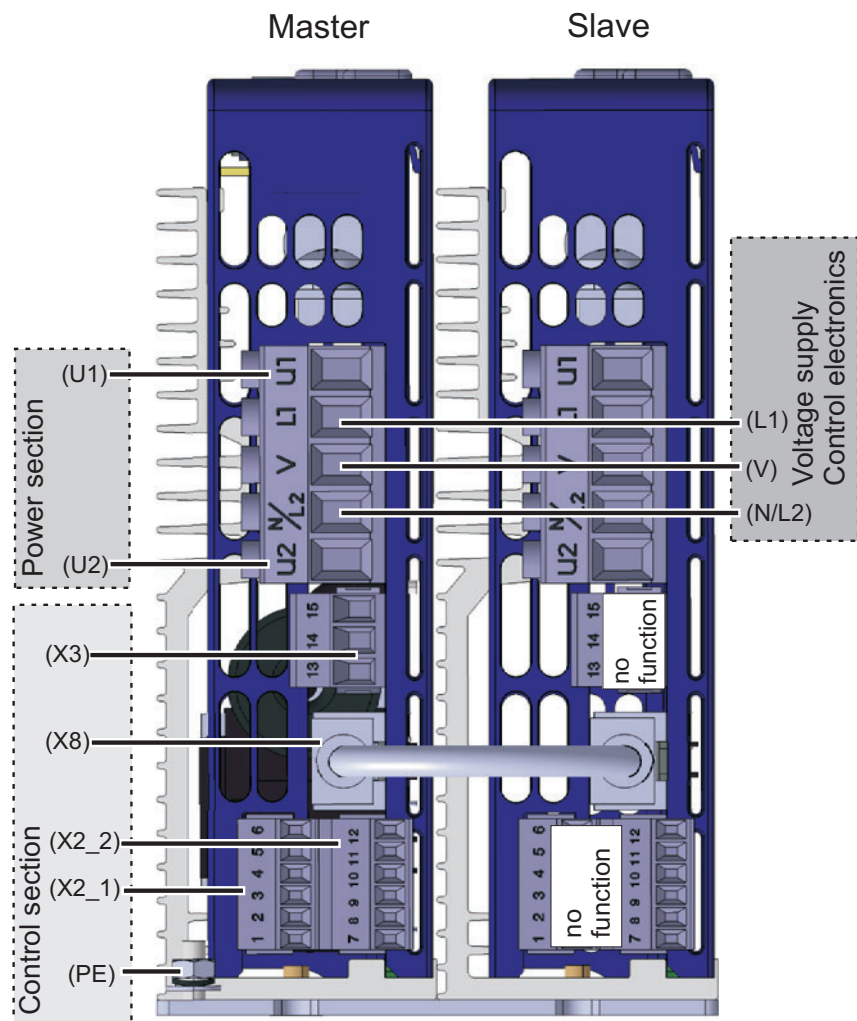
All screw terminals supplied ex works must be inserted and screwed tight during operation!

3.1 Pluggable screw terminals with 20 A

Tools - Flat-blade screwdriver, blade width 2, 3, and 5 mm

3.1.1 Type 709066/X-0X-20-0X-XXX-XX

The device with a load current of 20 A is connected via pluggable screw terminals.



3 Electrical connection

Terminal	Version	Conductor cross section	Maximum tightening torque
X2_1 and X2_2	Slotted screws, blade width 2 mm	0.2-1.5 mm ²	0.25 Nm
X3	Slotted screws, blade width 3 mm	0.2-2.5 mm ²	0.5 Nm
U2, N/L2, V, L1, U1	Slotted screws, blade width 5 mm	0.5-6 mm ²	0.6 Nm
For applications according to UL, only 60 °C or 60 °C/75 °C copper conductors may be used!			
Ground terminal PE	M4 setscrew with hexagon nut Width across flats 7 mm	Cable lug with drilled hole: 4 mm	3 Nm

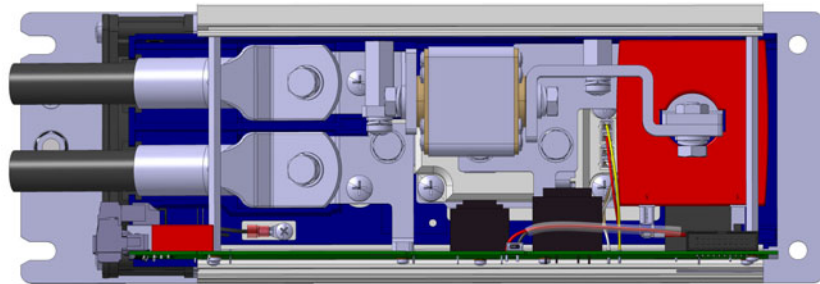
Master-slave connection

Terminal	Connection for
RJ 45 socket X8	Master-slave The 1:1 patch cable (included in scope of delivery) must be plugged in for correct operation (X8 connection to slave).

3.2 Cable lugs and pluggable screw terminals from 32 A

Tools

- Flat-blade screwdriver, blade width 2, 3, and 5 mm
- Ring or open-end wrench, wrench size 7, 10, 13 mm



3 Electrical connection

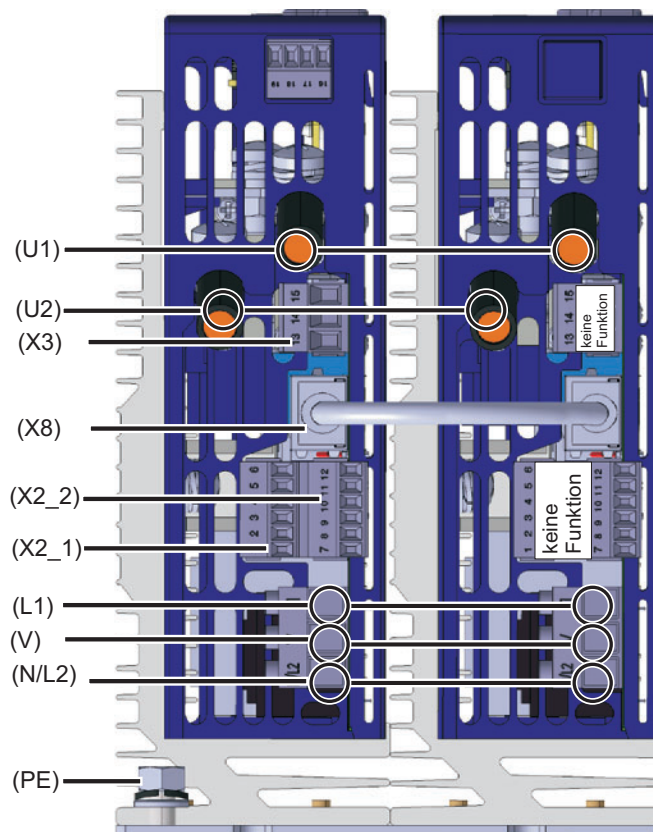
3.2.1 Type 709066/X-0X-032-0X-XXX-XX Type 709066/X-0X-050-0X-XXX-XX

Devices with a load current of 32 A and 50 A are equipped with pluggable screw terminals in the control section and cable lugs in the power section.

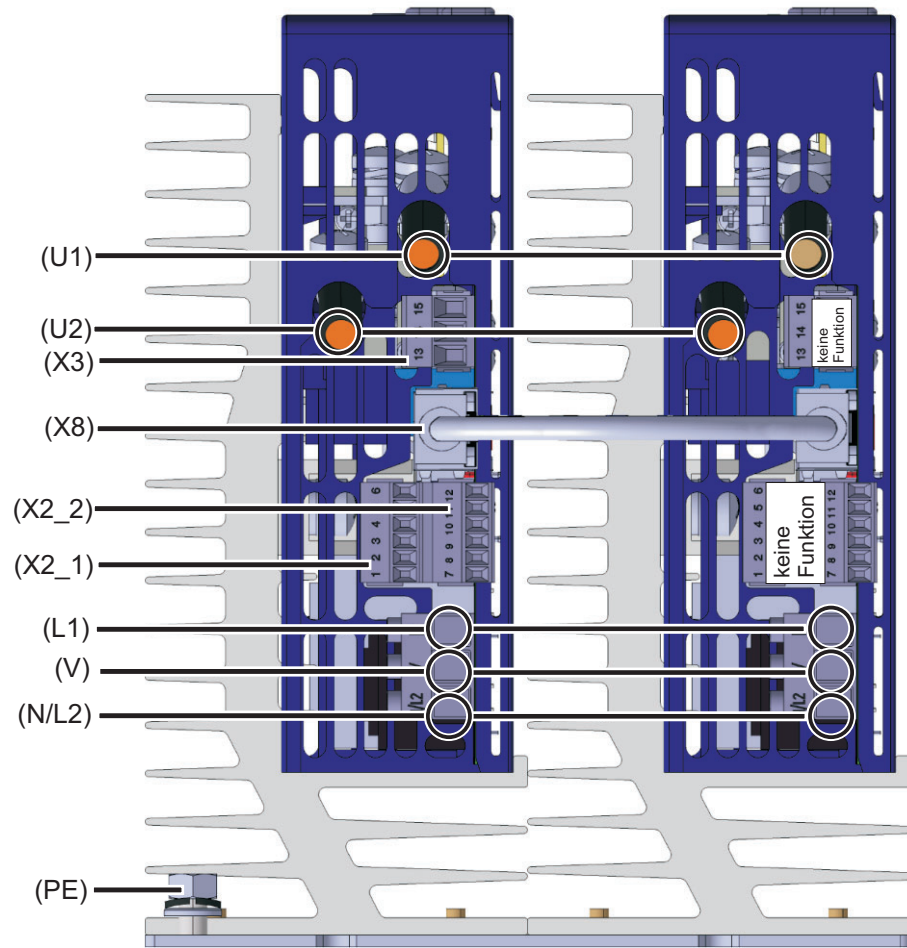
Terminal	Version	Conductor cross section	Maximum tightening torque
X2_1 and X2_2	Slotted screws, blade width 2 mm	0.2 to 1.5 mm ²	0.25 Nm
X3	Slotted screws, blade width 3 mm	0.2 to 2.5 mm ²	0.5 Nm
U2, U1	M6 recessed head screws	6 to 25 mm ²	5 Nm
For applications according to UL, only 60 °C or 60 °C/75 °C copper conductors may be used!			
N/L2, V, L1	Slotted screws, blade width 3 mm	0.5 to 4 mm ² or (0.5 to 2.5 mm ² with ferrule) For UL AWG 20-12)	0.5 Nm
Ground terminal PE	M6 setscrew with hexagon nut Wrench size 10 mm	Cable lug drilled hole: 6 mm	5 Nm

Master-slave connection

Terminal	Connection for
RJ 45 socket X8	Master-slave The 1:1 patch cable (included in scope of delivery) must be plugged in for correct operation (X8 connection to slave).



3 Electrical connection



3 Electrical connection

3.2.2 Type 709066/X-0X-100-0X-XXX-XX

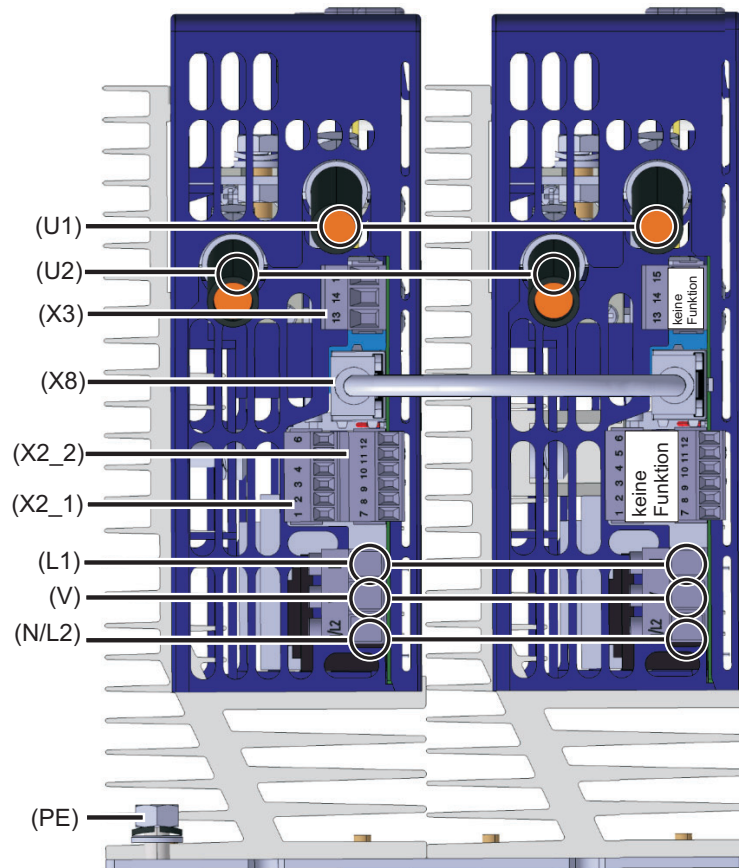
Devices with a load current of 100 A are equipped with pluggable screw terminals in the control section and cable lugs in the power section.

Terminal	Version	Conductor cross section	Maximum tightening torque
X2_1 and X2_2	Slotted screws, blade width 2 mm	0.2 to 1.5 mm ²	0.25 Nm
X3	Slotted screws, blade width 3 mm	0.2 to 2.5 mm ²	0.5 Nm
U2, U1	M6 hex-headed screws, width across flats 10 mm	16 to 50 mm ²	5 Nm
For applications according to UL, only 75 °C copper conductors may be used!			
N/L2, V, L1	Slotted screws, blade width 3 mm	0.5 to 4 mm ² or (0.5 to 2.5 mm ² with ferrule) for UL AWG 20-12	0.5 Nm
Ground terminal PE	M6 setscrew with hexagon nut Wrench size 10 mm	Cable lug drilled hole: 6 mm	5 Nm

Master-slave connection

Terminal	Connection for
RJ 45 socket X8	Master-slave The 1:1 patch cable (included in scope of delivery) must be plugged in for correct operation (X8 connection to slave).

3 Electrical connection



3 Electrical connection

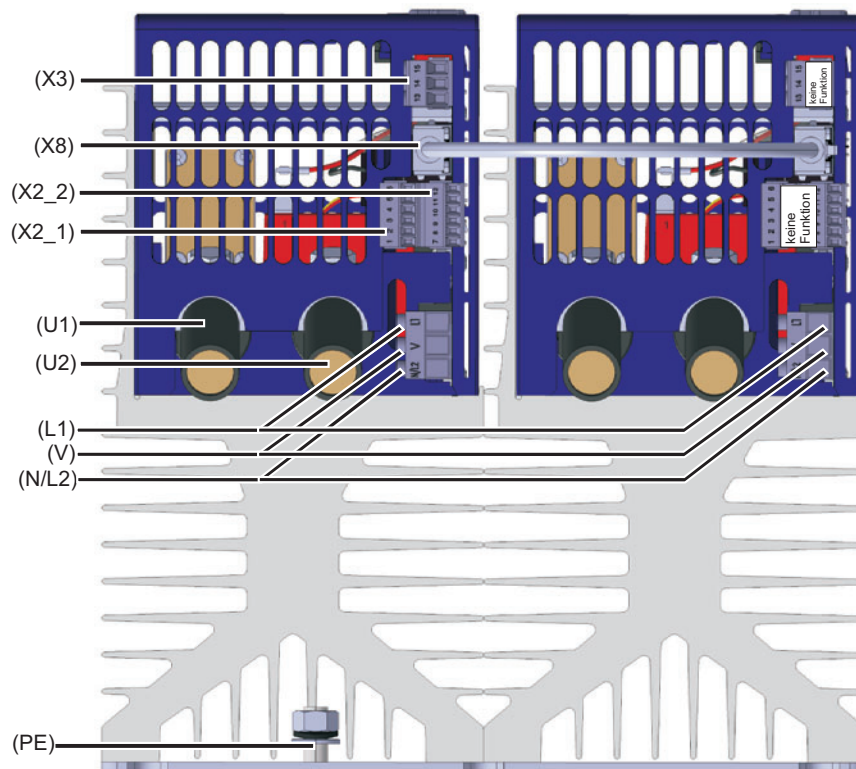
3.2.3 Type 709066/X-0X-150-0X-XXX-XX Type 709066/X-0X-200-0X-XXX-XX

Devices with a load current of 150 A are equipped with pluggable screw terminals in the control section and cable lugs in the power section.

Terminal	Version	Conductor cross section	Maximum tightening torque
X2_1 and X2_2	Slotted screws, blade width 2 mm	0.2 to 1.5 mm ²	0.25 Nm
X3	Slotted screws, blade width 3 mm	0.2 to 2.5 mm ²	0.5 Nm
U2, U1	M8 hex-headed screws, width across flats 13 mm	95 to 150 mm ²	12 Nm
For applications according to UL, only 75 °C copper conductors may be used!			
N/L2, V, L1	Slotted screws, blade width 3 mm	0.5 to 4 mm ² or (0.5 to 2.5 mm ² with ferrule) for UL AWG 20-12	0.5 Nm
Ground terminal PE	M8 setscrew with hexagon nut, wrench size 13 mm	Cable lug Drilled hole: 8 mm	12 Nm

Master-slave connection

Terminal	Connection for
RJ 45 socket X8	Master-slave The 1:1 patch cable (included in scope of delivery) must be plugged in for correct operation (X8 connection to slave).



3 Electrical connection

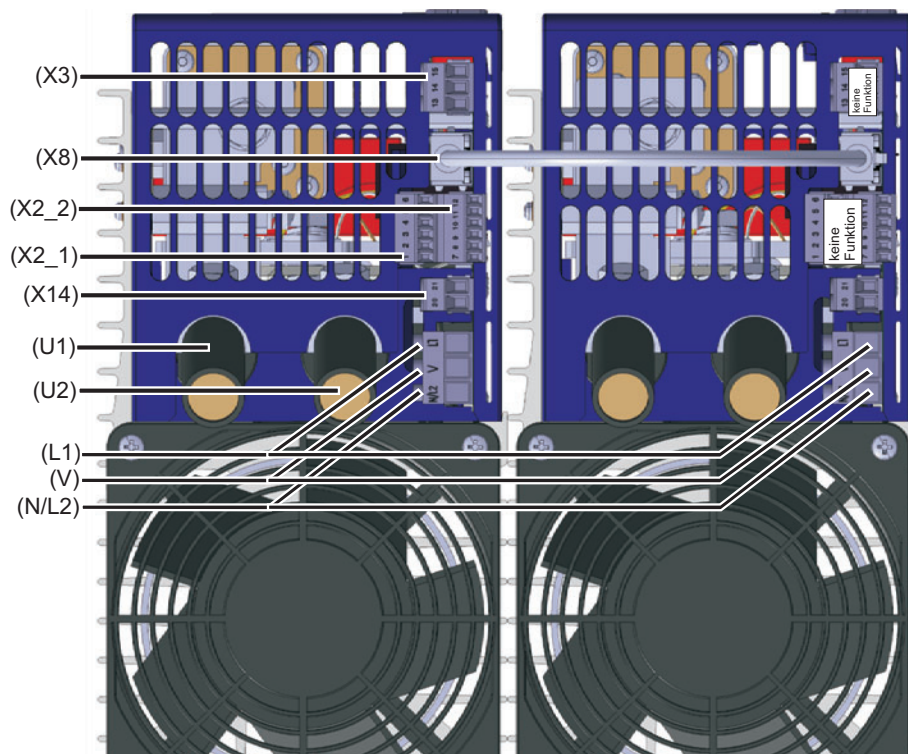
3.2.4 Type 709066/X-0X-250-0X-XXX-XX

Devices with a load current of 200 to 250 A are equipped with pluggable screw terminals in the control section and cable lugs in the power section.

Terminal	Version	Conductor cross section	Maximum tightening torque
X2_1 and X2_2	Slotted screws, blade width 2 mm	0.2 to 1.5 mm ²	0.25 Nm
X3	Slotted screws, blade width 3 mm	0.2 to 2.5 mm ²	0.5 Nm
U2, U1	M8 hex-headed screws, width across flats 13 mm	95 to 150 mm ²	12 Nm
For applications according to UL, only 75 °C copper conductors may be used!			
N/L2, V, L1	Slotted screws, blade width 3 mm	0.5 to 4 mm ² or (0.5 to 2.5 mm ² with ferrule) for UL AWG 20-12	0.5 Nm
Ground terminal PE	M8 setscrew with hexagon nut, wrench size 13 mm	Cable lug Drilled hole: 8 mm	12 Nm
Fan X14	Slotted screws, blade width 3 mm	0.5 to 2.5 mm ²	0.5 Nm

Master-slave connection

Terminal	Connection for
RJ 45 socket X8	Master-slave The 1:1 patch cable (included in scope of delivery) must be plugged in for correct operation (X8 connection to slave).



3 Electrical connection



Depending on the mains voltage, the fan terminal X14 must be supplied with the voltage specified below.

The lead protection must be between **2 A and a maximum of 5 A**.

The fan is temperature-controlled, switches on automatically when the device temperature reaches 85 °C, and remains in operation until the device temperature falls below 70 °C.

Voltage supply for fan

Mains voltage at the power controller	Tolerances	Fan specifications
Mains voltage AC 400 V	-15 to +10 %, 48 to 63 Hz	AC 230 V/2x30 VA
Mains voltage AC 460 V		
Mains voltage AC 500 V		

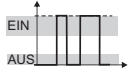
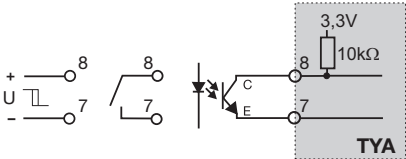
3.3 Connection diagram

Connection for	Screw terminals	Connection
Voltage supply for control electronics (corresponds to the mains voltage of the ordered device type)	L1 N/L2 V	
Load connection in the power section and protective conductor connection	U1 U2 PE	
Fan X14	20, 21 (only for load current of 250 A)	

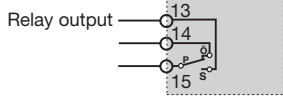
Control section

Connection for	screw terminal X2_1	Connection
Setpoint specification for current input	1 2	
Setpoint specification for voltage input (surge proof up to max. DC +32 V)	3 (GND) (for permanent control) 4	<p>external Setpoint specification with potentiometer</p>
Digital input PLC 0/24 V ON logical "1" = DC +5 to 32 V OFF logical "0" = DC 0 to < 5 V	3 (GND) (for PLC logic signals) 4	
Output DC 10 V fixed voltage (max. +10 V, 2 mA)	5	
Ground potential	6 (GND)	

3 Electrical connection

Connection for	screw terminal X2_2	Connection
Firing pulse inhibit ON logical "1" = DC +2 to 32 V OFF logical "0" = DC 0 to +0.8 V 	8 (not for PLC logic signals) 7 (GND)	
GND	7, 11	Ground potential
The ground terminals X2_2/11 or X2_1/6 of the master and slave must be connected to one another.		

Fault signal output

Connection for	screw terminal X3	Connection
Relay	13 N/O contact or collector 14 N/C contact 15 pole or emitter	

Master-slave connection

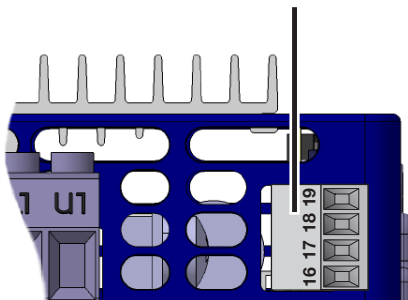
Terminal	Connection for
RJ 45 socket X8	The 1:1 patch cable (included in scope of delivery) must be plugged in for correct operation between the master and slave (X8 connection to slave).

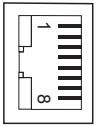
Interfaces

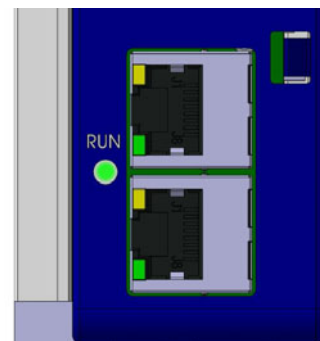
Connection	Modbus	RS422	RS485
Pluggable screw terminals on the bottom of the housing	19	TxD (-)	RxD/TxD B(-)
	18	TxD (+)	RxD/TxD A(+)
	17	RxD (-)	-
	16	RxD (+)	-

The shield of the Modbus cables must be routed to ground potential (PE)!

(RS422/485 Modbus)



PROFINET		
	1 TX+	Transmission data +
	2 TX-	Transmission data -
	3 RX+	Received data +
	6 RX-	Received data -



3.4 Switch-on sequence

Observe the general switch-on sequence

The **S2** switch is not required if no bus system is used. The control section and power section are switched on simultaneously via switch **S1**.



This is particularly important for the operation of transformer loads and resistance loads with a high temperature coefficient ($TC \gg 1$). This makes sure the necessary load start functions (soft start, current limiting, etc.) are activated accordingly.

Switch-on sequence when using bus systems

When using a bus system, the control section and power section are switched on via **S1** and **S2**.

The TYA S202 control section must always remain connected to the mains voltage (e.g. **S1** always closed) in order to maintain the fieldbus communication.

S2 is used to activate the load.

In the event of transformer loads or loads with a large temperature coefficient ($TC \gg 1$), the controller output must be blocked using the inhibit function prior to opening **S2**. After closing **S2**, the controller output must be reactivated via the inhibit function.

3.4.1 Rotary current economic circuit Master-Slave for resistive loads in star-, delta connection or transformer loads (resistive-induktive)

Prerequisite

To facilitate master-slave operation, the devices must have the same order code and the same device software version.

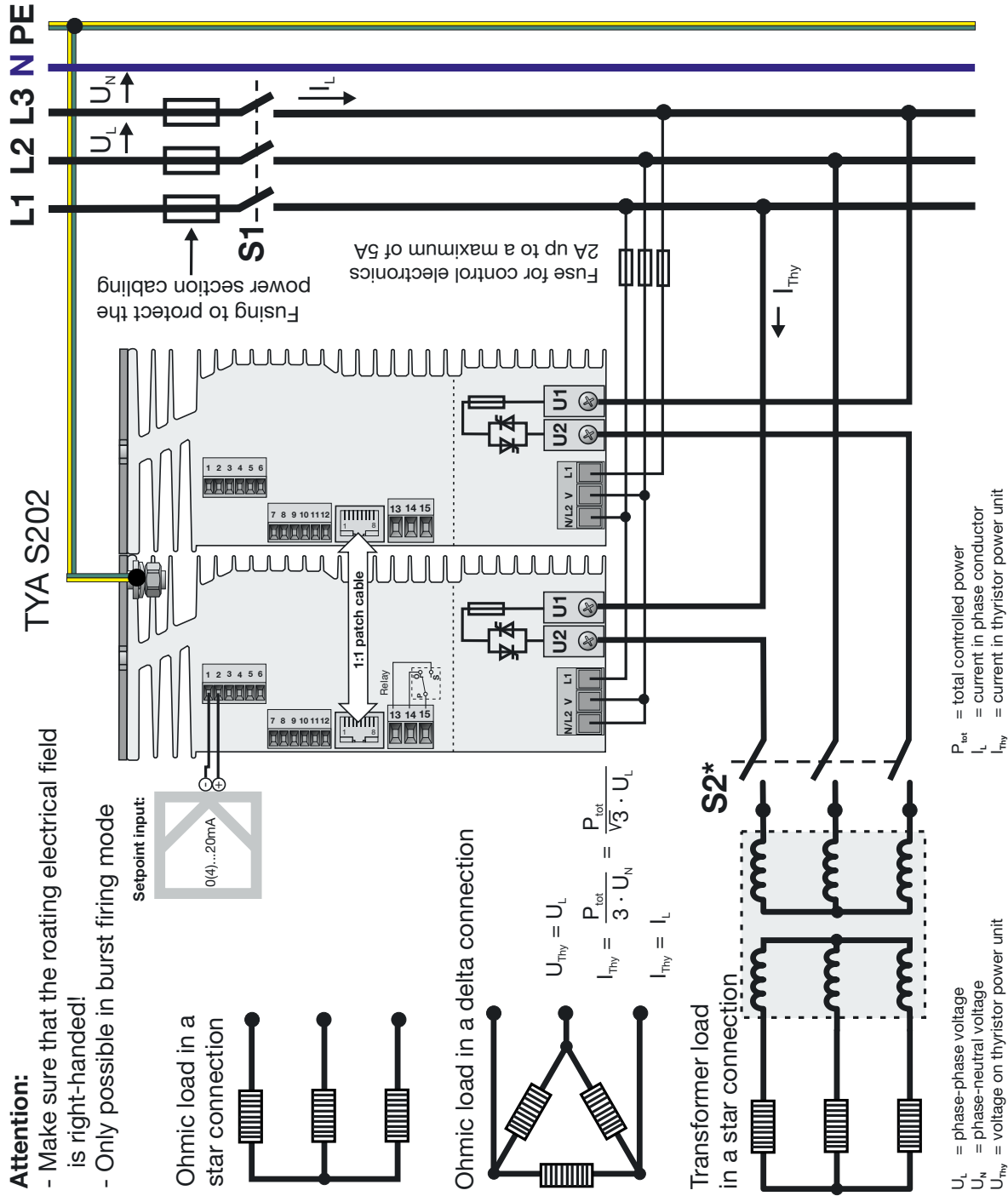
The two devices are connected by means of a 1:1 patch cable (max. length of 30 cm).

The image shows the wiring of a TYA S202, which is available ex works as a fully assembled and configured unit, and behaves exactly like two single TYA 201 devices in master-slave operation.

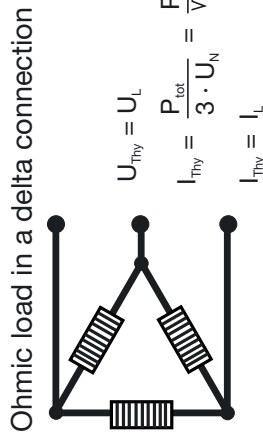
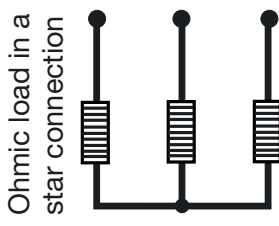
Operating mode

In the standard version, the master-slave economy circuit operates with a U^2 control. The control electronics of the master power controller assume the actual power control function, and drive the slave power controller in synchronization. This makes it possible to drive transformer loads. In combination with the fixed cycle time and the U^2 control, high voltage consistency of the individual load resistances can be achieved.

3 Electrical connection



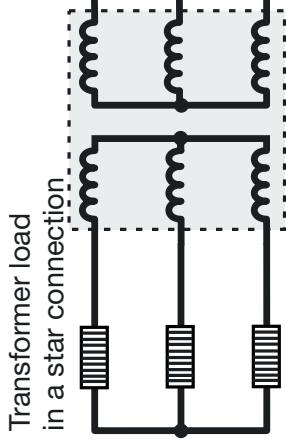
Attention:
 - Make sure that the rotating electrical field is right-handed!
 - Only possible in burst firing mode



$$U_{thy} = U_L$$

$$I_{thy} = \frac{P_{tot}}{3 \cdot U_N} = \frac{P_{tot}}{\sqrt{3} \cdot U_L}$$

$$I_{thy} = I_L$$



U_L = phase-phase voltage
 U_N = phase-neutral voltage
 U_{thy} = voltage on thyristor power unit
 P_{tot} = total controlled power
 I_L = current in phase conductor
 I_{thy} = current in thyristor power unit

* see switch on sequence if bus-systems are used




In the case of power controllers with a load current of 250 A, the fan terminal X14 must also be supplied with the specified voltage!
 The lead protection must be between **2 A and a maximum of 5 A.**

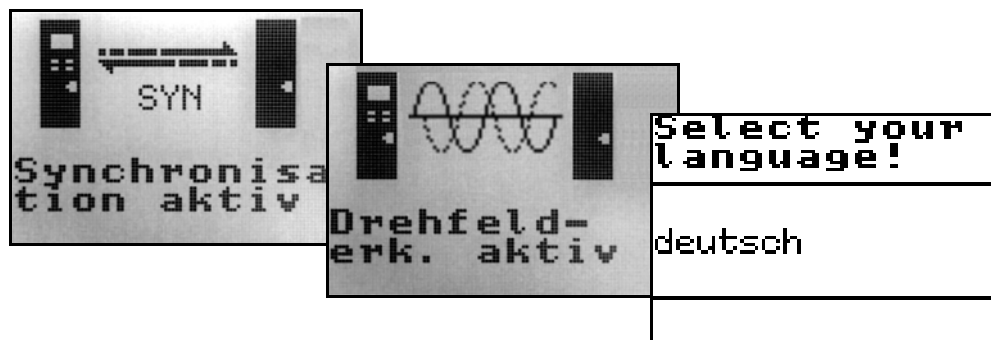
⇒ Chapter 3.2.4 "Type 709066/X-0X-250-0X-XXX-XX"

4.1 Display after switching on the device

Hourglass and national language selection

Initially, as soon as the voltage supply is switched on, the Power LED is permanently lit in green and an hourglass appears on the display. The master is then synchronized with the slave devices and rotary field detection is carried out. If everything is wired correctly, the power controller shows a national language selection on the display.


Select the national language and confirm your selection with .



Language wizard



This option enables you to select whether the language wizard should be reactivated the next time the device is started.

Select "Yes" or "No", press .

Measured values then appear on the device.

⇒ Chapter 4.1.2 "Appearance of measured values".

Error messages

The following chapter explains the error messages that may appear in the info line at the bottom of the screen:

Chapter 8 "Fehlermeldungen und Alarme"

4 Operation

4.1.1 Display and control elements

Legend	Comment	Diagram
1	The Power LED (green) lights up permanently when the voltage supply is connected. Flashes at regular intervals if the display lighting is switched off. ⇒ Chapter 9 "Was tun, wenn ..."	
2	Display (96 x 64 pixels) with white background lighting. The information line at the bottom of the display shows the current settings and error messages.	
3	Fuse LED (red) is lit in the event of a defective semi-conductor fuse on the corresponding power controller.	
4	K1 LED (yellow) fault indicator	
5	Keys: <ul style="list-style-type: none"> Increase value / previous parameter Decrease value / next parameter Cancel / one level back Programming / one level forward 	
6	USB setup interface Configuration is performed on the left device and transferred automatically to the right device via the patch cable.	
7	Spring clip to release the plastic housing ⇒ Chapter 8.2 "Defekte Halbleitersicherung austauschen"	

and can be used to view the current measured values such as currents, actual voltage values, load resistance setpoint value, device temperature, and power.

This information is also displayed in the diagnosis window for the setup program.

⇒ Chapter 7 "Setup Programm"

4.1.2 Appearance of measured values

Overview of measured values At this level, the description of the measured value is displayed in the top line, and the numerical value together with the unit is displayed in the middle.

Designation	Mains voltage	Manual mode	Device temperature
Measured value	221.7 V	019 % 318.4V 0.1A	41 °C
Info line or error		Error on connect. load	

4 Operation

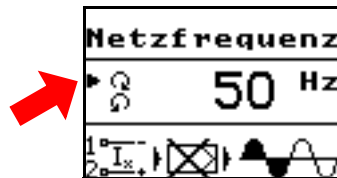
The info line shows the selected input (with terminal designation), the active subordinate control loop, and the operating mode.

It is also used to display temporary states (e.g. error messages).

⇒ Chapter 8 "Fehlermeldungen und Alarmer"

Mains frequency

In this window, the rotary field direction is shown alongside the supply frequency. The small triangle indicates the corresponding direction of rotation.



Meaning of the symbols in the info line

Input signal		Subordinate control loop		Operating mode load output	
	Voltage		None		Burst-firing operation
	Current		Logic (switch)		Soft start with phase-angle control
	Interface		Invalid control configured		Burst-firing operation with α start
	Input signal incorrectly configured				General logic
					Logic with α start
					Firing pulse inhibit

4.1.3 Meaning of the displayed measured values

Measured value	Meaning	Unit
Master mains voltage	Effective value of the mains voltage – measured on the master between the L1 and N/L2 terminals	V
Mains voltage Slave	Effective value of the mains voltage – measured on the slave between the L1 and N/L2 terminals	V
Master⁴ load voltage	Effective value of the supply voltage U12 - measured on the master between the V and U2 terminals	V
Load voltage Slave⁴	Effective value of the supply voltage U31 - measured on the slave between the V and U2 terminals	V
Master^{1,4} load current	Effective value of the load current I1 measured from the master	A
Load current Slave¹	Effective value of the load current I3 measured from the slave	A

4 Operation

Master 1 power	Effective power measured from the master	W or kW
Power Slave ¹	Effective power measured from the slave	W or kW
Three-phase power 1	Overall effective power (total effective power contributed by master and slave)	W or kW
Master1 load resistance	Effective resistance measured from the master	Ω
Setpoint	Effective setpoint value (with calculated base load)	%
Mains frequency	Currently measured mains frequency	Hz
Master device temperature	Currently measured temperature inside the master power controller	°C or °F
Slave device temperature	Currently measured temperature inside the slave power controller	°C or °F
Current input	Measured value of the current input – measured on the master power controller between terminals 1 and 2 on X2_1	mA
Voltage Input	Measured value of the voltage input – measured on the master power controller between terminals 3 and 4 on X2_1	V

¹: Is only displayed if the current transformer is fitted (option I²- / I- or P control)

4.1.4 Appearance in the configuration level

Scroll bar The entry highlighted in black is selected and contains further parameters. If there are more than three entries in one level, a scroll bar that shows the current position in the menu appears.

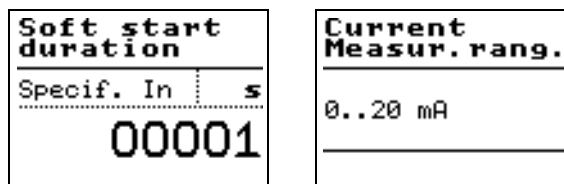
Navigation



Navigation principle

one level back	EXIT	▲	increase value/ parameter up
one level lower	PGM	▼	decrease value/ parameter down

Numerical entry or selection Once you have reached the required parameter, the ▲ or ▼ key can be used to enter a numerical value or to select a parameter.



* Save the setting using PGM.

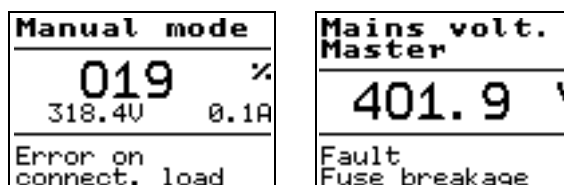
If you do not wish to apply the value, the entry can be canceled by selecting EXIT.

4.1.5 Appearance of error messages and special statuses

Cyclical appearance The symbols for input, subordinate control loop, and operating mode are displayed alternately in the info line together with error messages or information about special statuses.

⇒ Chapter 8 "Fehlermeldungen und Alarme"

Examples

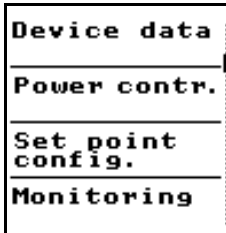


4 Operation

4.2 Operating level



All parameters for the maximum device extension level are listed in the following tables. Depending on the order details (see nameplate or device information) or the current configuration, parameters that are not required are hidden.



Here you will find the parameters that can be modified **during ongoing operation**.

They can be accessed without a password by default, but can also be protected with a 4-digit code if necessary.

⇒ Chapter 5.1.12 "Codes ändern"

During ongoing operation, the power controller can be adapted to the plant and optimized.

- * In the measured value overview, press the **PGM** key
- * Select the operating level and press **PGM** again

Editing a parameter

The changes are effective **immediately**.

Once the correct setting (e.g. for display contrast) has been found, the parameter can be stored by pressing **PGM**.

If you do not wish to apply the value, the entry can be canceled by pressing **EXIT**.

4.2.1 Device data

	Value range	Description
	deutsch english francais National language4	German (deutsch), English, and French (francais) are permanently stored in the device 1 additional national language can be subsequently loaded via Setup.
	0... 50 ...100 %	50 % is set by default.
	0000 to 1440 min	0000 minutes are set by default, which means the display is not switched off.

■ / **bold** = default setting

4.2.2 Power controller

Angle α start	
Specif. In	°el
	75

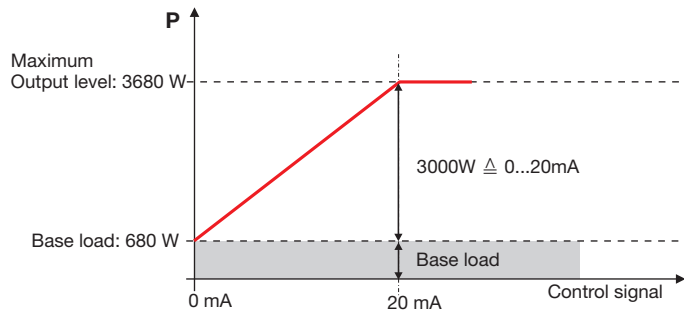
Value range	Description
0 to 75 to 90° el	75° el is set by default. If " α start" is set to "No" in the configuration, this window is not displayed and α start is set to 0° el.

■ / **bold** = default setting

4.2.3 Setpoint value configuration

Basic load	
Specif. In	V
	000.00
	30.1 V
Current load voltage	

Value range	Description
0...100 % of output level	In the case of continuous thyristor control via the analog input, the base load at the measuring range start (e.g. 0 mA) can be varied during operation . Note: This setting is only available if Power controller → Thyristor control → Continuous (power controller) is set.



■ / **bold** = default setting

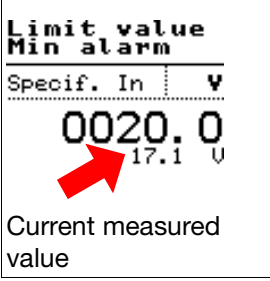
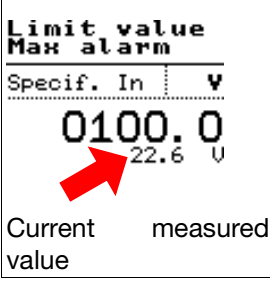
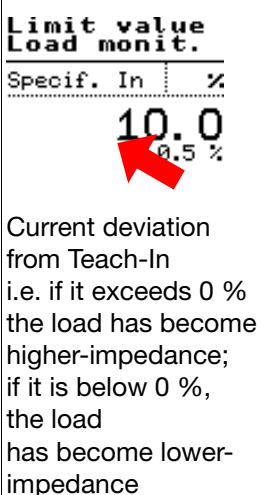
4 Operation

4.2.4 Monitoring

The value to be monitored can be adjusted.

⇒ Chapter 5.1.5 "Überwachungen"

The load voltage was used in this example.


	Value range	Your setting:
<p>Limit value Min alarm</p> <p>Specif. In V</p> <p>0020.0 17.1 V</p> <p>Current measured value</p> 	0 ... 9999.9	<p>The absolute minimum limit values for load voltage, load current, power, resistance, mains voltage, or device temperature can be monitored.</p> <p>The measurands in the master branch are measured.</p> <p>⇒ Chapter 5.1.5 "Überwachungen"</p> <p>Example: If the voltage falls below 20 V, an alarm is issued.</p>
<p>Limit value Max alarm</p> <p>Specif. In V</p> <p>0100.0 22.6 V</p> <p>Current measured value</p> 	0 ... 9999.9	<p>The absolute maximum limit values for load voltage, load current, power, resistance, mains voltage, or device temperature can be monitored.</p> <p>The measurands in the master branch are measured.</p> <p>⇒ Chapter 5.1.5 "Überwachungen"</p> <p>Example: If the voltage exceeds 100 V, an alarm is issued.</p>
<p>Limit value Hysteresis</p> <p>Specif. In V</p> <p>0001.0 12.6 V</p>	0 ... 1 ... 9999.9	<p>The switching differential at the minimum or maximum limit value</p>
<p>Limit value Load monit.</p> <p>Specif. In %</p> <p>10.0 0.5 %</p> <p>Current deviation from Teach-In i.e. if it exceeds 0 % the load has become higher-impedance; if it is below 0 %, the load has become lower-impedance</p> 	0...10...100 %	<p>Partial load failure or partial load short circuit:</p> <p>The monitoring value for the percentage of change to the load is selected (undercurrent or overcurrent).</p> <p>⇒ Chapter 5.1.5 "Überwachungen"</p> <p>By displaying the current deviations from the Teach-In value in all three phases, it is possible to check how, for example, the resistance change behaves over the entire setting range. The load monitoring limit value can then be adjusted accordingly.</p> <p>Guide values for the identification of load errors: ⇒ Chapter 6.1 "Erkennung von Lastfehlern"</p>

■ / **bold** = default setting


Load monit. Teach-In
Apply now

This function is not configured by default.

This window only appears if the following setting has been selected in the configuration level:

* Press the  key to switch to the **configuration level**


* Set Monitoring → Teach-In type load monit.
→ Manual

* Press the  key
The "Manual teach-in" function is now configured.

* Change to the **operating level** → Monitoring → Load monit.
Teach-In

* Press the  key

A screen now appears asking whether the state should be applied now. If so:

* Press the  key to apply the current load state as the OK state.

A change in the load (load error) will be evaluated by the device on the basis of this state.

■ / **bold** = default setting

4 Operation

5.1 Configuration level

The configuration level contains parameters for configuring the power controller.

If the parameters at this level are modified during operation, the power controller is locked (Inhibit) as a result. It does not provide any power in this state.

When exiting the configuration level with the **EXIT** key, the power controller continues operation with the modified parameters.

This level can be locked with a password. However, no password is set by default.



All parameters for the maximum device extension level are listed in the following tables. Depending on the device version (see nameplate) or configuration, parameters that are not required are hidden.

The configuration level can be accessed from the overview of measured values by pressing the following keys:

- * In the overview of measured values, press the **PGM** key
- * Select the configuration level and press **PGM**

The parameters are combined in the following groups, which are explained in detail as sub-chapters in the tables on the following pages.

Parameter groups

Device data	⇒ Chapter 5.1.1 "Device data"
Power contr.	⇒ Chapter 5.1.2 "Power controller"
Analog inputs	⇒ Chapter 5.1.3 "Analog inputs"
Set point config.	etc.
Monitoring	
Binary inputs	
Binary output	
RS 422/ RS 485	⇒ see Chapter 5.1.8 "RS422/485"
Change codes	

5 Configuration

5.1.1 Device data

Basic settings for display and temperature unit.

	Value / settings	Description
Language wizard active	Yes	A query appears when the device is started, asking which national language is to be used to display the subsequent operation.
	No	No query appears
National language	German	
	English	
	French	
	Setup	Spanish is added to Setup by default. Spanish can be replaced with other national languages if needs be.
Temperature unit	°C	Defines the unit for the displayed temperatures, such as the device temperature.
	°F	
Display contrast	0... 50 ...100 %	Bright/dark contrast setting
Switch-off display lighting	0000 to 1440 min	The background lighting for the display switches off once the selected number of minutes has passed. Power LED (green) flashes. 0000 means: lighting is always switched on
Apply default settings	Apply now?	The default settings are restored if the PGM key is pressed.

■ / **bold** = default setting

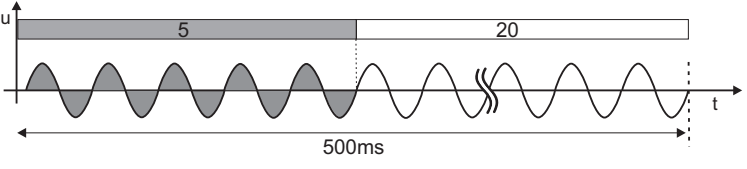
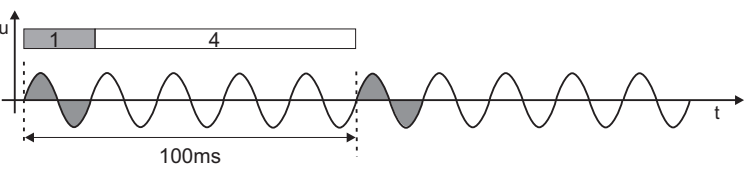
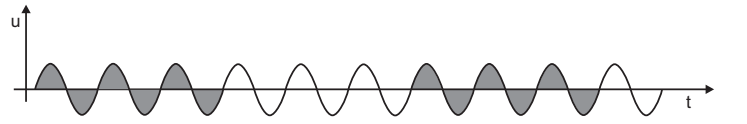
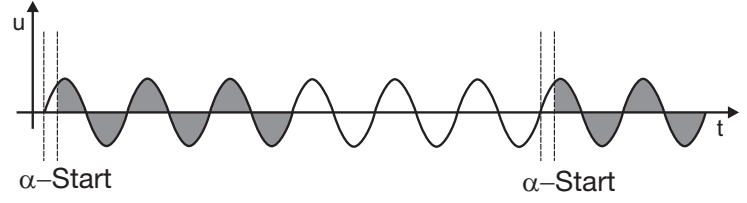
5.1.2 Power controller

Settings for the switching behavior of the power controller in the plant

	Value / settings	Description
Thyristor control	Continuous (power controller)	The power controller provides the power for the load continuously according to the setpoint specification.
	Logic (switch)	Note: Subordinate control loop cannot be modified! The power controller acts like a switch and provides the power by either switching ON or OFF.

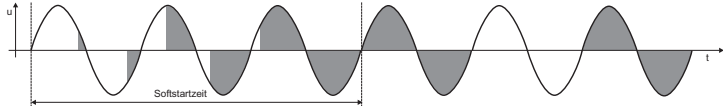
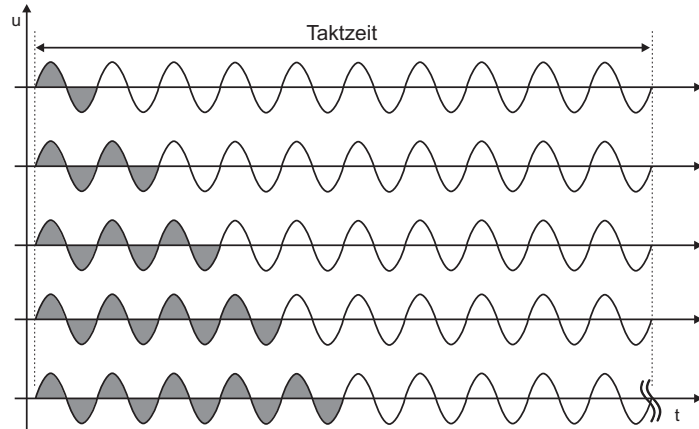
■ / **bold** = default setting

5 Configuration

	Value / settings	Description
Cycle time	Fixed (500 ms) (For slow heating elements)	<p>Note: This setting is only available in burst-firing operation. For example, for a fixed period of 500 ms, 5 sine waves are switched on and 20 switched off at an output level of 20 %.</p> 
	Fastest possible (For quick-response heating elements)	<p>The cycle time is variable with this setting. At the required output level, the device attempts to find the shortest possible cycle time for full sine waves. For an output level of 20 %, this means one sine wave ON and four sine waves OFF.</p> 
Min. ON period	None	
	3 full sine waves	<p>Dependent on the cycle time setting. At least three full sine waves are always let through. For example, at an output level of 50 % and the fastest possible cycle time, three sine waves are switched on and three switched off.</p>  <p>Note: Particularly suitable for the control of transformer loads</p>
α start	No	<p>Note: This setting is available in continuous burst-firing operation mode and in logic operation. No: for resistive load Yes: for transformer loads If set to "Yes", the first half-wave of each pulse group is cut with the set phase control angle α.</p> 
	Yes	
α start angle	0 to 75 to 90° el	Phase control angle for α start
Soft start	No	This setting determines the starting behavior of the power controller after power ON and is deactivated by default
	Yes	"Yes" means that a soft start with phase-angle control or burst-firing is performed after power ON.

■ / **bold** = default setting

5 Configuration

	Value / settings	Description
Soft start type	With phase-angle control	<p>This parameter only appears if soft start is set to "Yes".</p> <p>Starting from 180 °, the phase control angle α is steadily reduced until a full wave has passed through. This ends the soft start and the device switches to burst-firing operation.</p>  <p>Note: If the output level is reduced to 0 % for longer than 8 seconds, a soft start is initiated again as soon as the output level is increased once more.</p> <p>If current limiting is activated during the soft start phase, the soft start duration is extended because the phase control angle cannot be reduced further during current limiting.</p>
	With pulse groups	<p>This setting is available in burst-firing operation mode with a fixed cycle time and with the fastest possible cycle time. During the soft start time, the ON/OFF ratio is increased from 0 to a maximum of 100 %.</p> 
Soft start duration	1 ... 65535s	<p>Specifies the duration of the soft start.</p> <p>Note: Due to the system, when current limiting is switched on, the soft start duration is at least 4 s, even if a shorter time is configured as the soft start duration.</p>
Current limiting	No	No current limiting
	Yes	<p>Current limiting is implemented via phase-angle control.</p> <p>In this case, the load current from the master is monitored on the basis of the set current limit value. Only phase control angles that do not cause the current limit value to be exceeded are permitted.</p> <p>It is also possible to activate an external current limit value via a digital input.</p> <p>Chapter 5.1.6 "Digital inputs"</p>

■ / **bold** = default setting

Dual energy management

Value / settings	Description
Switched off	This parameter only appears with the following settings: Cycle time: fixed (500 ms), Operating mode: burst-firing operation. This setting allows 2 devices ¹ to be configured in such a way that they do not simultaneously draw power from the mains at small output levels. This prevents current peaks. ⇒ Chapter 6.4 "Duales Energiemanagement"
Device1	
Device2	
1. The master-slave group type 709066 is regarded as "one" device.	

■ / **bold** = default setting

5 Configuration

5.1.3 Analog inputs

The power controller has a voltage input and a current input. These inputs (setpoint specification) specify the output to be provided by the power controller at the load output.

In most cases, this signal is sent as a standard signal from an electronic controller or PLC and is adjusted with these settings.

	Value / settings	Description
Current measuring range	0 ... 20 mA	This setting specifies which current standard signal is connected. ⇒ Chapter 3.3 "Anschlussplan"
	4 ... 20 mA	
	Customer-specific ¹	
Current measuring range, start	0 to 20 mA	Note: This parameter only appears if "Customer-specific" is set for the current measuring range (see above)!
Current measuring range, end	0 to 20 mA	Note: This parameter only appears if "Customer-specific" is set for the current measuring range (see above)!
Voltage measuring range	0 ... 10 V	This setting specifies which voltage standard signal is connected. ⇒ Chapter 3.3 "Anschlussplan"
	2 to 10 V	
	0 to 5 V	
	1 ... 5 V	
	Customer-specific ¹	
Voltage measuring range, start	0 to 10 V	Note: This parameter only appears if "Customer-specific" is set for the voltage measuring range (see above)!
Voltage measuring range, end	0 to 10 V	Note: This parameter only appears if "Customer specific" is set for the voltage measuring range (see above)!

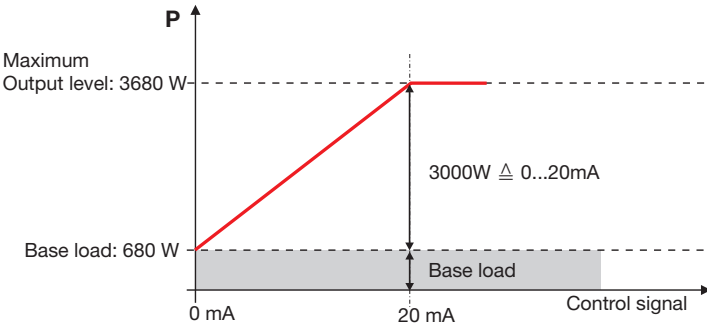
■ / **bold** = default setting

1. Inverting analog inputs:

If, for example, the current measuring range start is set to 20 mA and the current measuring range end is set to 0 mA, the power controller is switched off at 20 mA and switched on at 0 mA.

5.1.4 Setpoint value configuration

This setting determines which analog input specifies the setpoint value, how high the base load is, and which replacement value should be applied in the event of a fault.

Setpoint specification	Value / settings	Description
	Current input 1 $\overline{I_x}$ 2 $\underline{I_x}$	This setting specifies which analog input supplies the setpoint value for the power output. Note:
	Voltage input 3 $\overline{U_x}$ 4 $\underline{U_x}$	These inputs can also be used for logic operation. ⇒ For switching level, see Chapter 10.7 "Allgemeine Kenndaten"
	Via interface ↔	Means that the setpoint value for the power output is provided via an interface.
Input in the event of an error		Current, voltage, and interface input are monitored for errors (wire breaks or bus errors). This setting specifies which replacement value the power controller should use if the setpoint specification is incorrect.
	Last value	The last valid value is used by default.
	Voltage input or current input	Depending on which input is set for the setpoint specification, the second input – which is still free – appears at this point. If an error (e.g. wire break) now occurs at the current input which is set by default for the setpoint specification, the power controller uses the value at the voltage input.
	Value, adjustable	This means that the " Value in the event of an error " is used.
Value in the event of an error	000.0	This value is used in the event of an error.
Base load	0...100 % of output level	<p>Note: This setting is only available if Power controller → Thyristor control → Continuous (power controller) is selected.</p> 

■ / **bold** = default setting

5 Configuration

5.1.5 Monitoring

This allows an internal measurand to be monitored for compliance with limit values.

Depending on the switching behavior, an overrange or underrange is output at the digital output (option: relay or optocoupler).

Value / settings	Description
Limit value monitoring	
Switched off	No monitoring
Load voltage	These measurands can be monitored and are dependent on the ordered device type.
Load current	
Power (in W)	Control direction
Power (in kW)	
Resistance	Binary output relay
Mains voltage	
Device temperature	
	<p style="text-align: center;">Limit value monitoring</p> <p>The diagram illustrates the switching behavior of a binary output relay. It shows two scenarios: one for a normally open (SPST) relay and one for a normally closed (SPST) relay. The process variable (e.g., Load voltage) is plotted against time. Two limit values are shown: a minimum limit value alarm and a maximum limit value alarm. Hysteresis is indicated by the width of the pulses. For the normally open relay, the relay switches from Off to On when the process variable reaches the minimum limit value and returns to Off when it reaches the maximum limit value. For the normally closed relay, the relay switches from On to Off when the process variable reaches the minimum limit value and returns to On when it reaches the maximum limit value.</p> <p>The limit values are monitored in the master and in the slave and, if the limit value is breached, the corresponding error message is shown in the info line at the bottom of the display (e.g. "Slave2:Limit val. MinVal reached")</p> <p>Note: If Power controller -> Thyristor control -> Logic (switch) and Monitoring -> Limit value monitoring -> Load voltage, load current, power (in W), or power (in kW) is selected, the limit value monitoring only operates in the periods in which the thyristors have been fired. If the thyristors are blocked, as a general rule, the min. and max. alarms are switched off.</p>
Min. limit value alarm	0 ... 9999.9
	The absolute minimum limit values for load voltage, load current, power, resistance, mains voltage, or device temperature can be monitored. If the measurand falls below this value, an error message appears at the bottom of the display and the yellow K1 LED lights up. Depending on the set control direction, the digital output switches as shown in the diagram. The unit of the limit value corresponds to the measurand to be monitored.
Max. limit value alarm	0 ... 9999.9
	The absolute maximum limit values for load voltage, load current, power, resistance, mains voltage, or device temperature can be monitored. If the measurand exceeds this value, an error message appears at the bottom of the display and the yellow K1 LED lights up. Depending on the set control direction, the digital output switches as shown in the diagram. The unit of the limit value corresponds to the measurand to be monitored.

5 Configuration

Limit value hysteresis	0 ... 1 ... 9999.9	Switching differential at the upper and lower limit of the monitoring range
Load monitoring	None	The load is not monitored.
	Undercutting current	Note:
	Overcurrent	This parameter is only available if the device type is equipped with an I, I ² , or P subordinate control loop and the current can therefore be measured. ⇒ Chapter 6.1 "Erkennung von Lastfehlern"
Limit value load monitoring		Note: This setting is only available if load monitoring has been set to undercurrent or overcurrent.
	0... 10 ... 100 %	Partial load failure or partial load short circuit: This setting specifies the percentage by which the load current must have decreased or increased for a load error to be triggered.
Load type load monitoring	Standard	Default setting (suitable for most load types)
	Infrared radiator (short-wave)	Especially suitable for short-wave infrared radiators
Teach-In type load monitoring	Automatic, once	The Teach-In value is automatically determined once after each power ON. ⇒ Chapter 6.1.1 "Teach-In"
	Manual	Teach-In can be performed in manual mode or at the operating level . ⇒ Chapter 6.2.2 "Teach-In konfigurieren (Voraussetzung für Teach-In im Handbetrieb)" ⇒ Chapter 4.2.4 "Überwachung"
	Automatic, cyclical	Teach-In is performed cyclically at a time interval of 1 minute.
Monitoring of the mains voltage drop	No	No monitoring
	Yes	If the effective values of the analyzed half-waves are more than 10 % apart, an alarm message is displayed and the binary output for the collective alarm switches depending on the set control direction. Immediate firing pulse inhibit prevents the connected transformer loads from destroying the semiconductor fuse due to a DC component. If there are no further mains voltage drops, the firing pulse inhibit is removed and the power controller continues operation (e.g. with a soft start).

■ / **bold** = default setting

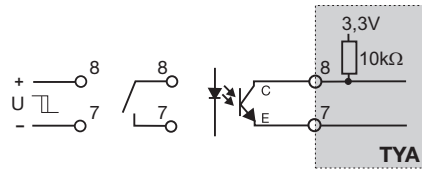
5 Configuration

5.1.6 Digital inputs

There is 1 digital input for firing pulse inhibit available, to which a potential-free contact can be connected.

Inhibit input control direction

Value / settings	Description
	The firing pulse inhibit can be triggered when the switching contact is closed or open. ⇒ Chapter 3.3 "Anschlussplan"
Open, load ON	By default:
Open, load OFF	Inhibit input open, power controller supplies power. Inhibit input closed, power controller does not supply power.



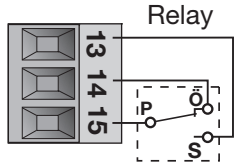
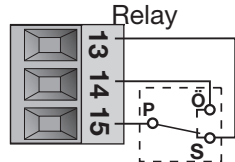
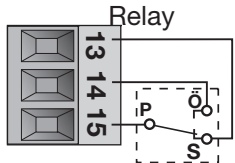
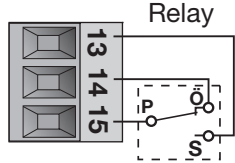
■ / **bold** = default setting

5.1.7 Digital output

With the digital output, it is possible to choose between the output mode "**collective fault transmitter**" or "**Interf. signal**".

⇒ Chapter 8.1 "Binärsignal für Sammelstörung"

The control direction is used to select the switching behavior of the relay and determine whether, in the event of an error message, it should switch on (error message via N/O contact) or drop out (error message via **N/C contact**).

	Value / settings	Description
Output mode	Collective fault transmitter	The digital output switches if a collective fault occurs on the device. This can be configured as an "N/C contact" or as an "N/O contact" (see below). In addition, the K1 LED lights up in the event of a fault.
	Interf. signal	The digital output is controlled via an interface
Control direction, digital output	Normally open contact	No error message or signal via interface is logically 0 "Low": Switching behavior: 14 and 15 pole and N/C contact closed  <p>Error message present or signal via interface is logically 1 "High": Switching behavior: 13 and 15 pole and N/O contact closed</p> 
	Normally closed contact	No error message or signal via interface is logically 0 "Low": Switching behavior: 13 and 15 pole and N/O contact closed  <p>Error message present or signal via interface is logically 1 "High": Switching behavior: 14 and 15 pole and N/C contact closed</p> 

■ / **bold** = default setting

5.1.8 RS422/485

5 Configuration

Interface parameters for RS422/485 (see interface description B709061.2)

	Value / settings	Description
Baud rate	9600	
	19200	
	38400	
Data format	8-1-none	Data bits-stop bits-parity check
	8-1-odd	
	8-1-even	
	8-2-none	
Device address	1 ...255	
Min. response time	0 ... 500 ms	

■ / **bold** = default setting

5.1.9 Changing codes

Here, it is possible to assign passwords (4-digit numeric codes) for **manual mode**, **operating level**, and **configuration level** to protect them from unauthorized access.

	Value / settings	Description
Code, manual mode	0000 ... 9999	0000 means: no inhibit 9999 means: level is hidden
Code, operating level	0000 ... 9999	0000 means: no inhibit 9999 means: level is hidden
Code, config. level	0000 ... 9999	0000 means: no inhibit

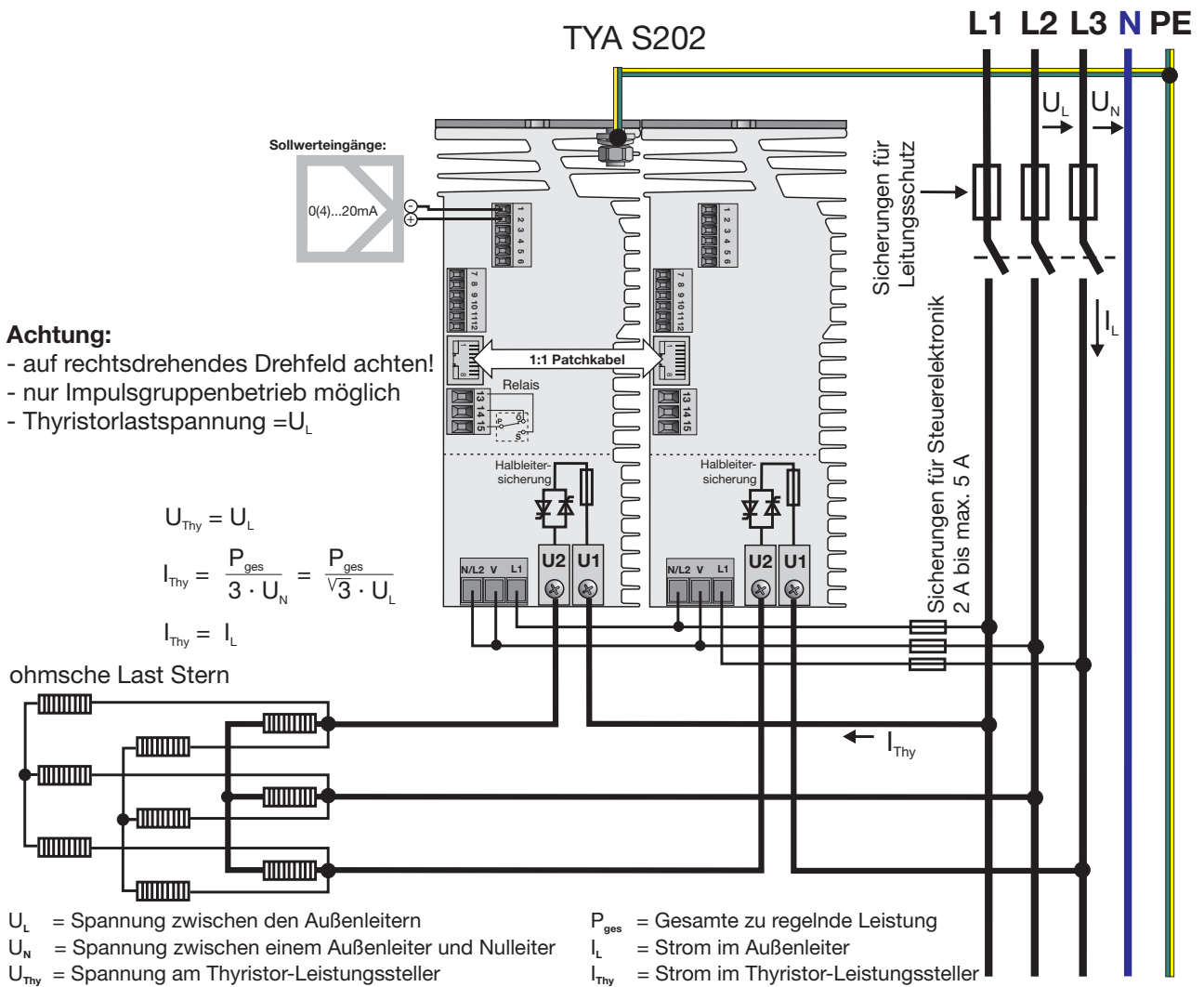
■ / **bold** = default setting

5.2 Configuration example

- Requirements**
- Power controller mains voltage 400 V
 - 9 heating elements each with 1 kW
 - Star connection with isolated star points
 - Load current: $9000 \text{ W}/(3 \times 230 \text{ V}) = 13 \text{ A}$
 - Temperature coefficient $TC = 1$
 - Base load: 0 %
 - Setpoint specification via standard signal of 0 to 20 mA.

These requirements are sufficient for the following power controllers:

Device type 709066/X-01-020-00-400-00



5 Configuration

6.1 Detection of load faults

The load monitoring function detects the percentage change in resistance of the load. It can detect and signal a load failure, partial load failure, or a partial load short circuit.

Undercutting current

This function is used for one or more heating elements connected in parallel that are to be monitored for failure.

Overcurrent

This function is used for several heating elements connected in series that are to be monitored for short circuits.

Function

This function not only takes the decreasing or increasing load current into consideration but also includes the load voltage in the monitoring process.

The plant's correct load ratios are saved during Teach-In.

Based on this state, the load changes are continuously monitored irrespective of the required output level. In the event of a failure or short circuit of a heating element, the load current increases or decreases. This is detected by the load monitor and a load fault is signaled.


Limit value

A limit value must be entered as a % in the configuration or operating level for load monitoring. This limit value depends upon the number of heating elements connected in parallel or in series.

For heating elements with a high positive or negative temperature coefficient, a suitable limit value must be determined independently. The values in % given below (see arrow) are used for this purpose.

A value in % is displayed for each of the three phases, which represents the current deviation from the Teach-In values as a percentage. Access this window via Operating level → Monitoring → Limit value load monit.

Limit value Load monit.	
Specif. In	%
010.0	2.0 %



These values can be used to find out in what phase a load error occurred. If a load break occurs in phase L3, for example, the value in % exceeds the set limit value (10 % in the table).

6 Special device functions

For heating elements with a temperature coefficient $TC \approx 1$, the limit value can be taken directly from the following tables:

Undercurrent

Number of heating elements	Star connection with separate star points without neutral conductor	Star connection with common star points without neutral conductor	Delta connection
5	10 %	-	-
4	13 %	10 %	-
3	17 %	13 %	10 %
2	25 %	20 %	12 %
1	50 %	50 %	21 %
Example: 2 heating elements			

The specifications in % refer to **resistance changes**

Overcurrent

Number of heating elements	Star connection without neutral conductor	Delta connection
6	-	-
5	10 %	-
4	10 %	10 %
3	14 %	13 %
2	25 %	26 %
Example for 2 heating elements		

The specifications in % refer to **resistance changes**



As a general rule, load monitoring does not yet take place during the soft start phase (which can last for an extended period due to active current limiting) as the standard working range of the load has not yet been reached. Teach-In cannot yet be performed in this phase either.

6.1.1 Teach-In

Depending on the configuration of the parameter "Load monit. Teach-In", Teach-In (i.e. determination of the load measured values in the OK state) is either performed once automatically after power ON or automatically and cyclically, repeatedly every minute, or manually.

"Manual" Teach-In

For "Manual Teach-In", the power controller must be told once after the operating point has been reached that it is now to perform the Teach-In. This can be performed in the operating level or in manual mode.

⇒ Chapter 4.2.4 "Überwachung"

⇒ Chapter 6.2.2 "Configuring Teach-In (prerequisite for Teach-In in manual mode)"

In this variant of Teach-In, the Teach-In values are then permanently saved. Teach-In does not need to be performed again when the power controller is switched off and on again.

Teach-In can be repeated whenever necessary. The old Teach-In values are then overwritten by the new ones.

The Teach-In values are only deleted if the load monitoring Teach-In parameter is explicitly configured to "Manual Teach-In" or when the default setting is applied. Teach-In is not affected when other parameters are reconfigured.



From software version 256.01.08, the determined Teach-In values are also transferred when the setup data of one power controller is transferred to another.

If "Manual Teach-In" has been configured but no Teach-In has been conducted, the message "Teach-In load monitoring!" appears on the display as a reminder. Manual Teach-In can only be performed on the device itself, not via the setup program.



To ensure that the load ratios for later operation are recorded precisely, only perform the Teach-In at a load current of at least 20 % of the nominal value.

Teach-In "Automatically once"

"Automatically once" means that the Teach-In values are temporarily saved after each power ON.

This setting is suitable only for heating elements with a temperature coefficient $TC = 1$.

When the power controller is disconnected from the mains voltage, the Teach-In values are deleted again. After another power ON, load monitoring therefore remains inactive until a new Teach-In process is performed. To ensure that the load ratios for later operation are recorded precisely, the Teach-In is only performed in phase angle control with at least 30 % of the output level. (In burst-firing operation mode, this restriction is not needed because a sufficiently high current always flows when the thyristor is fired. In this case, Teach-In is always performed shortly after a power ON or – if configured – after the completion of the soft start.)

6 Special device functions

Teach-In "Automatically cyclically"

"Automatically cyclically" means that the Teach-In values are temporarily saved again at intervals of 1 minute. This setting is particularly suitable for SIC heating elements as in this case the resistance in the load point changes with time due to aging.

When the power controller is disconnected from the mains voltage, the most recently detected Teach-In values are deleted again. After another power ON, the power controller resumes automatic Teach-In detection.

6.2 Manual mode

In this case, the setpoint value can be manually preset in % without the need for external wiring via the analog input.

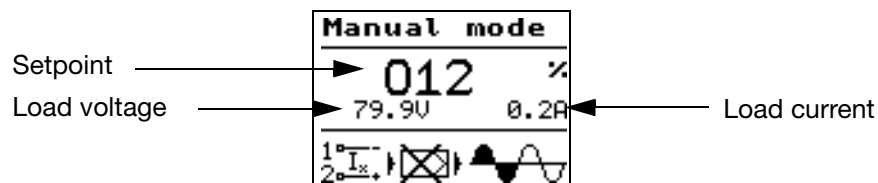
6.2.1 Setpoint specification in manual mode


Starting

Manual mode, as set by default, can be accessed without entering a code.

- * Press the **PGM** key once (selection menu)
- * Press the **PGM** key again (manual mode)
- * Use the **▲** or **▼** key to increase or decrease the setpoint value

The changes become effective immediately at the load output and are indicated on the display.



 The setpoint value for manual mode is not saved in the event of a power failure!

6.2.2 Configuring Teach-In (prerequisite for Teach-In in manual mode)

The Teach-In function records the current/voltage ratio of a load in the OK state.

This function is not configured by default.

⇒ Configuration level See "Teach-In Typ Lastüberwachung" on page 62.

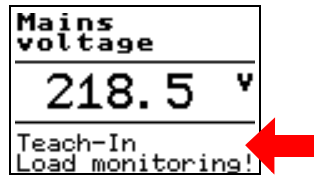
Configuring "manual" Teach-In

The power controller is in the "Measured value overview" level

- * Press the **PGM** key
- * Config. level → Monitoring → Load monitoring → Undercurrent or overcurrent → Teach-In type load monit. → Set to "manual"
- * Press the **PGM** key
- * Press the **EXIT** key twice

6 Special device functions

If Teach-In is being performed for the first time, the message "Teach-In load monitoring" appears in the bottom line of the display.

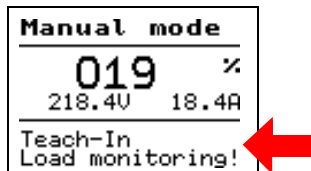


6.2.3 Performing Teach-In in manual mode

The power controller is in the "Measured value overview" level

- * Press the **PGM** key twice to return to **manual mode**.

If Teach-In is being performed for the first time, the message "Teach-In load monitoring" now appears in the bottom line of the display.



- * Press the **PGM** key and the following message will appear:



- * Press the **PGM** key to apply the current load state as the OK state.

A change in the load (load error) will be evaluated by the device on the basis of this state.

Repeating Teach-In

Teach-In can be repeated any number of times in manual mode

- * Press the **PGM** key and the following message will appear:

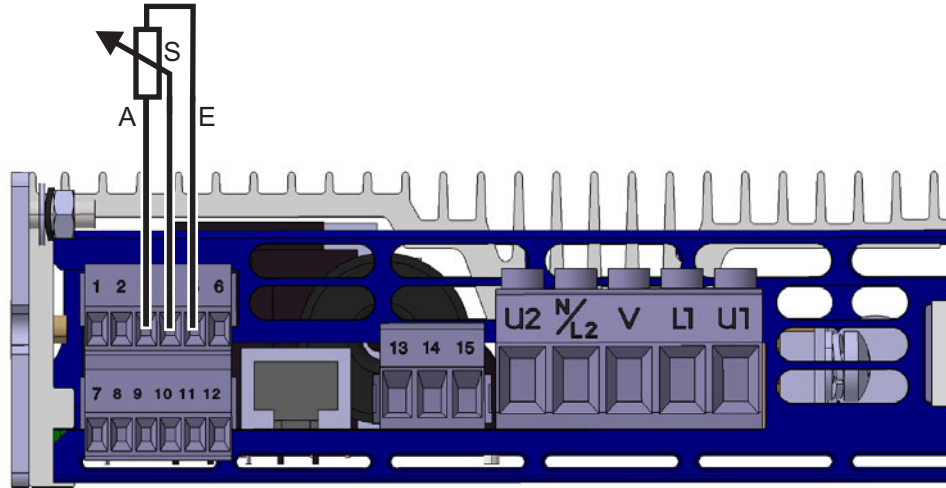


- * Press the **PGM** key to apply the current load state as the OK state.

6 Special device functions

6.3 Setpoint specification via potentiometer

For this, a 5 k Ω potentiometer is connected to the voltage input. It is supplied with DC 10 V at terminal 5 of the power controller.



- * Configuration level → Analog inputs → Set voltage measuring range 0 to 10 V
- * Configuration level → Setpoint config. → Setpoint specification → Set voltage input

Now the power controller power is preset via the external potentiometer.

6.4 Dual energy management

This allows setpoint values of up to 50 % each to be preset on two master-slave power controllers without causing current peaks in the network when they are switched on simultaneously.

No current peaks are caused in the network even if the setpoint values are asymmetrically distributed (e.g. 30 % and 70 %).

More than 2 power controllers

If more than two power controllers are required in a plant, they must be divided into groups of two. The "Dual energy management" parameter (Device1 and Device2) is set in each group.

Pre-requisites

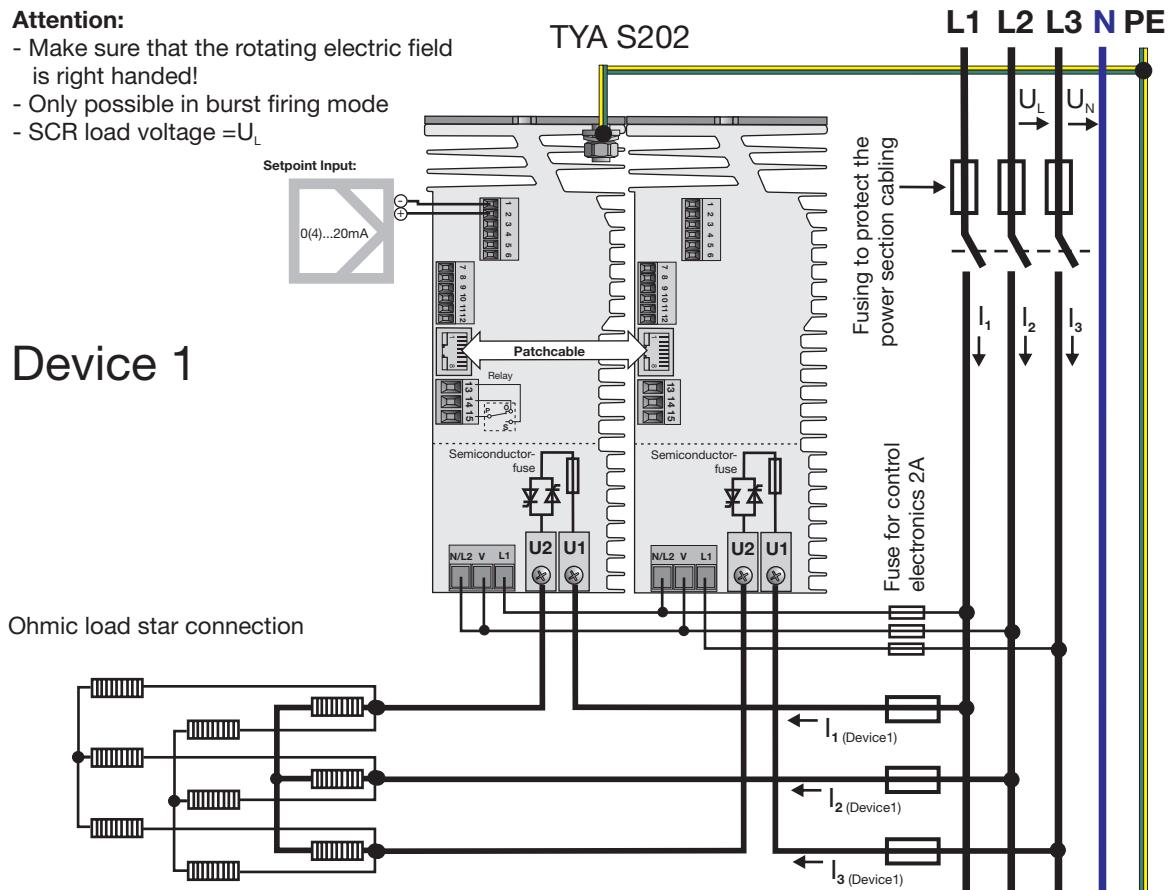
- The two master-slave devices must be wired identically as shown in the following image.
- The control electronics and the load circuit must have the same phase
- Synchronize both master-slave devices in a group by switching them on simultaneously
- The cycle time must be set to **500 ms (fixed)**
- In each group, one master-slave device must be configured as **Device1** and the other master-slave device as **Device2**.

6 Special device functions

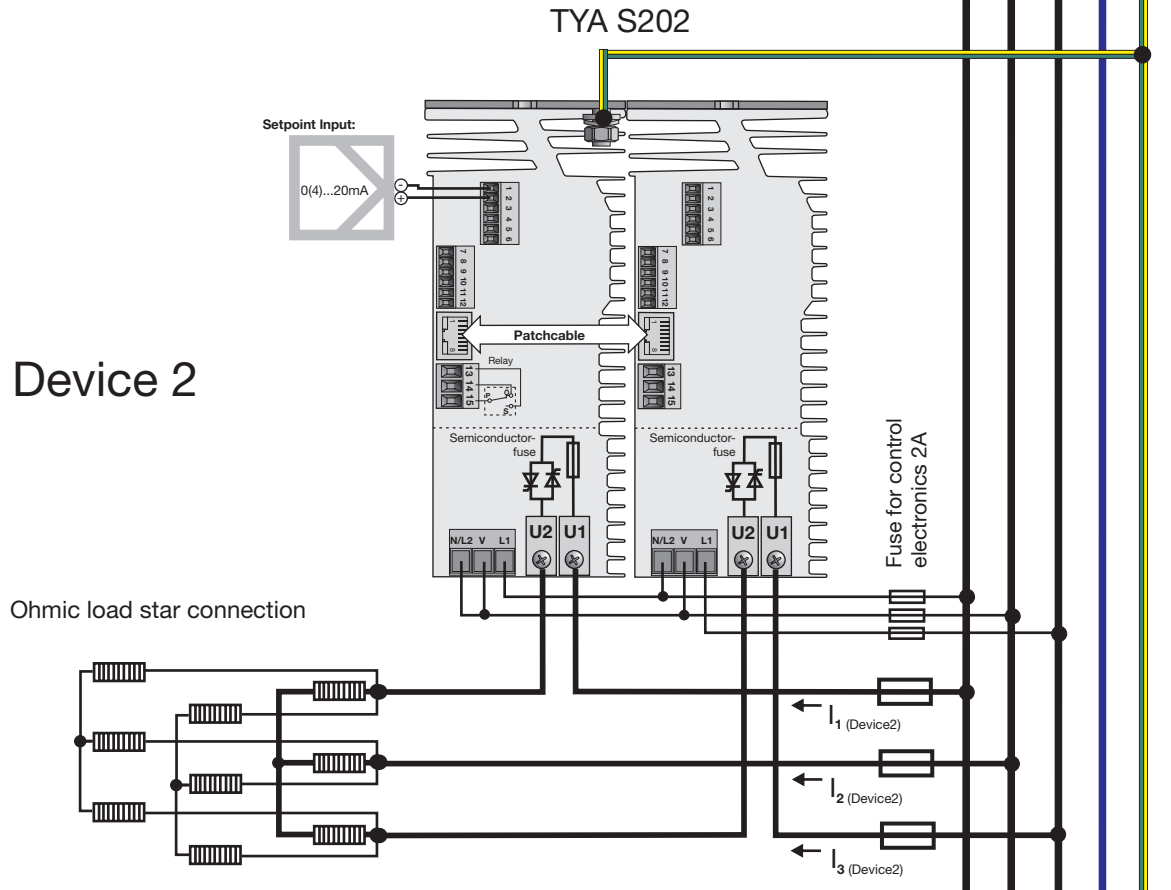
Attention:

- Make sure that the rotating electric field is right handed!
- Only possible in burst firing mode
- SCR load voltage = U_L

Device 1



Device 2

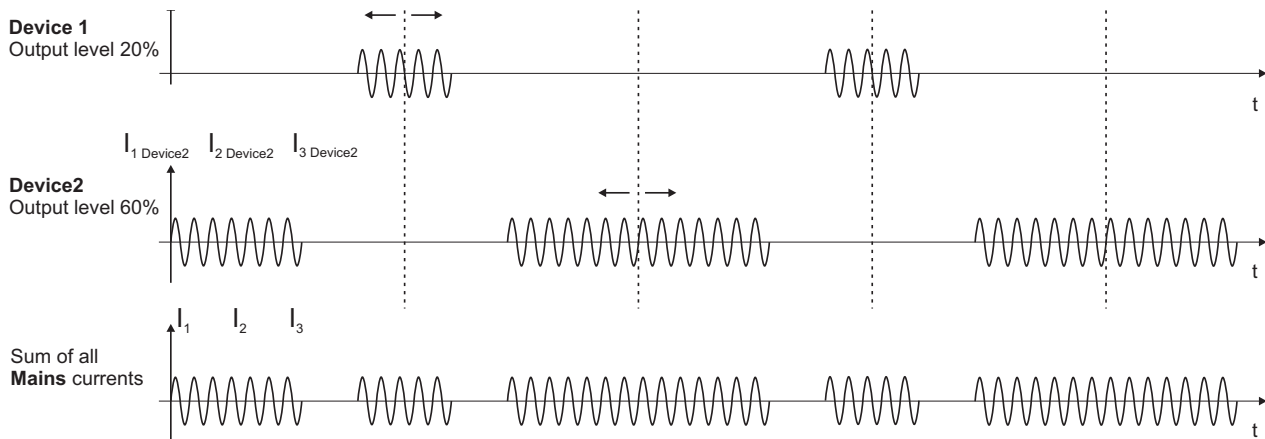


6 Special device functions

The two power controllers switch on at different times. Starting from the dashed lines, the dispersion of energy takes place symmetrically to the left and right (see arrows). For as long as the total output level of the two devices is below 100 %, two device currents in a single phase are prevented from overlapping. The next current level in the network is not started until the total output level exceeds 100 %.



If one power controller performs a restart when the configuration level is exited, it no longer operates synchronously with the others. All master-slave devices have to be switched on again simultaneously via a joint main switch!

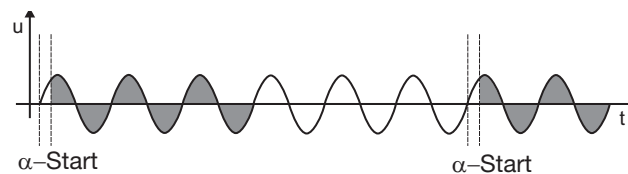


6.5 α start

Default setting

The phase-angle control of the first half-wave (α start) is not activated. For transformer loads, the thyristor power controllers operate in continuous burst-firing mode and in logic operation with phase-angle control of the first half-wave.

The factory setting is an angle of 70 °el. (electrical). This value can be adjusted at the configuration level or operator level within the range of 0 to 90 °el.



6.6 Monitoring of the mains voltage drop

If the effective values of the analyzed half-waves are more than 10 % apart, an alarm message is displayed and the binary output for the collective alarm switches depending on the set control direction.

Immediate firing pulse inhibit prevents the connected transformer loads from destroying the semiconductor fuse due to a DC component. If there are no further mains voltage drops, the firing pulse inhibit is removed and the power controller continues operation (e.g. with a soft start).

Default setting Monitoring is not activated.
⇒ Chapter 5.1.5 "Überwachungen"

6.7 Firing pulse inhibit

The inhibit function serves to protect the thyristor power controller and the connected devices.

Internal The thyristor output is locked during:

- Device switch-on (during the startup procedure)
- Changes in the configuration level
- Insufficient or excessive voltage supply
- Master/slave data line interruption
- Master/slave synchronization failure
- Setup of data transfer to the device
- Device temperature greater than 115 °C
- Rotary field error
- Short-term supply drops > 10 % within a half-wave

⇒ Chapter 5.1.5 "Überwachungen"

External Via the "Inhibit" digital input
⇒ Chapter 3.3 "Anschlussplan"

Alternatively, the thyristor output can also be switched off via the PROFIBUS or RS422/485 interfaces.

6 Special device functions

6.8 Thyristor control logic (switch)

- Operating mode** If the power controller is set to → Thyristor control → Logic (switch), the power controller operates as an electronic switch.
For as long as the configured digital or analog input is closed, the thyristors are fired in zero crossing of the mains voltage and are only locked again when the digital or analog input is opened.
- Transformer loads** In the case of transformer loads, the first mains voltage half-wave of each pulse group must be cut. This can take place by configuring α **start** and entering a **value**.
⇒ Chapter 5.1.2 "Steller"
The phase control angle for each first half-wave can be selected between 0 and 90°.
- Time behavior** The TYA S202 is not suitable for the targeted control of individual sine waves.

7 Setup program

The setup program enables all data for the device to be configured conveniently on a PC so that it can then be transferred to the device.



For configuration of the power controller it is sufficient to insert the USB cable into the master power controller and connect it to the PC.

The configuration data is applied as soon as the device is switched on.

7.1 Hardware

- 500 MB hard disk space
- 512 MB RAM

7.2 Compatible operating systems

- Microsoft® Windows® 2000/XP/Vista
- Windows7 32-bit
- Windows7 64-bit
- Windows 8 - 32-bit
- Windows 8 - 64-bit
- Windows 10 - 32-bit
- Windows 10 - 64-bit

Users




If several users are managed on one computer, make sure that the user who is logged in is the person who will be working with the program later.

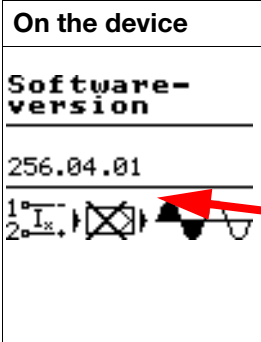
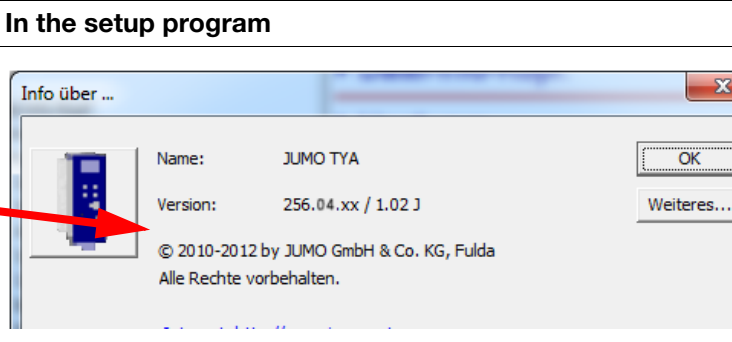
The user must have administrator rights for installing the software. After installation, the rights can be restricted again.

Failure to observe this information means that correct and complete installation cannot be guaranteed!

Software versions

The software versions for the device and the setup program must be compatible. An error message will appear if this is not the case!

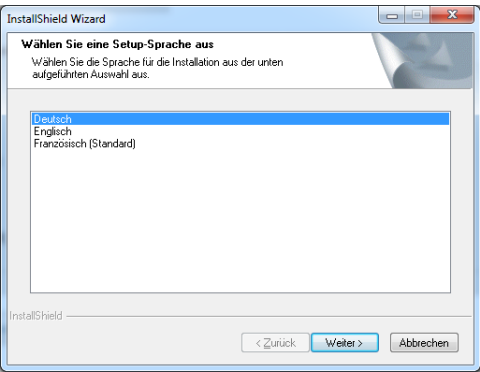
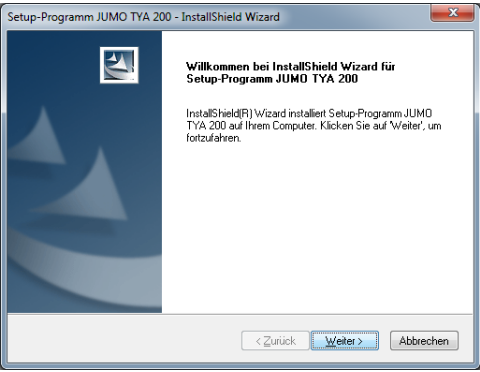
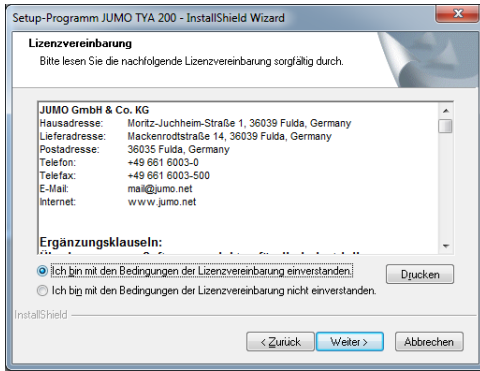
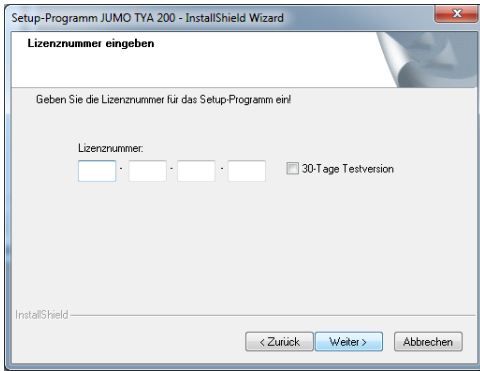
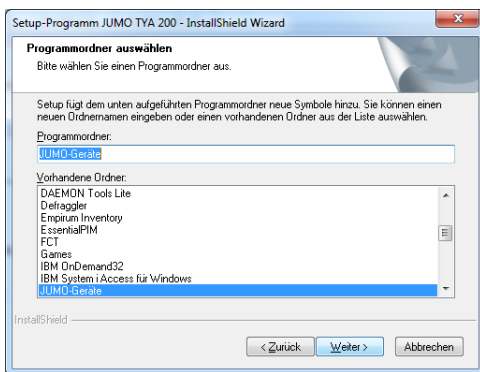
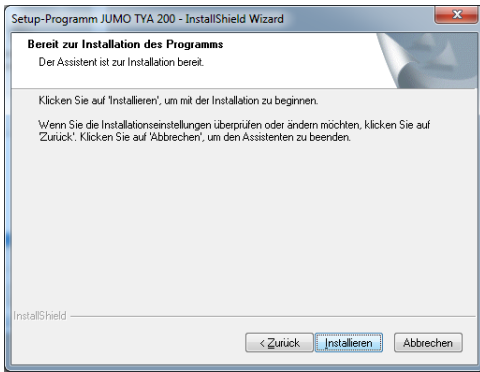
- * After switching on the device, press  The device software version is shown in the Device info menu.
- * Click "Info" in the setup program menu bar

On the device	In the setup program
	

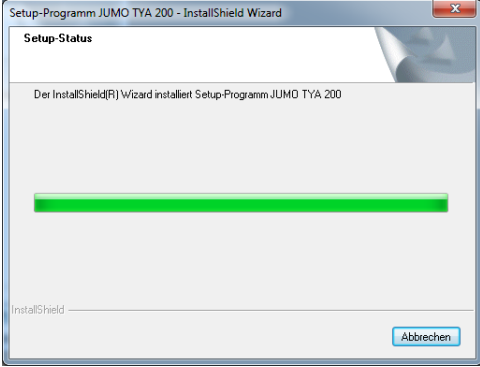
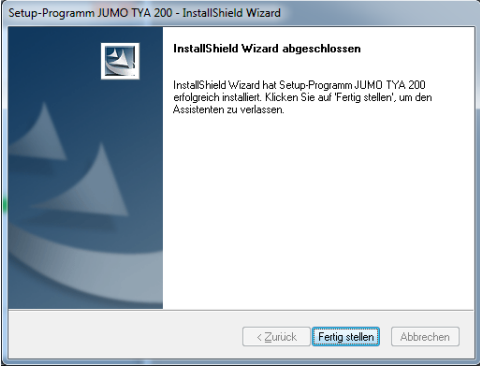
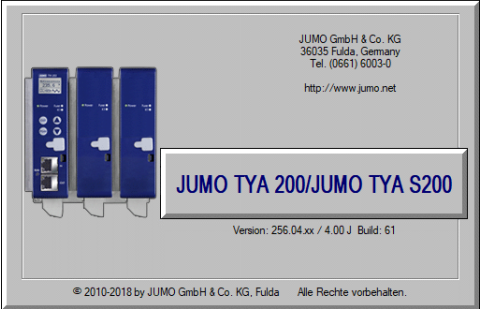
7 Setup program

7.3 Installation

* Install the setup program

Installation steps	Appearance on the PC screen	
	<p>1</p> 	<p>2</p> 
<p>Enter license number</p>	<p>3</p> 	<p>4</p> 
	<p>5</p> 	<p>6</p> 

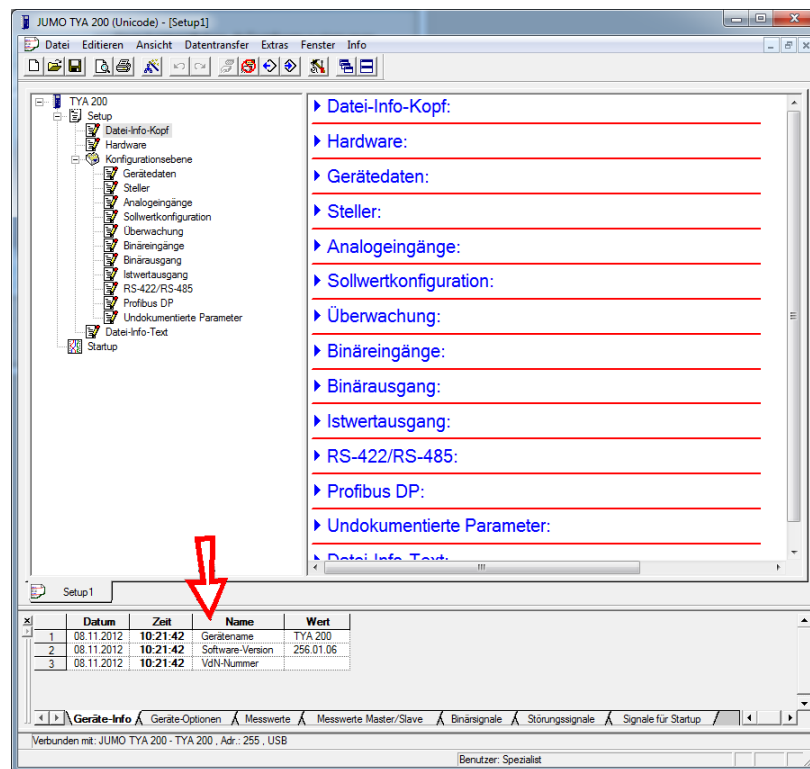
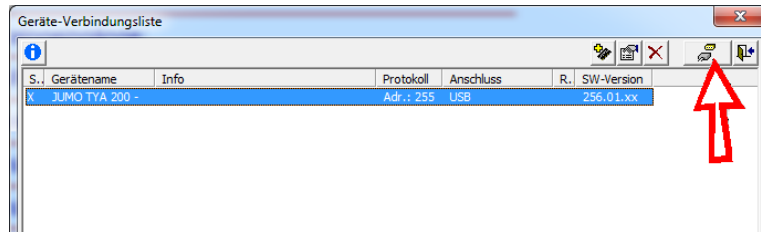
7 Setup program

Installation steps	Appearance on the PC screen	
Installation complete	7 	8 
Launch setup program	9 	

7 Setup program

7.4 Program start

- * Start the setup program using the Windows start menu
- * Connect the socket of the power controller to a USB socket on the PC using the supplied USB cable
- * Click *Connect* in the menu bar



Diagnostics

The diagnosis window appears at the bottom of the screen and shows the device info and the current measurement data. The connection has been established.



The power controller supplies no power while setup data is being transferred "to the device". The device restarts after the transfer.

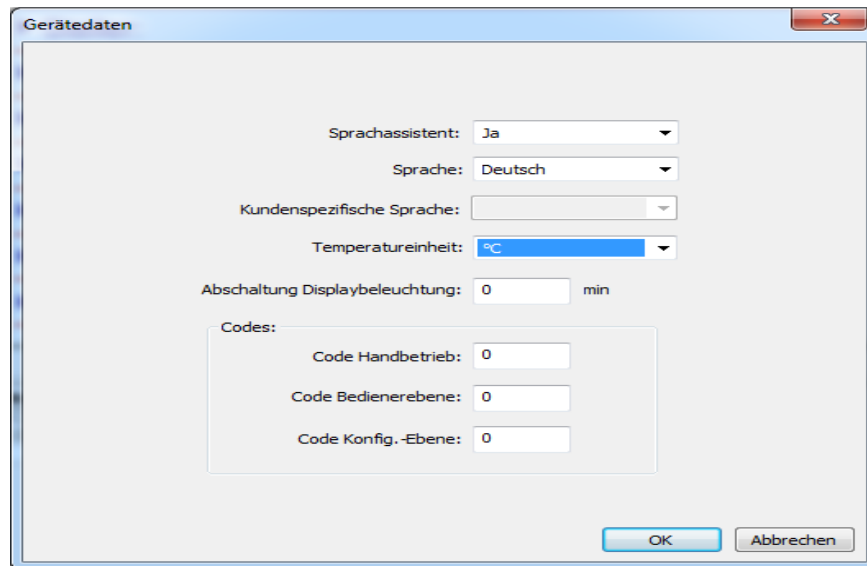
7.5 Forgotten the code?

If you have forgotten your password, you can extract the device data or enter a new code word via the setup program.

Extracting set-up data

- * Perform a *Data transfer* → *from the device*

The extracted codes are visible in the Device data menu.



Entering new codes

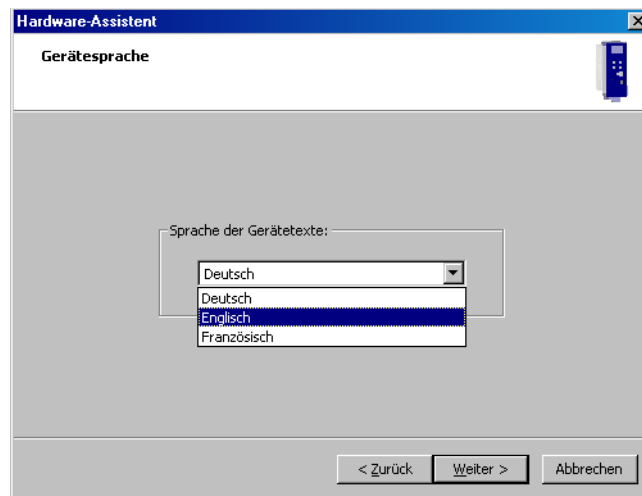
- * Enter a new code
- * Perform a *Data transfer* → *to the device*
After the setup data transfer, the device performs a restart and the codes are activated.

7 Setup program

7.6 Changing the language of the device texts

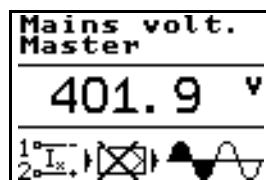
The default national language is specified in the order details. Only one national language can be transferred to the device with the setup program.

- * Connect the device to the PC using the USB cable
- * Start the setup program
- * Perform a *Data transfer* → *from the device*
- * *Edit* → *Execute hardware* and the hardware wizard will start
- * Click *Automatic detection* and the dialog for the device language will appear.



- * Select the desired national language
- * Continue in the hardware wizard by clicking *Continue* until it is completed
The device texts in the selected national language can now be found in the setup file.
- * Perform a *Data transfer* → *to the device*
- * Save the setup file and wait until the data transmission has been successfully completed

The device now restarts and texts will appear on the display in the desired national language.



8 Error messages and alarms

Cyclical appearance

The symbols for input, subordinate control loop, and operating mode are displayed alternately in the info line together with error messages or information about special statuses.

⇒ Chapter 4.1.2 "Darstellung von Messwerten"

Examples

Mains volt. Master <hr/> 401.9 V <hr/> Fault Fuse breakage	Manual mode <hr/> 019 % 318.4V 0.1A <hr/> Error on connect. load
---	---

The following alarms are limits entered by the users themselves that are intended to monitor the process:

Alarms	Cause	Remedy
Master: Limit val. Min-Val reached	The value has fallen below the selected limit value for the min. alarm at the master or slave	Check why the value has fallen below the limit value
Slave: Limit val. Min-Val reached		
Master: Limit val. MaxVal reached	The value has fallen below the selected limit value for the max. alarm at the master or slave.	Check why the limit value has been exceeded
Slave: Limit val. Max-Val reached		

The following error messages are detected separately in the master and slave:

Error message	Cause	Remedy
Master: Fault at connected load	Break or short-circuit of a load resistor. ⇒ Chapter 6.1 "Erkennung von Lastfehlern"	Replace defective heating elements.
Slave: fault at connected load		
Master: Fault, fuse failure	1. Semiconductor fuse defective; the red Fuse LED is lit accordingly.	⇒ Chapter 8.2 "Replacing a defective semiconductor fuse"
Slave: Malfunction Blown fuse (red LED fuse is lit)	2. No voltage at terminal U1; the red Fuse LED is lit accordingly	- Check wiring - Check the wire fuse for the load circuit
	3. The voltage supply for the control electronics L1/N does not have the same phase as the load circuit U1/U2 in the master, slave power controller.	Check wiring
	4. Thyristor in the master power controller defective (only with three-phase economy circuit where nominal voltage < 230 V)	The device must be returned to JUMO for repair. * Return the device

8 Error messages and alarms

Error message	Cause	Remedy
Master: Malfunction Thyristor failure	Thyristor defective	The device must be returned to JUMO for repair. * Return the device
Slave: thyristor breakage		
Master: Thyristor short circuit	Thyristor defective Note: Monitoring only works when the load resistance is so low that at least 10 % of the power controller nominal current is flowing.	The device must be returned to JUMO for repair. * Return the device
Slave: Thyristor short circuit		
Master: Caution! High temperature	Device temperature in the master or slave is higher than 100 °C (Excess temperature)	<ul style="list-style-type: none"> - Ensure adequate ventilation - Reduce load current - Use power controller with higher maximum load current
Slave: Caution! High temp.		
Master: Limit. active high temp.	Device temperature in the master or slave is higher than 105 °C Device is too hot, power is reduced! (Limited power due to excess temperature)	<ul style="list-style-type: none"> - Ensure adequate ventilation - Reduce load current - Use power controller with higher maximum load current
Slave: limit. active high temp.		
Master: Mains volt. too low	Mains voltage is not within specified tolerance range ⇒ Chapter 10.1 "Spannungsversorgung, Lüfterkenndaten bei 250A, Laststrom"	Check nominal voltage of the device type ⇒ Chapter 1.3 "Bestellangaben"
Slave: supply volt. too low		
Master: Mains volt. too high	Mains voltage is not within specified tolerance range Chapter 10.1 "Spannungsversorgung, Lüfterkenndaten bei 250A, Laststrom"	Check nominal voltage of the device type ⇒ Chapter 1.3 "Bestellangaben"
Slave: supply volt. too high		
Master: Temp drop in supply	Dangerous temporary DC component for transformer loads was detected in the master or slave power controller. ⇒ Chapter 5.1.5 "Überwachungen"	Ensure stable mains supply.
Slave: Temp.drop in mains voltage		

The following error messages apply for the entire power controller and are not divided into master and slave

Alarms	Cause	Remedy
Master-slave rotary field error	-Counterclockwise rotary field was detected -May also appear if the 1:1 patch cables of Slave1 and Slave2 are mixed up. ⇒ Chapter 3.1.1 "Typ 709066/X-0X-20-0X-XXX-XX"	⇒ Chapter 3.4.1 "Drehstrom Sparschaltung Master-Slave für ohmsche Lasten in Stern-, Dreieckschaltung oder Trafolasten (ohmsch-induktiv)"
Master-slave wiring is wrong.	Wiring fault has been detected	

8 Error messages and alarms

Alarms	Cause	Remedy
Rotary field detection failed	Rotary field detection not possible	<ul style="list-style-type: none"> - Check connection ⇒ Chapter 3.3 "Anschlussplan" - Eliminate mains disturbances
Master-slave Error in comm.	Error in the data transfer between master and slave	Check data connection of the 1:1 patch cable
Data cable faulty	Communication between master and slave interrupted.	Check the 1:1 patch cables and replace if necessary
Synchronization failed	Slave device switched off or communication between master and slave interrupted	Check data connection of the 1:1 patch cable or voltage supply

Messages for special device states:

Teach-In load monitoring!	Reminder that "manual" Teach-In has been configured but not yet executed.	Perform Teach-In ⇒ Chapter 6.1 "Erkennung von Lastfehlern"
Inhibit by inhibit input	A firing pulse inhibit has been triggered via a potential-free contact. No power from the power controller.	⇒ Chapter 3.3 "Anschlussplan" Open contact between terminal 7 and 8 at screw terminal X_2.
Inhibit by ext. inhibit	The firing pulse inhibit has been triggered via an interface.	⇒ Interface manual "Ext. inhibit"
Soft start phase	This display appears until the soft start period has elapsed.	⇒ Chapter 5.1.2 "Steller" -> Softstartdauer
Wire break Current input	Input current for the set measuring range outside the valid range.	<ul style="list-style-type: none"> - Check wiring for wire breaks and reverse polarity. - Check upstream devices (controllers)
Wire break Voltage input	Input current for the set measuring range outside the valid range.	<ul style="list-style-type: none"> - Check wiring for wire breaks and reverse polarity. - Check upstream devices (controllers)
Malfunction Bus error	No connection to Modbus, Profibus, or EtherCAT network	Check wiring and master device (PLC).

8 Error messages and alarms

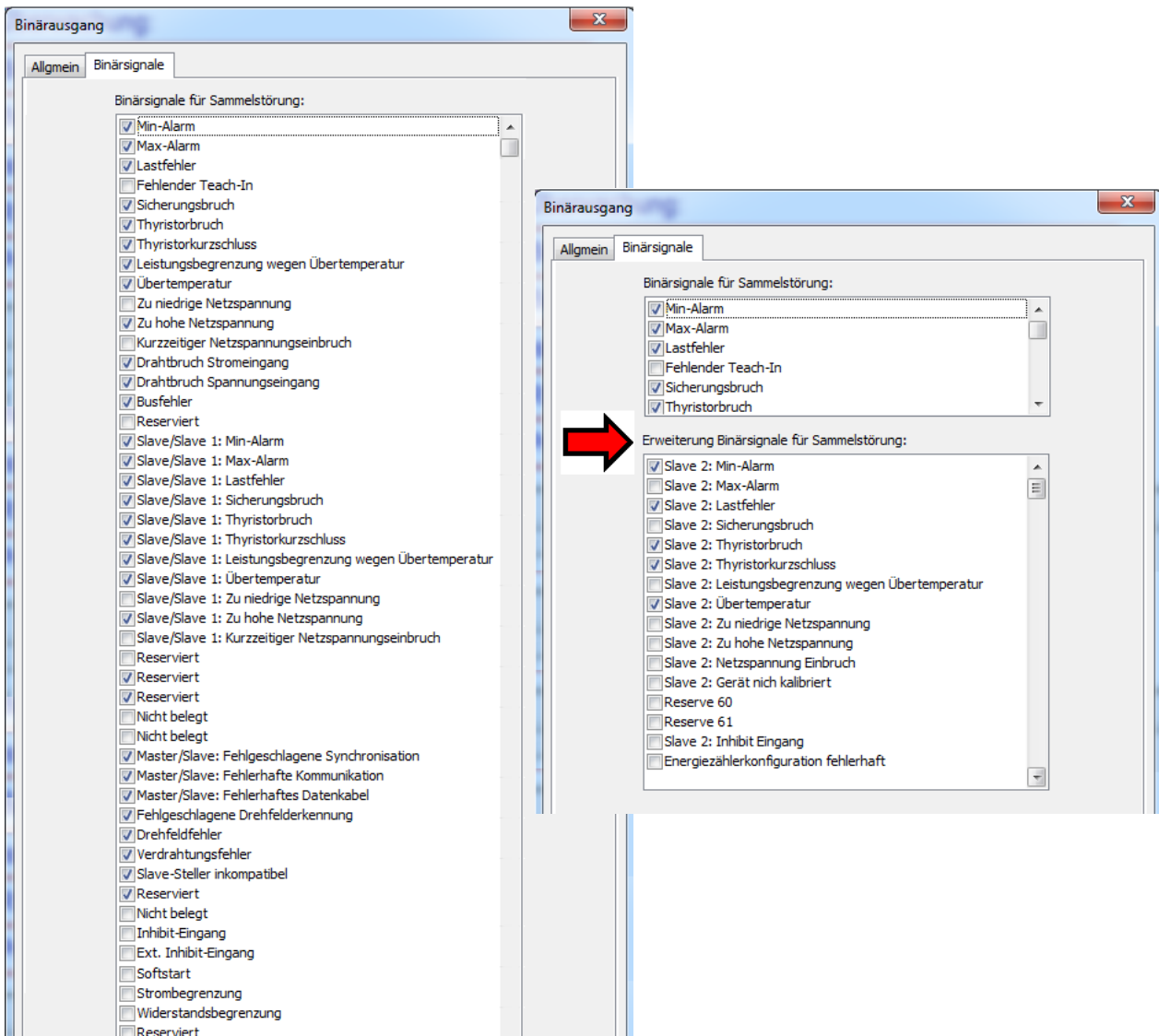
8.1 Binary signal for collective fault

This signal is used for controlling the digital output and LED K1, and can also be read out from the power controller via the interfaces.

You can use the setup program to configure which events (alarm and error messages) are to be grouped together as a binary signal for a collective fault.

TYA 200 series

This selection contains all events used in the TYA 200 series. Some events, such as "Slave 2 load error" are not relevant for the TYA S202 devices because they are not used.



All fault messages are OR-linked and output as a binary signal for a collective fault on the relay output. In addition, LED K1 lights up yellow.

This alarm can switch a relay at the binary output.

⇒ Chapter 5.1.7 "Binärausgang"

8 Error messages and alarms

8.2 Replacing a defective semiconductor fuse

Opening the housing



Caution! Risk of burns!

The device's heat sink can heat up during operation.

The current device temperature is shown on the display.

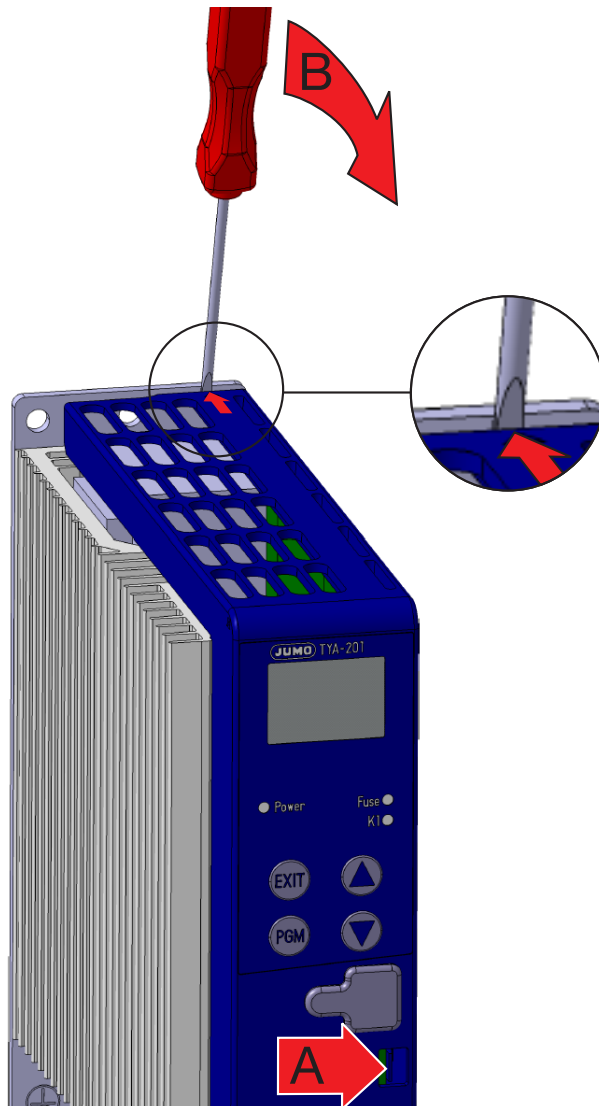
⇒ Operating overview (on the first cover page)

* Disconnect the built-in device from the voltage supply on all poles

⇒ Chapter 3.3 "Anschlussplan"

* Check that the device is isolated (green Power LED must not be lit)

* Press spring clip (A) to the right and lever up the plastic housing (at the point marked with an arrow) using a screwdriver (B).



A plug connection separates the display, keys, and interface from the power section and you will be able to see the semiconductor fuse.

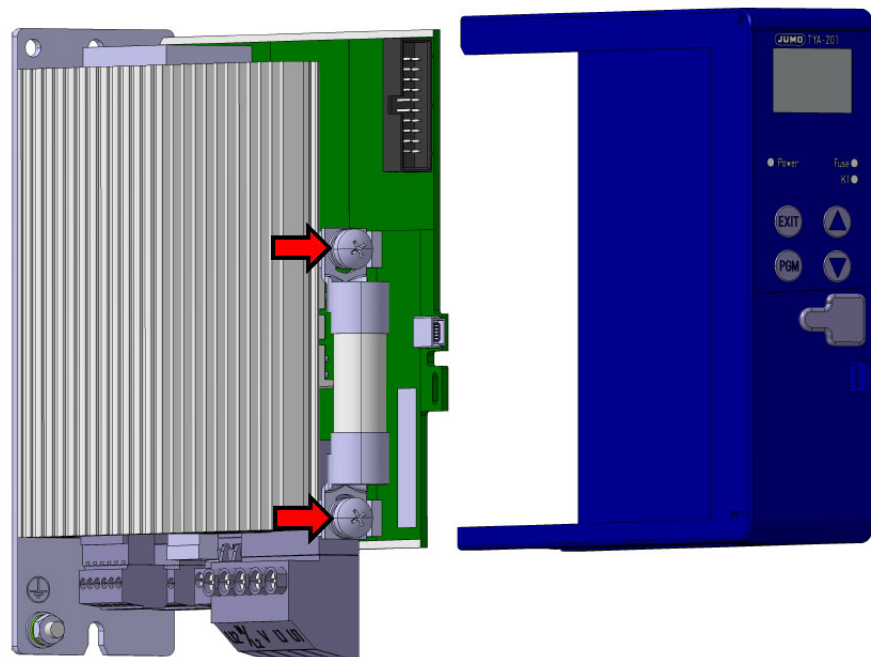
8 Error messages and alarms

8.2.1 Accessories: semiconductor fuses

The design of the semiconductor fuse differs according to the device type.

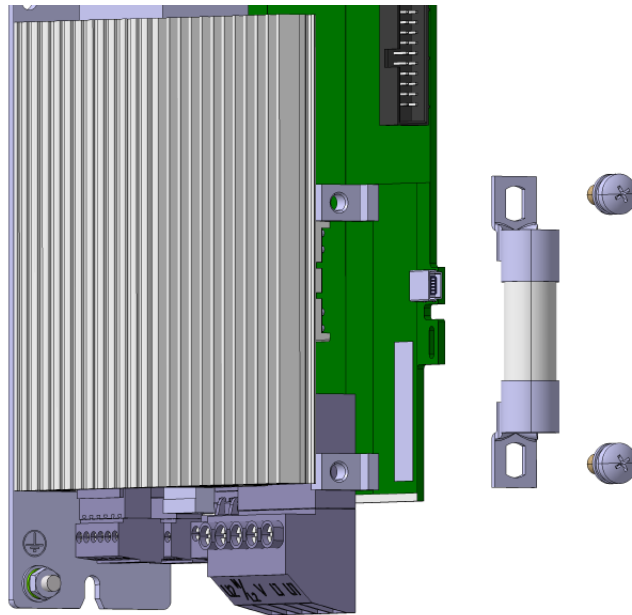
Power controller type	Tripping current	current:	Screws	Tightening torque	Sales no.
20 A	Tripping 40 A		Recessed head	3 Nm	70/00513108
32 A	Tripping 80 A		Recessed head	5 Nm	70/00068011
50 A	Tripping 80 A		Recessed head	5 Nm	70/00068011
100 A	Tripping 160 A		Hex-headed, wrench size 10 mm	5 Nm	70/00081801
150 A	Tripping 350 A		Hex-headed, wrench size 13 mm	12 Nm	70/00083318
200 A	Tripping 550 A		Hex-headed, wrench size 13 mm	12 Nm	70/00371964
250 A	Tripping 550 A		Hex-headed, wrench size 13 mm	12 Nm	70/00371964

8.2.2 Semiconductor fuses type 709066/X-0X-20...



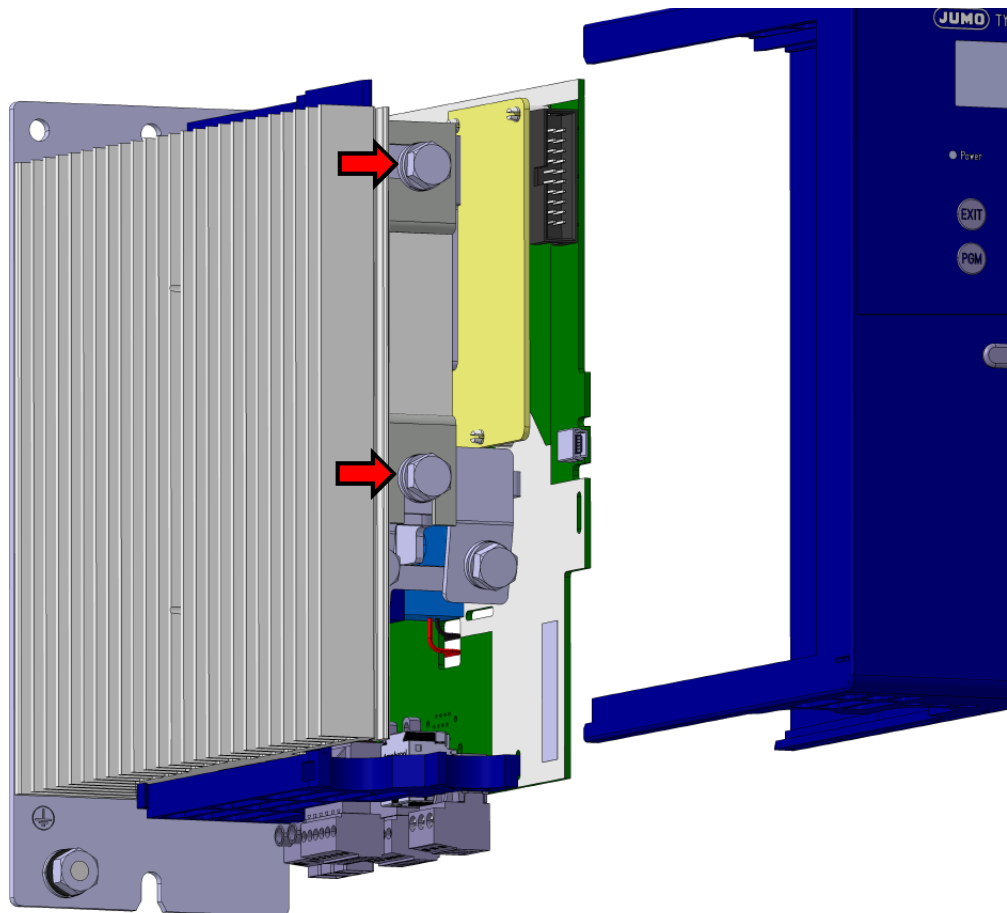
8 Error messages and alarms

- * Undo 2 recessed head screws



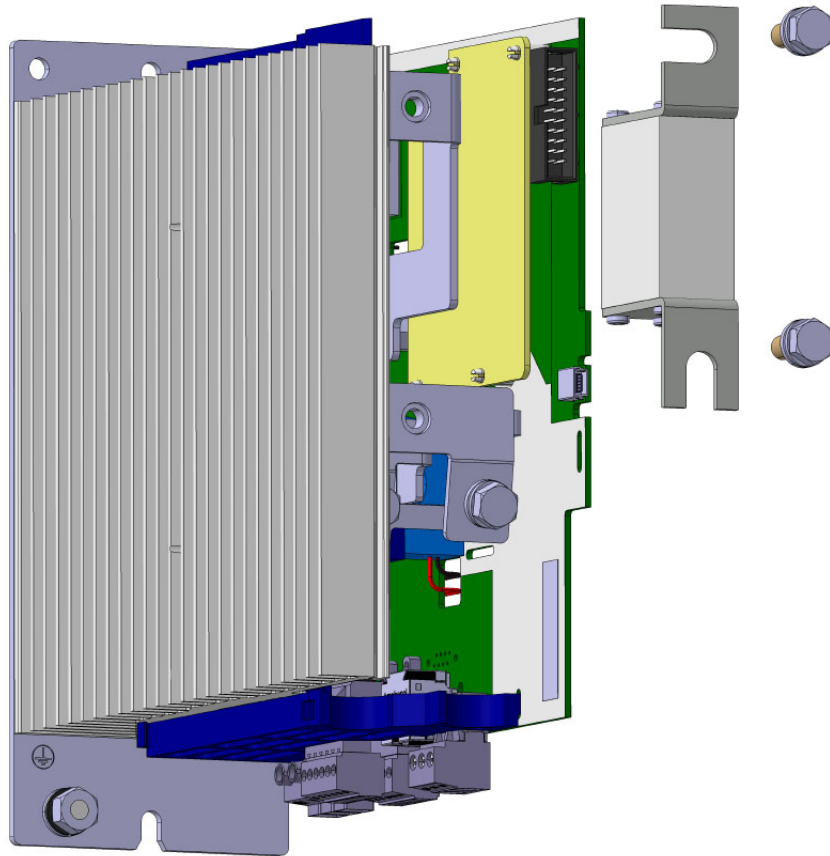
- * Replace the defective semiconductor fuse with a new one.
- * Tighten the screws with the specified tightening torque

8.2.3 Semiconductor fuses type 709066/X-0X-32...



8 Error messages and alarms

- * Undo 2 hex-headed screws



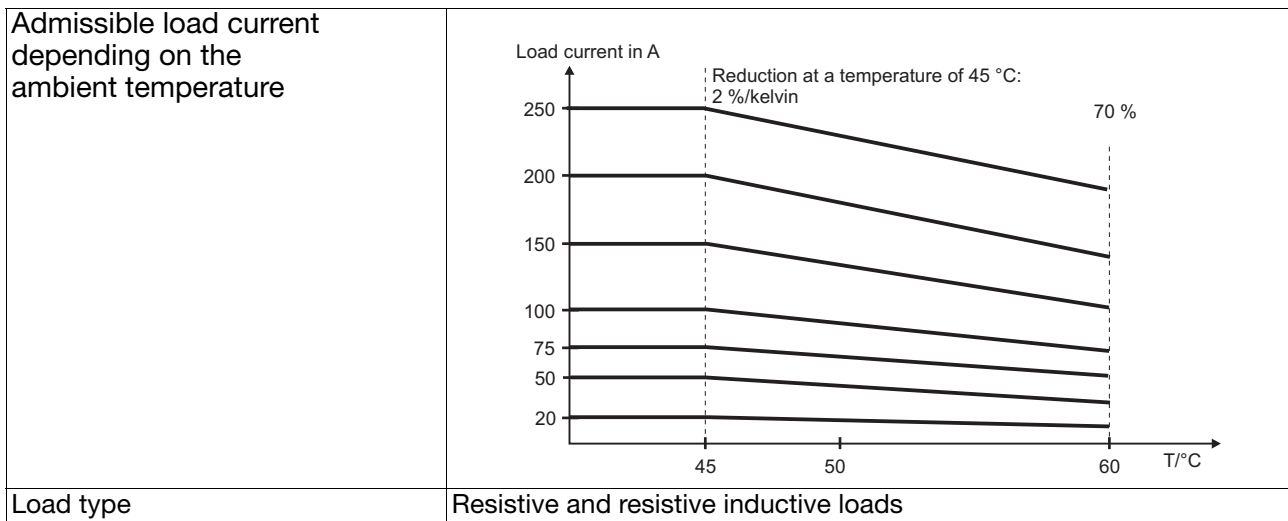
- * Replace the defective semiconductor fuse with a new one.
 - * Tighten the screws with the specified tightening torque
- Reassembling the housing**
- * Push the plastic housing back into the guide rails until the spring clip engages.

What is happening?	Cause / remedy	Info
Green Power LED is flashing	<ul style="list-style-type: none"> - Display switch-off active * Press any key 	⇒ Chapter 5.1.1 "Gerätedaten"
Power controller is not producing any output power even though the green Power LED is lit and a setpoint value has been set.	<ul style="list-style-type: none"> - Parameters have been changed in the configuration level but not completed. * Leave the configuration level by pressing EXIT and wait for a restart. 	-
	<ul style="list-style-type: none"> - Wire break at the analog input or incorrect analog input wiring 	⇒ Chapter 3.3 "Anschlussplan"
	<ul style="list-style-type: none"> - Setpoint value configuration incorrectly configured, e.g. set via interface. 	⇒ Chapter 5.1.4 "Sollwertkonfiguration"
	<ul style="list-style-type: none"> - Input for firing pulse inhibit active <p>A padlock symbol is shown as the operating mode in the info line.</p> <p>Undo connection between screw terminal 7 and 8 at terminal X2_2.</p>	⇒ Chapter 4.1.2 "Darstellung von Messwerten"
	<ul style="list-style-type: none"> - Load break * Check load and load connections 	⇒ Chapter 8 "Fehlermeldungen und Alarme"
Fuse LED is lit	<ul style="list-style-type: none"> - Semiconductor fuse defective due to short circuit in power section * Remedy short circuit in the load or load circuit * Fit a new semiconductor fuse 	⇒ Chapter 8.2 "Defekte Halbleitersicherung austauschen"
Power controller is producing power even though no setpoint value (output level) is specified by the controller.	<ul style="list-style-type: none"> - Configuration problem: Controller output signal set to 4 to 20 mA and current set to 0 to 20 mA at analog input of power controller. * Check configuration and select same standard signals for the controller and power controller. 	⇒ Chapter 5.1.3 "Analogeingänge" ⇒ Chapter 5.1.4 "Sollwertkonfiguration"
	<ul style="list-style-type: none"> - Power controller in manual mode * Exit manual mode by pressing EXIT 	⇒ Chapter 6.2 "Handbetrieb"
	<ul style="list-style-type: none"> - Base load settings selected * Check settings for base load settings 	⇒ See "Grundlast" on page 60.
	<ul style="list-style-type: none"> - Thyristor short circuit 	⇒ Chapter 8 "Fehlermeldungen und Alarme"

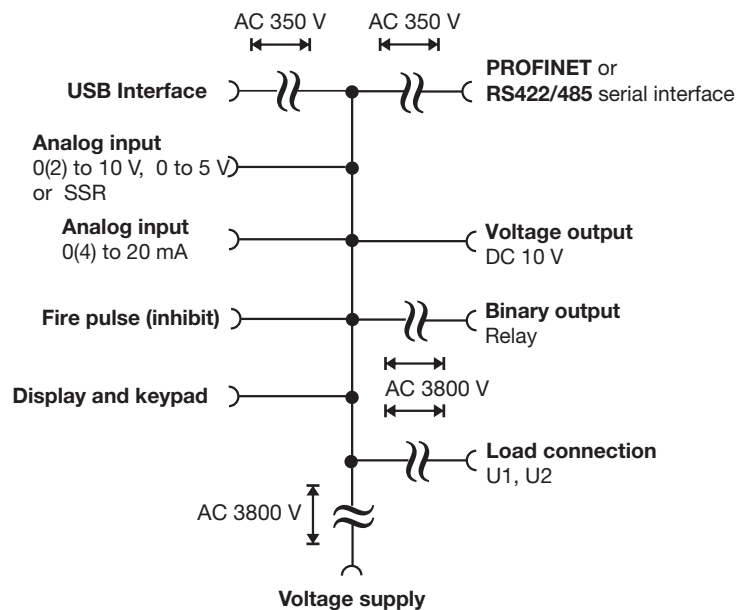
9 What to do, if ...

10.1 Voltage supply, fan specifications at 250 A, load current

Code	Voltage supply for control electronics = mains voltage	Fan specifications Type 709066/X-0X-250...
400	AC 400 V -20 % to +15 %, 48 to 63 Hz	AC 230 V/2x30 VA
460	AC 460 V -20 % to +15 %, 48 to 63 Hz	AC 230 V/2x30 VA
500	AC 500 V -20 % to +15 %, 48 to 63 Hz	AC 230 V/2x30 VA
Load current $I_{L\ rms}$	AC 20, 32, 50, 100, 150, 200, 250 A	
Load type	Resistive and resistive inductive loads	
Control section power consumption	Max. 40 VA	



10.2 Galvanic isolation



10.3 Analog inputs (master only)

10 Technical data

Current	0 (4) to 20 mA $R_i = 50 \Omega$
Voltage	0 (2) to 10 V $R_i = 25 k\Omega$
	0 (1) to 5 V $R_i = 25 k\Omega$

10.3.1 Display and measuring accuracy

All specifications refer to the power controller nominal data.

Mains voltage: $\pm 2.5 \%$ 	Load current: $\pm 1 \%$ 	Load voltage: $\pm 1 \%$ 	Analog input Voltage/current: $\pm 1 \%$
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10.4 Binary output (fault signal output master only)

Relay (changeover contact) without contact protection circuit	30,000 switching operations at a switching capacity of AC 230 V / 3 A (1.5 A), 50 Hz, B300 (UL 508)
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10.5 General specifications

Thyristor control:	Setpoint specification current input (can carry current up to 25 mA)	Setpoint specification voltage input (surge proof up to max. DC 32 V)	Via interface
Continuous	The power controller provides the power for the load continuously depending on the configured setpoint specification.		Possible
Logic (Solid state relay SSR)	The power controller acts like a switch and switches the load ON and OFF. The switching threshold is always in the middle of the configured current/voltage range At 4 to 20 mA, it is 12 mA; at 0 to 10 V, it is 5 V.		Possible

Circuit variants	- Three-phase economy circuit in master slave operation
Operating modes	- Burst-firing operation for resistive or transformer load
Load types	All resistive loads through to inductive loads are permitted. In the case of transformer loads, the nominal induction of 1.2 tesla must not be exceeded (value is 1.45 T in the case of mains overvoltage).
Special features	- Dual energy management - Soft start with pulse groups
Electrical connection	For type 709066/X -0X-020... Control and load leads are connected via screw terminals. From type 709066/X -0X-032... Control cables are connected via screw terminals and load leads via cable lugs DIN 46235 and DIN 46234 or tubular cable lugs.
Operating conditions	The power controller is designed as a built-in device according to: EN 50178, pollution degree 2, overvoltage category Ü III

10 Technical data

Electromagnetic compatibility	According to DIN 61326-1 Interference emission: Class B Interference immunity: to industrial requirements								
Protection type	All device types IP20 according to EN 60529								
Protection rating	Protection rating I, with isolated control circuitry for connection to SELV circuits								
Admissible range of ambient temperature	40 °C with forced air cooling using fan for type 709066/X-0X-250... 0 to 45 °C with natural air cooling (extended temperature range class 3K3 according to EN 60721-3-3) At higher temperatures, operation with reduced type current is possible. (from 45 °C with type current -2 %/°C) ⇒ Chapter 2.1.3 "Zulässiger Laststrom in Abhängigkeit von der Umgebungstemperatur und der Aufstellhöhe"								
Admissible storage temperature range	-30 to +70 °C (1K5 according to EN 60721-3-1)								
Altitude	≤ 2000 m above MSL Caution: At site altitudes > 1000 m above MSL, the ampacity of the power controller decreases by 0.86 % per 100 m								
Cooling	- Natural convection up to a load current of 200 A - From 250 A of load current, forced convection - At installation heights over 1000 m, the ampacity of the power controller decreases ⇒ Chapter 2.1.3 "Zulässiger Laststrom in Abhängigkeit von der Umgebungstemperatur und der Aufstellhöhe"								
Fans (only for type 709066/X-0X-250...)	Depending on the mains voltage of the power controller, the fan terminal X14 must be supplied with the voltage specified below. The lead protection must be between 2 A and a maximum of 5 A . The fan is temperature-controlled, switches on automatically when the device temperature reaches 85 °C, and remains in operation until the device temperature falls below 70 °C. <table border="1" data-bbox="523 1272 1433 1473"> <thead> <tr> <th>Mains voltage of the power controller</th> <th>Tolerances</th> <th>Fan specifications</th> </tr> </thead> <tbody> <tr> <td>Mains voltage AC 400 V</td> <td rowspan="3">-15 to +10 %, 48 to 63 Hz</td> <td rowspan="3">AC 230 V/2x30 VA</td> </tr> <tr> <td>Mains voltage AC 460 V</td> </tr> <tr> <td>Mains voltage AC 500 V</td> </tr> </tbody> </table>	Mains voltage of the power controller	Tolerances	Fan specifications	Mains voltage AC 400 V	-15 to +10 %, 48 to 63 Hz	AC 230 V/2x30 VA	Mains voltage AC 460 V	Mains voltage AC 500 V
Mains voltage of the power controller	Tolerances	Fan specifications							
Mains voltage AC 400 V	-15 to +10 %, 48 to 63 Hz	AC 230 V/2x30 VA							
Mains voltage AC 460 V									
Mains voltage AC 500 V									
Resistance to climatic conditions	Rel. humidity ≤ 85 % annual average, no condensation 3K3 according to EN 60721								
Installation position	Vertical								
Test voltage	According to EN 50178 Tab. 18								
Creepage distances	8 mm between supply current circuit and SELV circuits for type 709066/X -0X-020... 12.7 mm between supply current circuit and SELV circuits from type 709066/X -0X-032... SELV = Separate Extra Low Voltage (safe low voltage)								
Housing	Plastic, flammability class UL94 V0, color: cobalt blue RAL 5013								
Power loss	The power loss can be calculated using the following empirical formula: $P_v = 2x (20 W + 1.3 V \times I_{Load} A)$								

10 Technical data

Maximum temperature of the heat sink	110 °C
Weight	Load current 20 A approx. 2.2 kg Load current 32 A approx. 4.2 kg Load current 50 A approx. 5.4 kg Load current 100 A approx. 7.6 kg Load current 150 A approx. 17 kg Load current 200 A approx. 19 kg Load current 250 A approx. 20.4 kg
Standard accessories	1 operating manual

10.6 Approvals/approval marks

Approval mark	Testing agency	Certificates/ Certification numbers	Inspection basis	Valid for type
UL	Underwriters Laboratories	E223137	UL 508 (Category NRNT), pollution degree 2 C22.2 NO. 14-10 Industrial Control Equipment (Category NRNT7)	709066/X-XX-020-... Load current 20 A
			UL 508 (Category NRNT) C22.2 NO. 14-10 Industrial Control Equipment (Category NRNT7)	709066/X-XX-032... 709066/X-XX-050... 709066/X-XX-100... 709066/X-XX-150... 709066/X-XX-200... 709066/X-XX-250... Load current 32 to 250 A
EAC	Новая волна	EAЭС N RU Д-DE.MH06,В.021 04/20	TP TC 004/2011 TP TC 020/2011	all types

Lead protection for the control electronics	2 A up to max. 5 A, conductor cross section maximum AWG 20-12
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10 Technical data



JUMO GmbH & Co. KG

Street address:
Moritz-Juchheim-Straße 1
36039 Fulda, Germany
Delivery address:
Mackenrodtstraße 14
36039 Fulda, Germany
Postal address:
36035 Fulda, Germany
Phone: +49 661 6003-0
Fax: +49 661 6003-607
Email: mail@jumo.net
Internet: www.jumo.net

JUMO Instrument Co. Ltd.

JUMO House
Temple Bank, Riverway
Harlow, Essex, CM20 2DY, UK
Phone: +44 1279 63 55 33
Fax: +44 1279 62 50 29
Email: sales@jumo.co.uk
Internet: www.jumo.co.uk

JUMO Process Control, Inc.

6733 Myers Road
East Syracuse, NY 13057, USA
Phone: +1 315 437 5866
Fax: +1 315 437 5860
Email: info.us@jumo.net
Internet: www.jumousa.com

