

# Operating Instructions

Radar sensor for continuous level measurement

## VEGAPULS 31

Two-wire: 4 ... 20 mA/HART



Document ID: 57820



# VEGA

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# 1 About this document

## 1.1 Function

This instruction provides all the information you need for mounting, connection and setup as well as important instructions for maintenance, fault rectification, safety and the exchange of parts. Please read this information before putting the instrument into operation and keep this manual accessible in the immediate vicinity of the device.

## 1.2 Target group

This instruction manual is directed to trained personnel. The contents of this manual must be made available to the qualified personnel and implemented.

## 1.3 Symbols used



### Document ID

This symbol on the front page of this instruction refers to the Document ID. By entering the Document ID on [www.vega.com](http://www.vega.com) you will reach the document download.



**Information, note, tip:** This symbol indicates helpful additional information and tips for successful work.



**Note:** This symbol indicates notes to prevent failures, malfunctions, damage to devices or plants.



**Caution:** Non-observance of the information marked with this symbol may result in personal injury.



**Warning:** Non-observance of the information marked with this symbol may result in serious or fatal personal injury.



**Danger:** Non-observance of the information marked with this symbol results in serious or fatal personal injury.



### Ex applications

This symbol indicates special instructions for Ex applications.



#### List

The dot set in front indicates a list with no implied sequence.



#### Sequence of actions

Numbers set in front indicate successive steps in a procedure.



### Disposal

This symbol indicates special instructions for disposal.

## 2 For your safety

### 2.1 Authorised personnel

All operations described in this documentation must be carried out only by trained and authorized personnel.

During work on and with the device, the required personal protective equipment must always be worn.

### 2.2 Intended use

VEGAPULS 31 is a sensor for continuous level measurement.

You can find detailed information about the area of application in chapter "*Product description*".

Operational reliability is ensured only if the instrument is properly used according to the specifications in this document as well as possible supplementary instructions.

### 2.3 Warning about incorrect use

Inappropriate or incorrect use of this product can give rise to application-specific hazards, e.g. vessel overflow through incorrect mounting or adjustment. Damage to property and persons or environmental contamination can result. Also, the protective characteristics of the instrument can be impaired.

### 2.4 General safety instructions

This is a state-of-the-art instrument complying with all prevailing regulations and directives. The instrument must only be operated in a technically flawless and reliable condition. The operating company is responsible for the trouble-free operation of the instrument. When measuring aggressive or corrosive media that can cause a dangerous situation if the instrument malfunctions, the operating company has to implement suitable measures to make sure the instrument is functioning properly.

The safety instructions in this instructions manual, the national installation standards as well as the valid safety regulations and accident prevention rules must be observed.

For safety and warranty reasons, any invasive work on the device beyond that described in this instructions manual may be carried out only by personnel authorised by us. Arbitrary conversions or modifications are explicitly forbidden. For safety reasons, only the accessory specified by us must be used.

To avoid any danger, the safety approval markings and safety tips on the device must also be observed.

The low transmitting power of the radar sensor is far below the internationally approved limits. No health impairments are to be expected with intended use. The band range of the measuring frequency can be found in chapter "*Technical data*".

## 2.5 Mode of operation - Radar signal

Country or region specific settings for the radar signals are determined via the mode. The operating mode must be set in the operating menu via the respective operating tool at the beginning of the setup.



### **Caution:**

Operating the device without selecting the relevant mode constitutes a violation of the regulations of the radio approvals of the respective country or region.

## 2.6 Installation and operation in the USA and Canada

This information is only valid for USA and Canada. Hence the following text is only available in the English language.

Installations in the US shall comply with the relevant requirements of the National Electrical Code (NEC - NFPA 70) (USA).

Installations in Canada shall comply with the relevant requirements of the Canadian Electrical Code (CEC Part I) (Canada).

### 3 Product description

#### 3.1 Configuration

##### Scope of delivery

The scope of delivery encompasses:

- Radar sensor
- Information sheet "*Documents and software*" with:
  - Instrument serial number
  - QR code with link for direct scanning
- Information sheet "*PINs and Codes*" (with Bluetooth versions) with:
  - Bluetooth access code
- Information sheet "*Access protection*" (with Bluetooth versions) with:
  - Bluetooth access code
  - Emergency Bluetooth unlock code
  - Emergency device code

The further scope of delivery encompasses:

- Documentation
  - Ex-specific "*Safety instructions*" (with Ex versions)
  - Radio licenses
  - If necessary, further certificates



##### Information:

Optional instrument features are also described in this instructions. The respective scope of delivery results from the order specification.

##### Constituent parts

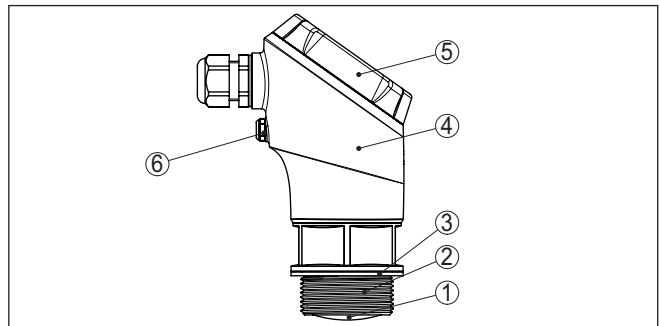


Fig. 1: Components of VEGAPULS 31

- 1 Radar antenna
- 2 Process fitting
- 3 Process seal
- 4 Electronics housing
- 5 Display and adjustment unit
- 6 Ventilation/pressure compensation

##### Type label

The type label contains the most important data for identification and use of the instrument:

- Instrument type
- Information about approvals
- Configuration information
- Technical data
- Serial number of the instrument
- QR code for device identification
- Numerical code for Bluetooth access (optional)
- Manufacturer information

**Documents and software** To find order data, documents or software related to your device, you have the following options:

- Move to "[www.vega.com](http://www.vega.com)" and enter in the search field the serial number of your instrument.
- Scan the QR code on the type label.
- Open the VEGA Tools app and enter the serial number under "**Documentation**".

### 3.2 Principle of operation

#### Application area

VEGAPULS 31 is a radar sensor for non-contact, continuous level measurement. It is suitable for liquids and solids in practically all industries.

#### Functional principle

The instrument emits a frequency-modulated continuous radar signal (FMCW) through its antenna. The emitted signal is reflected by the medium and received by the antenna as an echo with modified frequency. The frequency change is proportional to the distance and is converted into the level.

### 3.3 Adjustment

#### Local adjustment

On-site adjustment of the device is carried out via the integrated display and adjustment unit.



#### Note:

The housing with display and adjustment unit can be rotated 330° for optimum readability and operability without tools.

#### Wireless adjustment

Devices with integrated Bluetooth module can be adjusted wirelessly via standard adjustment tools:

- Smartphone/tablet (iOS or Android operating system)
- PC/notebook (Windows operating system)

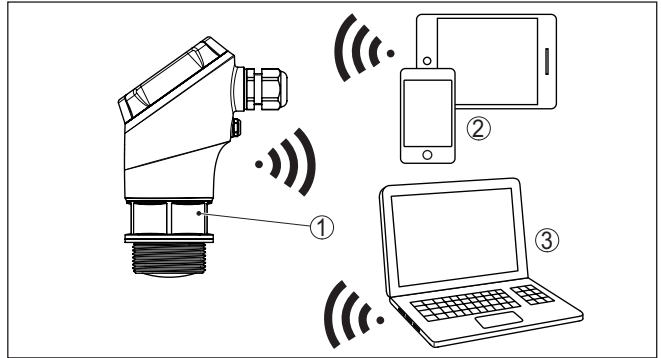


Fig. 2: Wireless connection to standard operating devices with integrated Bluetooth LE

- 1 Sensor
- 2 Smartphone/Tablet
- 3 PC/Notebook

**Adjustment via the signal cable**

Devices with signal output 4 ... 20 mA/HART can also be operated via a signal cable. This is done via an interface adapter and a PC/notebook using DTM/PACTware.

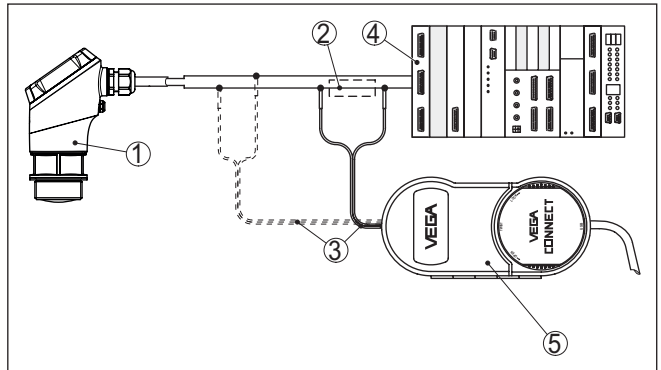


Fig. 3: Connecting the PC to the signal cable

- 1 Sensor
- 2 HART resistance 250 Ω (optional depending on evaluation)
- 3 Connection cable with 2 mm pins and terminals
- 4 Voltage supply
- 5 Interface adapter VEGACONNECT

**3.4 Packaging, transport and storage**

Your instrument was protected by packaging during transport. Its capacity to handle normal loads during transport is assured by a test based on ISO 4180.

The packaging consists of environment-friendly, recyclable cardboard. For special versions, PE foam or PE foil is also used. Dispose of the packaging material via specialised recycling companies.

**Transport**

Transport must be carried out in due consideration of the notes on the transport packaging. Nonobservance of these instructions can cause damage to the device.

**Transport inspection**

The delivery must be checked for completeness and possible transit damage immediately at receipt. Ascertained transit damage or concealed defects must be appropriately dealt with.

**Storage**

Up to the time of installation, the packages must be left closed and stored according to the orientation and storage markings on the outside.

Unless otherwise indicated, the packages must be stored only under the following conditions:

- Not in the open
- Dry and dust free
- Not exposed to corrosive media
- Protected against solar radiation
- Avoiding mechanical shock and vibration

**Storage and transport temperature**

- Storage and transport temperature see chapter "*Technical data - Ambient conditions*"
- Relative moisture 20 ... 85 %

**3.5 Accessories**

The instructions for the listed accessories can be found in the download area on our homepage.

**Flanges**

Screwed flanges are available in different versions according to the following standards: DIN 2501, EN 1092-1, BS 10, ASME B 16.5, JIS B 2210-1984, GOST 12821-80.

**Welded socket, threaded and hygienic adapter**

Welded sockets are used to connect the devices to the process.

Threaded and hygienic adapters enable simple adaptation of devices with standard threaded fittings to process-side hygiene connections.

**Mounting strap**

The mounting accessories are used for stable mounting of the device at the measuring point. The parts are available in various versions and sizes.

## 4 Mounting

### 4.1 General instructions

#### Ambient conditions

The instrument is suitable for standard and extended ambient conditions acc. to DIN/EN/BS EN/IEC/ANSI/ISA/UL/CSA 61010-1. It can be used indoors as well as outdoors.

#### Process conditions



##### Note:

For safety reasons, the instrument must only be operated within the permissible process conditions. You can find detailed information on the process conditions in chapter "Technical data" of the operating instructions or on the type label.

Hence make sure before mounting that all parts of the instrument exposed to the process are suitable for the existing process conditions.

These are mainly:

- Active measuring component
- Process fitting
- Process seal

Process conditions in particular are:

- Process pressure
- Process temperature
- Chemical properties of the medium
- Abrasion and mechanical influences

#### Permissible process pressure (MWP) - Device

The permissible process pressure range is specified on the type label with "MWP" (Maximum Working Pressure). The MWP takes into account the component with the lowest pressure and may be applied permanently. This specification refers to a reference temperature of +20 °C (+68 °F).

In addition, a temperature derating of the process fitting, e. g. with flanges, can limit the permissible process pressure range according to the respective standard.



##### Note:

To prevent damage to the device, a test pressure may only briefly exceed the specified MWP by 1.5 times at reference temperature.

#### Permissible process pressure (MWP) - Mounting accessory

The permissible process pressure range is stated on the type label. The instrument should only be operated with these pressures if the mounting accessory used also fulfils these values. This should be ensured by suitable flanges, welded sockets, tension rings with Clamp connections, sealings, etc.

#### Protection against moisture

Protect your instrument against moisture ingress through the following measures:

- Use a suitable connection cable (see chapter "Connecting to power supply")
- Tighten the cable gland or plug connector

- Lead the connection cable downward in front of the cable entry or plug connector

This applies mainly to outdoor installations, in areas where high humidity is expected (e.g. through cleaning processes) and on cooled or heated vessels.



**Note:**

Make sure that during installation or maintenance no moisture or dirt can get inside the instrument.

To maintain the housing protection, make sure that the housing lid is closed during operation and locked, if necessary.

## 4.2 Mounting instructions

### Polarisation

Radar sensors for level measurement emit electromagnetic waves. The polarization is the direction of the electrical component of these waves.

The polarization direction is marked on the housing, see following drawing:

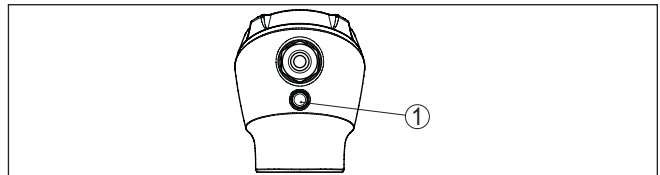


Fig. 4: Position of the polarisation

1 Marking of the polarisation



**Note:**

When the housing is rotated, the direction of polarization changes and hence the influence of the false echo on the measured value. Please keep this in mind when mounting or making changes later.

### Reference plane

The centre of the antenna lens is the beginning of the measuring range and at the same time the reference plane for the min./max. adjustment, see following diagram:

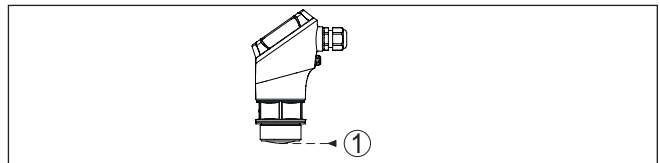


Fig. 5: Reference plane

1 Reference plane

### Installation position

When mounting the device, keep a distance of at least 200 mm (7.874 in) from the vessel wall. If the device is installed in the center of dished or round vessel tops, multiple echoes can arise. However,

these can be suppressed by an appropriate adjustment (see chapter "Set up").

If you cannot maintain this distance, you should carry out a false signal suppression during setup. This applies particularly if buildup on the vessel wall is expected. In such cases, we recommend repeating the false signal suppression at a later date with existing buildup.

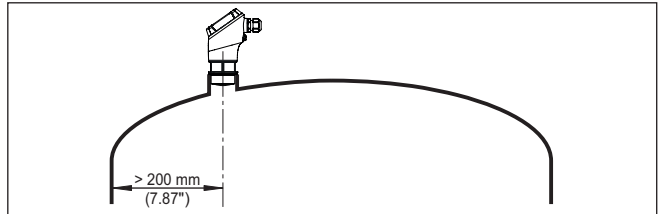


Fig. 6: Mounting of the radar sensor on round vessel tops

In vessels with conical bottom it can be advantageous to mount the device in the centre of the vessel, as measurement is then possible down to the bottom.

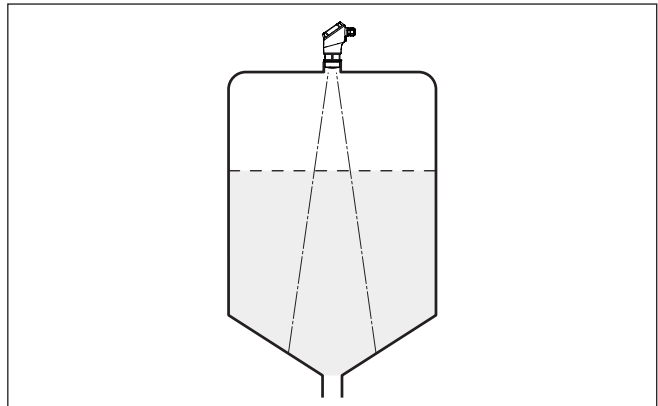


Fig. 7: Mounting of the radar sensor on vessels with conical bottom

**Inflowing medium**

Do not mount the instruments in or above the filling stream. Make sure that you detect the medium surface, not the inflowing product.

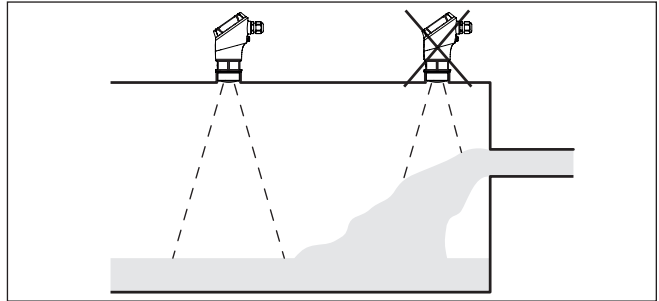


Fig. 8: Mounting of the radar sensor with inflowing medium

### Threaded socket and socket piece

With threaded connection, the antenna end should protrude at least 5 mm (0.2 in) out of the nozzle.

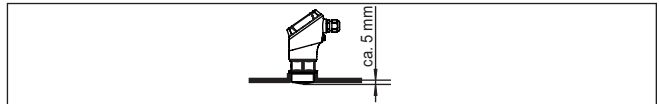


Fig. 9: Thread mounting

If the reflective properties of the medium are good, you can mount VEGAPULS 31 on sockets longer than the antenna. The socket end should be smooth and burr-free, if possible also rounded.

You will find recommended values for socket heights in the following illustration or the table. The values come from typical applications. Deviating from the proposed dimensions, also longer sockets are possible, however the local conditions must be taken into account.

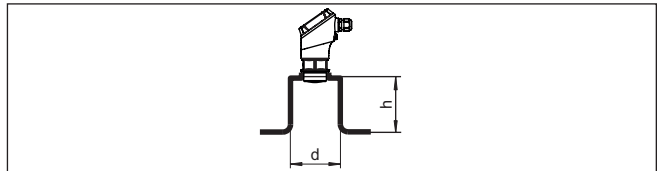


Fig. 10: Socket mounting

Socket diameter d		Socket length h	
40 mm	1½"	≤ 150 mm	≤ 5.9 in
50 mm	2"	≤ 200 mm	≤ 7.9 in
80 mm	3"	≤ 300 mm	≤ 11.8 in
100 mm	4"	≤ 400 mm	≤ 15.8 in
150 mm	6"	≤ 600 mm	≤ 23.6 in



#### Note:

When mounting on longer nozzles, we recommend carrying out a false signal suppression (see chapter "Parameter adjustment").

**Vessel installations**

The mounting location of the radar sensor should be a place where no other equipment or fixtures cross the path of the radar signals.

Vessel installations, such as e.g. ladders, limit switches, heating spirals, struts, etc., can cause false echoes and impair the useful echo. Make sure when planning your measuring point that the radar sensor has a "clear view" to the measured product.

In case of existing vessel installations, a false signal suppression should be carried out during setup.

If large vessel installations such as struts or supports cause false echoes, these can be attenuated through supplementary measures. Small, inclined sheet metal baffles above the installations "scatter" the radar signals and prevent direct interfering reflections.

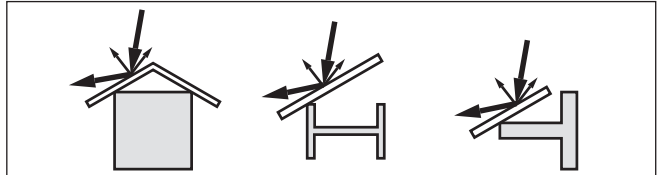


Fig. 11: Cover flat, large-area profiles with deflectors

**Alignment - Liquids**

In liquids, direct the device as perpendicular as possible to the medium surface to achieve optimum measurement results.

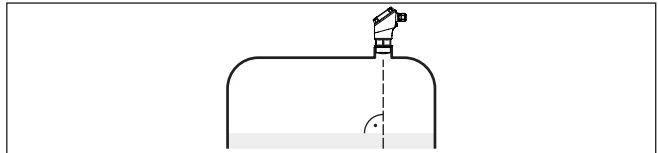


Fig. 12: Alignment in liquids

**Orientation - Bulk solids**

In order to measure as much of the vessel volume as possible, the device should be aligned so that the radar signal reaches the lowest level in the vessel. In a cylindrical silo with conical outlet, the sensor is mounted anywhere from one third to one half of the vessel radius from the outside wall (see following drawing).

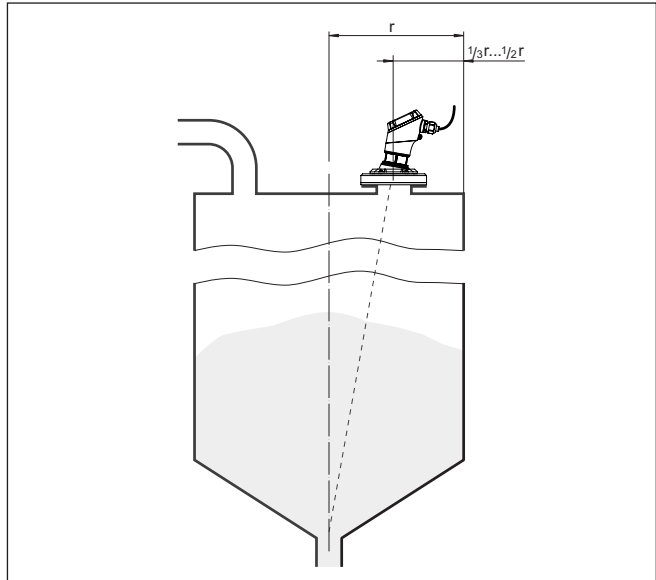


Fig. 13: Mounting position and orientation

### Orientation

Due to respective socket design or with an alignment device, the device can be easily aligned to the vessel centre. The necessary angle of inclination depends on the vessel dimensions. It can be easily checked with a suitable bubble tube or mechanic's level on the sensor.

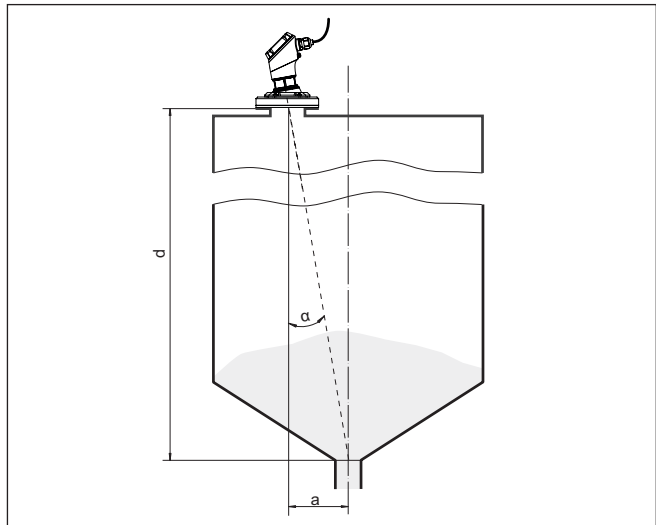


Fig. 14: Proposal for installation after orientation VEGAPULS 31

The following table shows the necessary angle of inclination. It depends on the measuring distance and the distance "a" between vessel centre and installation position.

Distance d (m)	2°	4°	6°	8°	10°
2	0.1	0.1	0.2	0.3	0.4
4	0.1	0.3	0.4	0.6	0.7
6	0.2	0.4	0.6	0.8	1.1
8	0.3	0.6	0.8	1.1	1.4
10	0.3	0.7	1.1	1.4	1.8
15	0.5	1	1.6	2.1	2.6
20	0.7	1.4	2.1	2.8	3.5

**Example:**

In a vessel with 20 m height, the installation position of the sensor is 1.4 m away from the vessel center.

The necessary angle of inclination of 4° can be read out from this table.

**Agitators**

If there are agitators in the vessel, a false signal suppression should be carried out with the agitators in motion. This ensures that the interfering reflections from the agitators are saved with the blades in different positions.

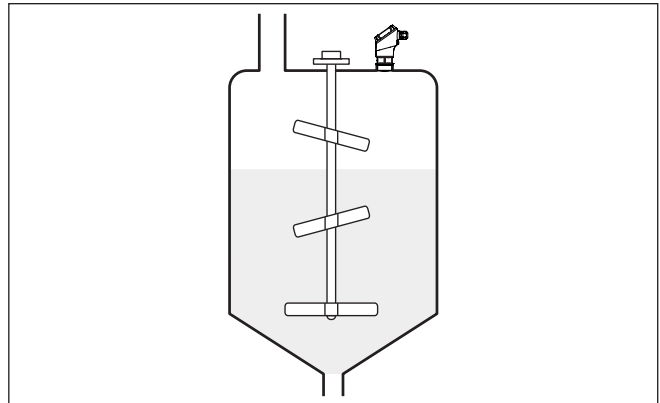


Fig. 15: Agitators

**Foam generation**

Through the action of filling, stirring and other processes in the vessel, compact foams which considerably damp the emitted signals may form on the medium surface.



**Note:**

If foams lead to measurement errors, you should use the biggest possible radar antennas or as an alternative, sensors with guided radar.

**Mounting****4.3 Measurement setup - Flow**

In general, the following must be observed while mounting the device:

- Mounting the sensor on the upstream or inlet side
- Installation in the centre of the flume and vertical to the liquid surface
- Distance to the overfall orifice or Venturi flume
- Distance to the max. height of the orifice or flume for optimum accuracy: > 250 mm (9.843 in)<sup>1)</sup>
- Requirements from approvals for flow measurement, e.g. MCERTS

**Flume****Predefined curves:**

A flow measurement with these standard curves is very easy to set up, as no dimensional information of the flume is required.

- Palmer-Bowlus flume ( $Q = k \times h^{1.86}$ )
- Venturi, trapezoidal weir, rectangular flume ( $Q = k \times h^{1.5}$ )
- V-Notch, triangular overfall ( $Q = k \times h^{2.5}$ )

**Channel with dimensions according to ISO standard:**

When selecting these curves, the dimensions of the flume must be known and entered via the assistant. As a result, the accuracy of the flow measurement is higher than with the specified curves.

- Rectangular flume (ISO 4359)
- Trapezoidal flume (ISO 4359)
- U-shaped flume (ISO 4359)
- Triangular overfall thin-walled (ISO 1438)
- Rectangular flume thin-walled (ISO 1438)
- Rectangular weir broad crown (ISO 3846)

**Flow formula:**

If the flow formula of your flume is known, you should select this option, as the accuracy of the flow measurement is highest here.

- Flow formula:  $Q = k \times h^{\text{exp}}$

**Manufacturer definition:**

If you use a Parshall flume from the manufacturer ISCO, this option must be selected. This gives you a high accuracy of flow measurement with easy configuration.

Alternatively, you can also take over Q/h table values provided by the manufacturer here.

- ISCO Parshall flume
- Q/h table (assignment of height with corresponding flow in a table)

**Tip:**

Detailed project planning data can be found at the channel manufacturers and in the technical literature.

The following examples serve as an overview for flow measurement.

<sup>1)</sup> The value given takes into account the block distance. At smaller distances, the measuring accuracy is reduced, see "Technical data".

Rectangular overflow

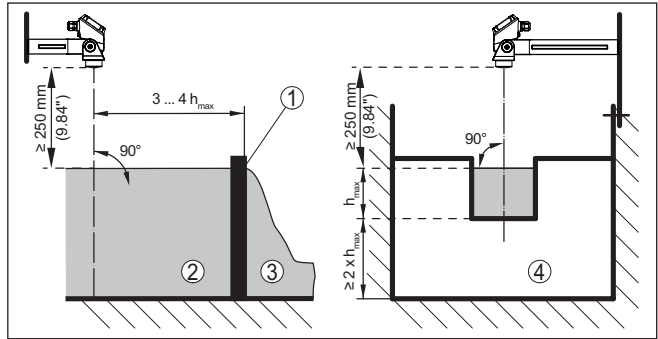


Fig. 16: Flow measurement with rectangular flume:  $h_{max}$  = max. filling of the rectangular flume

- 1 Overflow orifice (side view)
- 2 Upstream water
- 3 Tailwater
- 4 Overflow orifice (view from tailwater)

Khafagi-Venturi flume

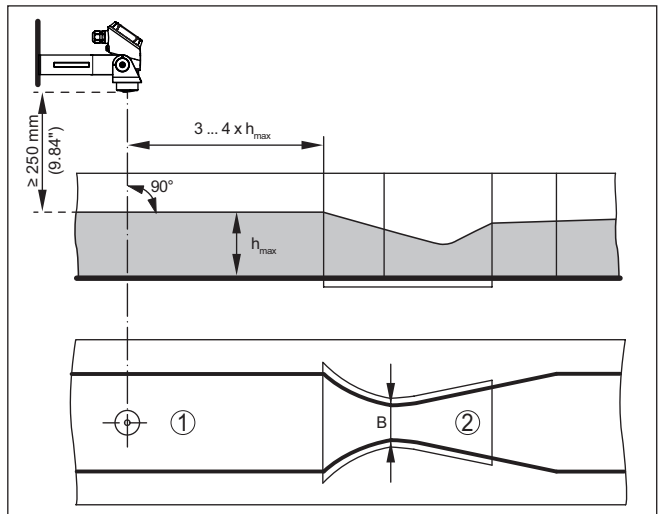


Fig. 17: Flow measurement with Khafagi-Venturi flume:  $h_{max}$  = max. filling of the flume; B = tightest constriction in the flume

- 1 Position sensor
- 2 Venturi flume

## 5 Connecting to power supply

### 5.1 Preparing the connection

#### Safety instructions

Always keep in mind the following safety instructions:

- Carry out electrical connection by trained, qualified personnel authorised by the plant operator



#### Warning:

Only connect or disconnect in de-energized state.

#### Voltage supply

The data for power supply are specified in chapter "*Technical data*".



#### Note:

Power the instrument via an energy-limited circuit (power max. 100 W) acc. to IEC 61010-1, e.g.:

- Class 2 power supply unit (acc. to UL1310)
- SELV power supply unit (safety extra-low voltage) with suitable internal or external limitation of the output current
- PELV power supply unit (protective low voltage) with suitable internal or external limitation of the output current

Keep in mind the following additional factors that influence the operating voltage:

- Lower output voltage of the power supply unit under nominal load (e.g. with a sensor current of 20.5 mA or 22 mA in case of fault signal)
- Influence of additional instruments in the circuit (see load values in chapter "*Technical data*")

#### Connection cable

Use cable with round cross section for instruments with housing and cable gland. To ensure the seal effect of the cable gland (IP protection rating), find out which cable outer diameter the cable gland is suitable for.

The instrument is connected with standard two-wire cable. If electromagnetic interference is expected which is above the test values of EN 61326-1 for industrial areas, shielded cable should be used.



#### Note:

Shielded cable generally necessary in HART multidrop mode.

#### Note:

If the temperatures are too high, the cable insulation can be damaged. Hence keep apart from the ambient temperature also the self-heating of the instrument for the temperature resistance of the cable in the connection compartment in mind.<sup>2)</sup>

<sup>2)</sup> With an ambient temperature  $\geq 50$  °C (122 °F) the connection cable should be suitable for a temperature which is at least 20 °C (36 °F) higher.

**Cable screening and grounding**

We recommend to connect the cable screening to ground potential at one end on the supply side when using shielded cable.

**Cable gland**

**Metric threads**

In the case of instrument housings with metric thread, the cable gland is screwed in at the factory. It is sealed with plastic plugs as transport protection.

You have to remove this plug before electrical connection.

**NPT thread**

In the case of instrument housings with self-sealing NPT threads, it is not possible to have the cable entry screwed in at the factory. The cable gland is therefore covered with a red dust protection cap as transport protection.



**Note:**

To ensure the protection class, you must replace this protective cap with an approved NPT cable gland before setup.



**Note:**

Do not use grease when screwing in the NPT cable gland or a conduit steel pipe.

Maximum torque see chapter "*Technical data*".

**5.2 Connecting**

**Connection technology**

The voltage supply and the signal output are connected in one of the following two ways, depending on the device version:

- Through the cable gland into the spring-loaded terminals in the housing.
- By means of a complete confectioned cable with counter plug.

The connection steps described below are not necessary when using a complete confectioned cable with counter plug.

**Connection procedure**

Proceed as follows:

1. Unscrew the housing lid
2. Remove display and adjustment unit
3. Loosen compression nut of the cable gland and remove blind plug
4. Remove approx. 10 cm (4 in) of the cable mantle, strip approx. 1 cm (0.4 in) of insulation from the ends of the individual wires
5. Insert the cable into the sensor through the cable entry



Fig. 18: Connection steps 5 and 6

6. Insert the wire ends into the terminals according to the bottom wiring plan



**Note:**

Fixed conductors and flexible conductors with ferrules can be inserted directly into the terminal openings. In the case of flexible conductors for opening the terminals, use a screwdriver (3 mm blade width) to push the actuator lever away from the terminal opening. When released, the terminals are closed again.

7. Check the hold of the wires in the terminals by lightly pulling on them
8. Tighten the compression nut of the cable entry gland. The seal ring must completely encircle the cable
9. Insert display and adjustment module
10. Screw the housing lid back on

The electrical connection is finished.

### 5.3 Wiring plan

#### Electronics and connection compartment

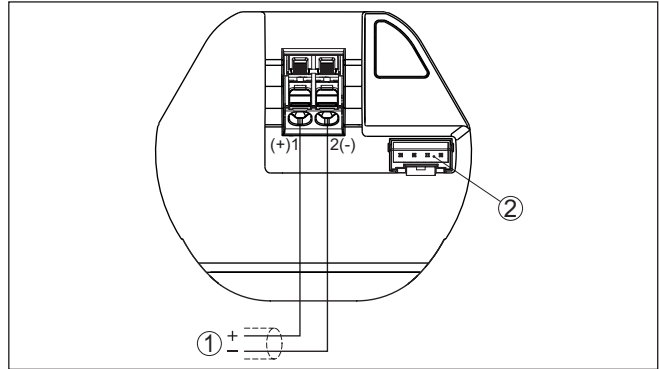


Fig. 19: Connection compartment VEGAPULS 31

- 1 Voltage supply, signal output
- 2 Plug connector for display and adjustment unit

#### Assignment of the plug connector

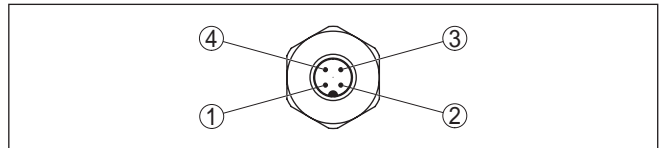


Fig. 20: Top view of the M12 x 1 plug connector

The plug connector is available in three different plug assignments.

	Assignment		
	A	B	C
1 (brown)	free	1 (+)	1 (+)
2 (white)	free	2 (-)	free
3 (blue)	2 (-)	free	2 (-)
4 (black)	1 (+)	free	free

### 5.4 Switch-on phase

After connection to the power supply, the device carries out a self-test:

- Internal check of the electronics
- Output signal is set to failure

The current measured value is then output on the signal cable.

## 6 Access protection

### 6.1 Bluetooth radio interface

Devices with a Bluetooth radio interface are protected against unwanted access from outside. This means that only authorized persons can receive measured and status values and change device settings via this interface.

#### Bluetooth access code

A Bluetooth access code is required to establish Bluetooth communication via the adjustment tool (smartphone/tablet/notebook). This code must be entered once when Bluetooth communication is established for the first time in the adjustment tool. It is then stored in the adjustment tool and does not have to be entered again.

The Bluetooth access code is individual for each device. It is printed on the device housing with Bluetooth. In addition, it is supplied with the device in the information sheet "*PINs and Codes*". In addition, the Bluetooth access code can be read out via the display and adjustment unit, depending on the device version.

The Bluetooth access code can be changed by the user after the first connection is established. If the Bluetooth access code is entered incorrectly, the new entry is only possible after a waiting period has elapsed. The waiting time increases with each further incorrect entry.

#### Emergency Bluetooth unlock code

The emergency Bluetooth access code enables Bluetooth communication to be established in the event that the Bluetooth access code is no longer known. It can't be changed. The emergency Bluetooth access code can be found in information sheet "*Access protection*". If this document is lost, the emergency Bluetooth access code can be retrieved from your personal contact person after legitimation. The storage and transmission of Bluetooth access codes is always encrypted (SHA 256 algorithm).

### 6.2 Protection of the parameterization

The settings (parameters) of the device can be protected against unwanted changes. The parameter protection is deactivated on delivery, all settings can be made.

#### Device code

To protect the parameterization, the device can be locked by the user with the aid of a freely selectable device code. The settings (parameters) can then only be read out, but not changed. The device code is also stored in the adjustment tool. However, unlike the Bluetooth access code, it must be re-entered for each unlock. When using the adjustment app or DTM, the stored device code is then suggested to the user for unlocking.

#### Emergency device code

The emergency device code allows unlocking the device in case the device code is no longer known. It can't be changed. The emergency device code can also be found on the supplied information sheet "*Access protection*". If this document is lost, the emergency device code can be retrieved from your personal contact person after legitimation.

The storage and transmission of the device codes is always encrypted (SHA 256 algorithm).

### 6.3 Storing the codes in myVEGA

If the user has a "myVEGA" account, then the Bluetooth access code as well as the device code are additionally stored in his account under "*PINs and Codes*". This greatly simplifies the use of additional adjustment tools, as all Bluetooth access and device codes are automatically synchronized when connected to the "myVEGA" account

## 7 Set up with the integrated display and adjustment unit

### 7.1 Adjustment system

#### Function

The instrument is operated via the three keys of the integrated display and adjustment unit. The respective menu items are shown on the LC display. You can find the function of the individual keys in the below overview.

Certain settings are only possible to a limited extent or not possible with the integrated display and adjustment unit. For these settings, we recommend using the adjustment app or PACTware with corresponding DTM.

#### Display and adjustment elements

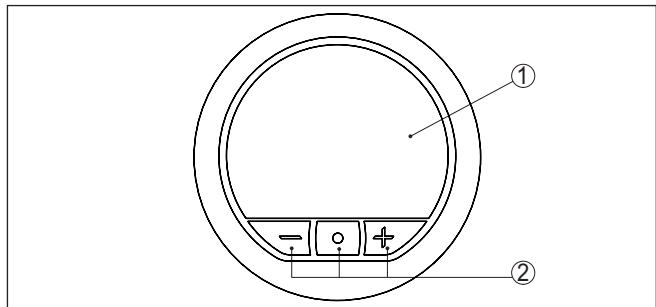


Fig. 21: Elements of the integrated display and adjustment unit

- 1 LC display
- 2 Adjustment keys

#### Key functions

Key	Function
[*]	Entry to the menu level Jump to selected menu item Edit parameter Select editing position Save value
[+]	Switching between the individual measured value windows Navigation in the menu items, forwards Change parameter values upwards
[-]	Switching between the individual measured value windows Navigation in the menu items, backwards Change parameter values downwards
[+] and [-] simultaneously	Jump to next higher menu Interrupt input

**Time functions**

When the **[+]** and **[-]** keys are pressed quickly, the edited value, or the cursor, changes one value or position at a time. If the key is pressed longer than 1 s, the value or position changes continuously.

Simultaneous pressing of the **[+]** and **[-]** keys causes a return to the measured value indication.

Approx. 60 minutes after the last pressing of a key, an automatic reset to measured value indication is triggered. Any values not confirmed with **[•]** will not be saved.

**7.2 Measured value and menu item display**

**Measured value indication**

The measured values are displayed according to the following presentation:

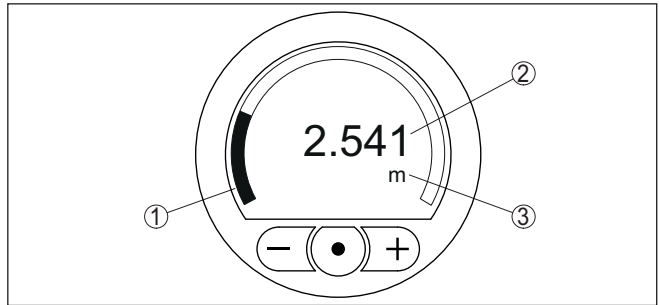


Fig. 22: Measured value display (example)

- 1 Measured value as bargraph
- 2 Digital value
- 3 Unit

**Menu item display**

The menu items are displayed according to the following presentation:

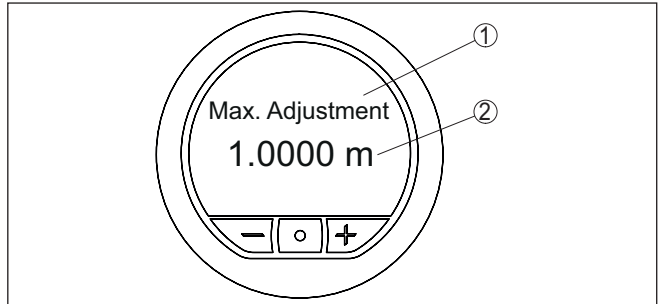


Fig. 23: Menu item display (example)

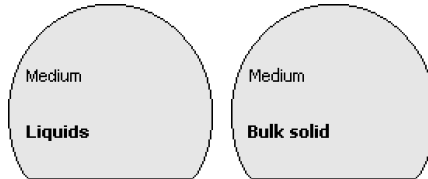
- 1 Menu item
- 2 Actual parameter value

## 7.3 Parameter adjustment

### 7.3.1 Main menu

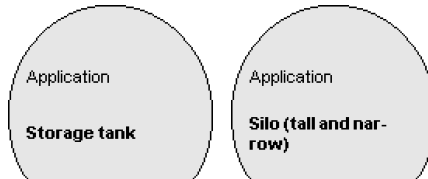
#### Medium

This menu item enables you to adapt the sensor to the different measuring conditions of the media "*Liquid*" or "*Bulk solid*". This selection adapts the signal processing to the expected reflections.



#### Application

This menu item enables you to optimally adapt the sensor to the application, the place of use and the measuring conditions. The adjustment possibilities depend on the selection made under "*Medium*", "*Liquid*" or "*Bulk solid*".



The vessels as well as the measuring and process conditions are described in the following as an overview.

#### Application - liquid

With "*Liquid*", the applications are based on the following features, to which the measuring characteristic of the sensor is adjusted in particular:

##### Storage tank

- Vessel:
  - Large volume
  - Upright cylindrical, horizontal round
- Process/measurement conditions:
  - Slow filling and emptying
  - Smooth medium surface
  - Multiple reflections from dished vessel ceiling
  - Condensation

##### Stirrer vessel

- Vessel:
  - Large agitator blades of metal
  - Installations like flow breakers, heating spirals
  - Nozzle
- Process/measurement conditions:
  - Frequent, fast to slow filling and emptying
  - Strongly agitated surface, foam and strong vortex generation
  - Multiple reflections through dished vessel ceiling

- Condensation, buildup on the sensor
- Further recommendations
  - False signal suppression when the agitator is running via the operating tool

### Dosing vessel

- Vessel:
  - Small vessels
- Process/measurement conditions:
  - Frequent and fast filling/emptying
  - Tight installation situation
  - Multiple reflections through dished vessel ceiling
  - Product buildup, condensate and foam generation

### Pumping station/Pump shaft

- Process/measurement conditions:
  - Partly strongly agitated surface
  - Installations such as pumps and ladders
  - Multiple reflections through flat vessel ceiling
  - Dirt and grease deposits on shaft wall and sensor
  - Condensation on the sensor
- Further recommendations
  - False signal suppression via the operating tool

### Overflow basin

- Vessel:
  - Large volume
  - Partly installed underground
- Process/measurement conditions:
  - Partly strongly agitated surface
  - Multiple reflections through flat vessel ceiling
  - Condensation, dirt deposits on the sensor
  - Flooding of the sensor antenna

### Vessel/Collecting basin

- Vessel:
  - Large volume
  - Upright cylindrical or rectangular
- Process/measurement conditions:
  - Slow filling and emptying
  - Smooth medium surface
  - Condensation

### Plastic tank (measurement through the vessel top)

- Process/measurement conditions:
  - Measurement through the tank top, if appropriate to the application
  - Condensation on the plastic ceiling
  - In outdoor facilities, water and snow on vessel top possible
- Further recommendations
  - When measuring through the tank ceiling, false signal suppression via the operating tool

- When measuring through the tank top in outdoor areas protective roof for the measuring point

#### Transportable plastic tank (IBC)

- Process/measurement conditions:
  - Material and thickness different
  - Measurement through the vessel top, if appropriate to the application
  - Changed reflection conditions as well as jumps in measured values when changing vessels
- Further recommendations
  - When measuring through the tank ceiling, false signal suppression via the operating tool
  - When measuring through the tank top in outdoor areas protective roof for the measuring point

#### Gauge measurement in waters

- Process/measurement conditions:
  - Slow gauge change
  - Extreme damping of output signal in case of wave generation
  - Ice and condensation on the antenna possible
  - Floating debris sporadically on the water surface

#### Flow measurement flume/Overfall

- Process/measurement conditions:
  - Slow gauge change
  - Smooth to agitated water surface
  - Measurement often from a short distance with the demand for accurate measurement results
  - Ice and condensation on the antenna possible

#### Demonstration

- Applications that are not typical level measurements, e.g. device tests
  - Instrument demonstration
  - Object recognition/monitoring
  - Fast position changes of a measuring plate during functional test

#### Application - bulk solid

With "*Bulk solid*", the applications are based on the following features, to which the measuring characteristic of the sensor is adjusted in particular:

#### Silo (slender and high)

- Process/measurement conditions:
  - Interfering reflections due to weld seams on the vessel
  - Multiple echoes/diffuse reflections due to unfavourable pouring positions with fine grain
  - Varying pouring positions due to outlet funnel and filling cone
- Further recommendations
  - False signal suppression via the operating tool
  - Alignment of the measurement to the silo outlet

**Bunker (large-volume)**

- Process/measurement conditions:
  - Large distance to the medium
  - Steep angles of repose, unfavourable pouring positions due to outlet funnel and filling cone
  - Diffuse reflections due to structured vessel walls or internals
  - Multiple echoes/diffuse reflections due to unfavourable pouring positions with fine grain
  - Changing signal conditions when large amounts of material slip off
- Further recommendations
  - False signal suppression via the operating tool

**Heap (point measurement/profile detection)**

- Process/measurement conditions:
  - Measured value jumps, e.g. through heap profile and traverses
  - Large angles of repose, varying pouring positions
  - Measurement near the filling stream
  - Sensor mounting on movable conveyor belts

**Crusher**

- Process/measurement conditions:
  - Measured value jumps and varying pouring positions, e.g. due to truck filling
  - Fast reaction time
  - Large distance to the medium
  - Interfering reflections from fixtures or protective devices
- Further recommendations
  - False signal suppression via the operating tool

**Demonstration**

- Applications that are not typical level measurements
  - Instrument demonstration
  - Object recognition/monitoring
  - Measured value verification with higher measuring accuracy with reflection without bulk solids, e.g. via a measuring plate

**Unit distance**

In this menu item you select the unit for measured distance in mm, m, in or ft.

**Adjustment**

Since the radar sensor is a distance measuring instrument, it is the distance from the sensor to the medium surface that is measured. To indicate the actual level, the measured distance must be assigned to a certain height percentage.

To perform the adjustment, enter the distance with full and empty vessel, see the following example:

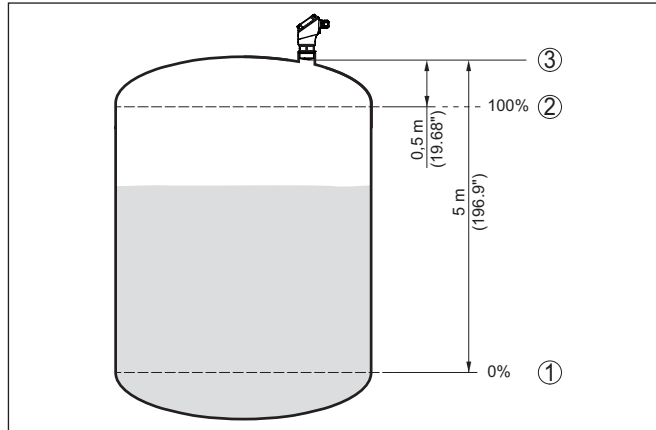


Fig. 24: Parameterisation example, Min./max. adjustment

- 1 Min. level = max. measuring distance
- 2 Max. level = min. measuring distance
- 3 Reference plane

The starting point for these distance specifications is always the reference plane, i.e. the lower edge of the sensor. Information on the reference plane can be found in the chapters "Mounting" and "Technical data". The actual filling height is then calculated on the basis of these entries.

The actual product level during this adjustment is not important, because the min./max. adjustment is always carried out without changing the product level. These settings can be made ahead of time without the instrument having to be installed.

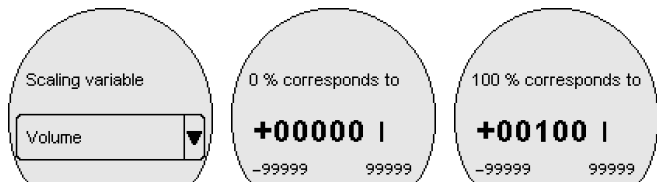
### 7.3.2 Extended functions

#### Displayed value

In the menu item "Display value" you define the indication of the measured values on the indication as filling height, distance, percent, lin. percent or scaled.

#### Scaling

In the menu item "Scaling" you define how the level value is shown on the indication. This includes the scaling size, unit and format as well as the assignment to 0 % and 100 % of the measured value. Scaling makes it possible, for example, to display the volume in m<sup>3</sup>.



#### Menu language

This menu item enables the setting of the requested national language for the display.

The following languages are available:

German, English, French, Spanish, Portuguese, Italian, Dutch, Russian, Chinese, Japanese, Turkish

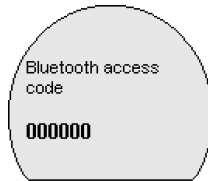
**Bluetooth access code**

In this menu item, you can change the factory-preset Bluetooth access code to your personal Bluetooth access code.



**Note:**

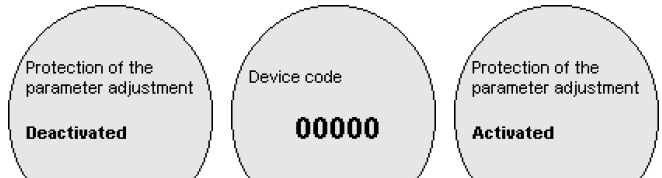
The individual preset Bluetooth access code of the device can be found on the supplied information sheet "*PINs and Codes*". If this is changed by the user and is no longer available, access is only possible via the emergency Bluetooth unlock code on the information sheet "*Emergency unlock codes*" also supplied.



For instruments without Bluetooth function, this menu item displays "*Instrument without Bluetooth*".

**Protection of the parameterization**

In the menu item "*Protection of the parameter adjustment*" you protect the sensor parameters against unwanted or unintentional changes by entering a device code.



With activated protection of the parameter adjustment, the individual menu items can be selected and displayed, however the parameters can no longer be modified.

Releasing the sensor adjustment is also possible in any menu item by entering the device code.



**Note:**

The factory set device code is "000000". If this is changed by the user and is no longer available, access is only possible via the emergency device unlock code on the information sheet "*Emergency unlock codes*" also supplied.

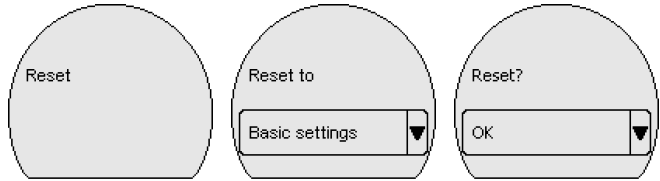


**Caution:**

With protected parameter adjustment, adjustment via the adjustment tool and other systems is also blocked.

**Reset**

During a reset, parameter settings made by the user are reset to the values of the basic setting or the delivery status (see chapter "*Menu overview*").<sup>3)</sup>

**Caution:**

For the duration of the reset, the set trouble signal is output via the current output. Within the context of the asset management function, the message "*Maintenance*" is output.

The following reset functions are available:

**Basic settings:**

Reset the parameter settings to the default values of the respective device. You will find the values in chapter "*Menu overview*".

**Note:**

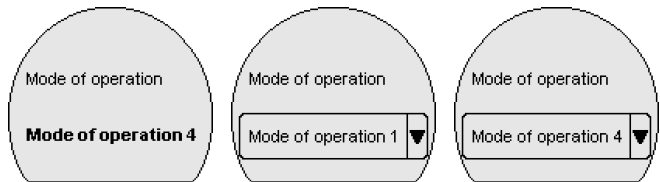
Order-related settings are not taken over into the current parameters after this reset. The currently set menu language is not reset.

**Delivery status:**

Resetting of the parameter adjustments to delivery status

**Mode of operation**

Country or region-specific settings for the radar signals are determined via the operating mode.



- Mode of operation 1: EU, Albania, Andorra, Azerbaijan, Australia, Belarus, Bosnia and Herzegovina, Canada, Egypt, Iceland, Liechtenstein, Moldavia, Monaco, Montenegro, Morocco, New Zealand, Northern Macedonia, Norway, San Marino, Saudi Arabia, Serbia, South-Africa, Switzerland, Turkey, Ukraine, United Kingdom, USA
- Mode of operation 2: Brazil, Japan, South Korea, Taiwan, Thailand
- Mode of operation 3: Chile, India, Malaysia, Zimbabwe
- Mode of operation 4: Russia, Kazakhstan

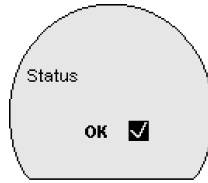
Depending on the operating mode, metrological properties of the device can change (see chapter "*Technical data, input variable*").

<sup>3)</sup> Language and Bluetooth access code are not reset.

### 7.3.3 Diagnostics

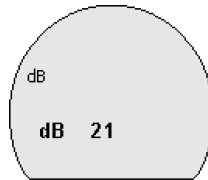
**Status**

In this menu item, the device status is displayed.



**Measurement reliability**

The measurement reliability represents the signal strength of the level echo above the detection threshold in dB. This makes it possible to assess the quality of the measurement. The measurement reliability should be at least 20 dB.



**Sensor information**

The menu item "*Sensor information*" provides the device name and serial number as well as the hardware and software version.

## 8 Setup with smartphone/tablet (Bluetooth)

### 8.1 Preparations

#### System requirements

Make sure that your smartphone/tablet meets the following system requirements:

- Operating system: iOS 13 or newer
- Operating system: Android 5.1 or newer
- Bluetooth 4.0 LE or newer

Download the VEGA Tools app from the "Apple App Store", "Google Play Store" or "Baidu Store" to your smartphone or tablet.

### 8.2 Connecting

#### Connecting

Start the adjustment app and select the function "Setup". The smartphone/tablet searches automatically for Bluetooth-capable instruments in the area.

The message "Connecting ..." is displayed.

The devices found are listed and the search is automatically continued.

Select the requested instrument in the device list.

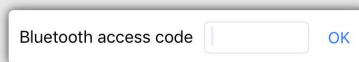
#### Authenticate

When establishing the connection for the first time, the operating tool and the sensor must authenticate each other. After the first correct authentication, each subsequent connection is made without a new authentication query.

#### Enter Bluetooth access code

For authentication, enter the 6-digit Bluetooth access code in the next menu window. You can find the code on the outside of the device housing and on the information sheet "Pins and Codes" in the device packaging.

For the very first connection, the adjustment unit and the sensor must authenticate each other.



Enter the 6 digit Bluetooth access code of your Bluetooth instrument.

Fig. 25: Enter Bluetooth access code



#### Note:

If an incorrect code is entered, the code can only be entered again after a delay time. This time gets longer after each incorrect entry.

The message "Waiting for authentication" is displayed on the smartphone/tablet.

#### Connected

After connection, the sensor adjustment menu is displayed on the respective adjustment tool.

If the Bluetooth connection is interrupted, e.g. due to a too large distance between the two devices, this is displayed on the adjustment tool. The message disappears when the connection is restored.

**Change device code**

Parameter adjustment of the device is only possible if the parameter protection is deactivated. When delivered, parameter protection is deactivated by default and can be activated at any time.

It is recommended to enter a personal 6-digit device code. To do this, go to menu "Extended functions", "Access protection", menu item "Protection of the parameter adjustment".

**8.3 Parameter adjustment**

**Enter parameters**

The sensor adjustment menu is divided into two areas, which are arranged next to each other or one below the other, depending on the adjustment tool.

- Navigation section
- Menu item display

The selected menu item can be recognized by the colour change.

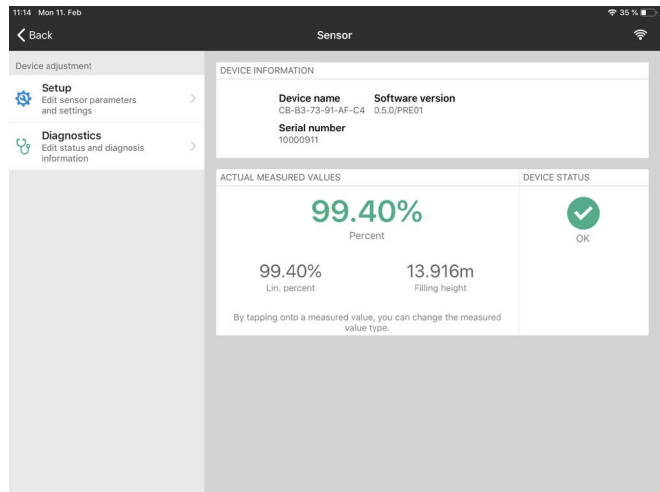


Fig. 26: Example of an app view - Setup measured values

Enter the requested parameters and confirm via the keyboard or the editing field. The settings are then active in the sensor.

Close the app to terminate connection.

## 9 Setup with PC/notebook (Bluetooth)

### 9.1 Preparations

#### System requirements

Make sure that your PC/notebook meets the following system requirements:

- Operating system Windows 10 or newer
- DTM Collection 10/2020 or newer
- Bluetooth 4.0 LE or newer

#### Activate Bluetooth connection

Activate the Bluetooth connection via the project assistant.



#### Note:

Older systems do not always have an integrated Bluetooth LE. In these cases, a Bluetooth USB adapter is required. Activate the Bluetooth USB adapter using the Project Wizard.

After activating the integrated Bluetooth or the Bluetooth USB adapter, devices with Bluetooth are found and created in the project tree.

### 9.2 Connecting

#### Connecting

Select the requested device for the online parameter adjustment in the project tree.

#### Authenticate

When establishing the connection for the first time, the operating tool and the device must authenticate each other. After the first correct authentication, each subsequent connection is made without a new authentication query.

#### Enter Bluetooth access code

For authentication, enter in the next menu window the 6-digit Bluetooth access code:

Fig. 27: Enter Bluetooth access code

You can find the code on the outside of the device housing and on the information sheet "PINs and Codes" in the device packaging.



**Note:**

If an incorrect code is entered, the code can only be entered again after a delay time. This time gets longer after each incorrect entry.

The message "Waiting for authentication" is displayed on the PC/notebook.

**Connected**

After connection, the device DTM appears.

If the connection is interrupted, e.g. due to a too large distance between device and adjustment tool, this is displayed on the adjustment tool. The message disappears when the connection is restored.

**Change device code**

Parameter adjustment of the device is only possible if the parameter protection is deactivated. When delivered, parameter protection is deactivated by default and can be activated at any time.

It is recommended to enter a personal 6-digit device code. To do this, go to menu "Extended functions", "Access protection", menu item "Protection of the parameter adjustment".

**Prerequisites**

**9.3 Parameter adjustment**

For parameter adjustment of the instrument via a Windows PC, the configuration software PACTware and a suitable instrument driver (DTM) according to FDT standard are required. The latest PACTware version as well as all available DTMs are compiled in a DTM Collection. The DTMs can also be integrated into other frame applications according to FDT standard.

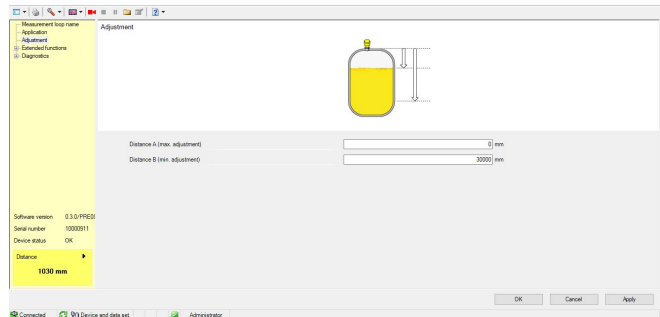


Fig. 28: Example of a DTM view - Setup, sensor adjustment

## 10 Setup with PC/notebook (VEGACONNECT)

### 10.1 Connect the PC

Via interface adapter to the signal cable

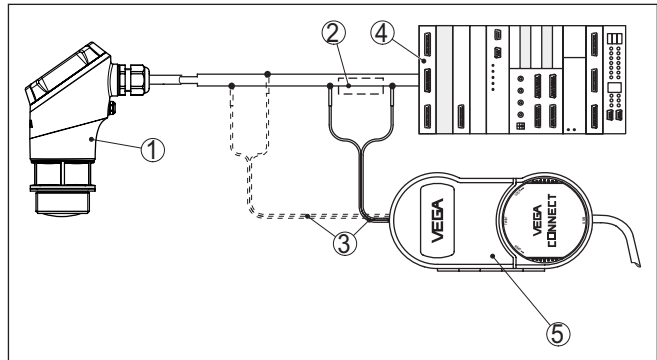


Fig. 29: Connecting the PC to the signal cable

- 1 Sensor
- 2 HART resistance 250  $\Omega$  (optional depending on evaluation)
- 3 Connection cable with 2 mm pins and terminals
- 4 Processing system/PLC/Voltage supply
- 5 Interface adapter VEGACONNECT



#### Note:

With power supply units with integrated HART resistance (internal resistance approx. 250  $\Omega$ ), an additional external resistance is not necessary. This applies, e.g. to the VEGA instruments VEGATRENN 149A, VEGAMET 381, VEGAMET 391. Common Ex separators are also usually equipped with a sufficient current limiting resistance. In such cases, the interface adapter can be connected parallel to the 4 ... 20 mA cable (dashed line in the previous illustration).

**Via interface adapter to the VEGAMET controller**

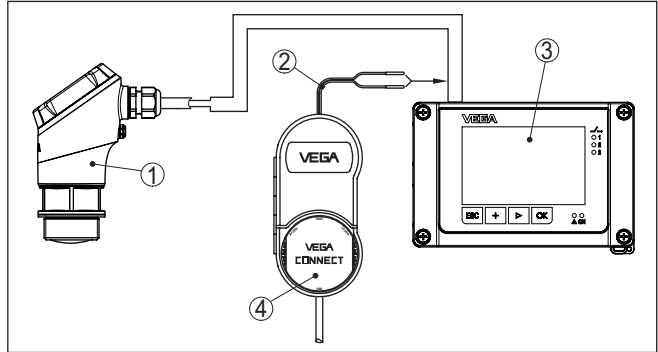


Fig. 30: Connection of the PC to the VEGAMET controller

- 1 Sensor
- 2 Connection cable with 2 mm pins
- 3 Controller, e.g. VEGAMET 841
- 4 Interface adapter VEGACONNECT

**10.2 Parameter adjustment**

**Prerequisites**

For parameter adjustment of the instrument via a Windows PC, the configuration software PACTware and a suitable instrument driver (DTM) according to FDT standard are required. The latest PACTware version as well as all available DTMs are compiled in a DTM Collection. The DTMs can also be integrated into other frame applications according to FDT standard.



**Note:**

To ensure that all instrument functions are supported, you should always use the latest DTM Collection. Furthermore, not all described functions are included in older firmware versions. You can download the latest instrument software from our homepage. A description of the update procedure is also available in the Internet.

Further setup steps are described in the operating instructions manual "DTM Collection/PACTware" attached to each DTM Collection and which can also be downloaded from the Internet. Detailed descriptions are available in the online help of PACTware and the DTMs.

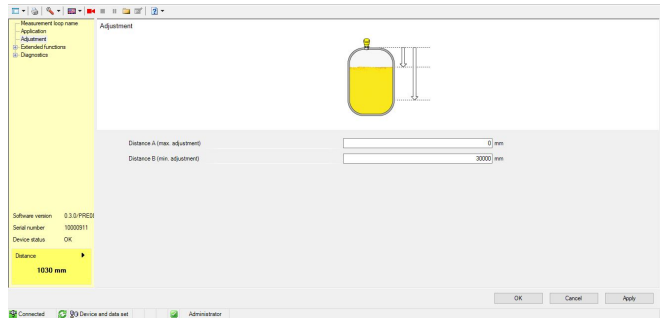


Fig. 31: Example of a DTM view

### 10.3 Save parameter adjustment data

We recommend documenting or saving the parameterisation data via PACTware. That way the data are available for multiple use or service purposes.

## 11 Menu overview

### 11.1 Display and adjustment unit (on site)

#### Measured value indication

Measured value window 1	Measured value window 2	Measured value window 2
Set display value digital and analogue	Set display value digital and analogue, Sensor-TAG	Set display value digital, Sensor-TAG

#### Main menu

Menu item	Selection	Basic settings
Medium	Liquid Bulk solid	Liquid
Application liquid	Storage tank, agitator tank, dosing tank, pumping station/pump shaft, rain overflow basin, tank/collection basin, plastic tank (measurement through tank top), mobile plastic tank (IBC), level measurement in waters, flow measurement flume/overflow, demonstration	Storage tank
Application bulk solid	Silo (slim and high), bunker (large volume), stockpile (point measurement/profile detection), crusher, demonstration	Silo (slender and high)
Units	Distance unit of the device Temperature unit of the instrument	Distance in m Temperature in °C
Adjustment	Max. adjustment (distance A) Min. adjustment (distance B)	Max. adjustment 0,000 m Min. adjustment 20,000 m

#### Extended functions

Menu item	Selection	Basic settings
Displayed value		Distance
Scaling	Scaling size Scaling unit Scaling format	0 % corresponds to 0 l 100 % correspond to 100 l
Menu language	Language	-
Bluetooth access code	-	Activated
Protection of the parameterization	Deactivated/Activated	Deactivated
	Device code	-
Reset	Delivery status, basic settings	-

Menu item	Selection	Basic settings
Mode of operation	<p>Mode of operation 1: EU, Albania, Andorra, Azerbaijan, Australia, Belarus, Bosnia and Herzegovina, Canada, Egypt, Iceland, Liechtenstein, Moldavia, Monaco, Montenegro, Morocco, New Zealand, Northern Macedonia, Norway, San Marino, Saudi Arabia, Serbia, South-Africa, Switzerland, Turkey, Ukraine, United Kingdom, USA</p> <p>Mode of operation 2: Brazil, Japan, South Korea, Taiwan, Thailand</p> <p>Mode of operation 3: Chile, India, Malaysia, Zimbabwe</p> <p>Mode of operation 4: Russia, Kazakhstan</p>	Mode of operation 1

### Diagnostics

Menu item	Selection	Basic settings
Status	Device status	-
Measurement reliability	-	-
Sensor information	Device name, serial number, hardware/software version, device revision, factory calibration date	-

## 11.2 VEGA Tools app and DTM (Bluetooth)

### Start image

Device information	Actual measured values	Device status
Device name, software version, serial number	Percent, filling height, distance, measurement reliability, electronics temperature, meas. rate etc.	OK, error indication

### Basic functions

Menu item	Selection	Basic settings
Measurement loop name	Alphanumeric characters	Sensor
Application liquid	Storage tank, agitator tank, dosing tank, pumping station/pump shaft, rain overflow basin, tank/collection basin, plastic tank (measurement through tank top), mobile plastic tank (IBC), level measurement in waters, flow measurement flume/overflow, demonstration	Storage tank
Application bulk solid	Silo (slim and high), bunker (large volume), stockpile (point measurement/profile detection), crusher, demonstration	Silo (slender and high)
Units	Distance unit of the device Temperature unit of the instrument	Distance in m Temperature in °C
Adjustment	Max. adjustment (distance A) Min. adjustment (distance B)	Max. adjustment 0,000 m Min. adjustment 20,000 m

**Extended functions**

Menu item	Selection	Basic settings
Damping	Integration time	0 s
Current output	Output characteristics	0 ... 100 % correspond to 4 ... 20 mA
	Current range	3.8 ... 20.5 mA
	Reaction when malfunctions occur	< 3.6 mA
Linearisation	Linearization type	Linear
Scaling	Scaling size	Volume
	Scaling unit	l
	Scaling format	100 l
	100 % correspond to 0 % correspond to	0 l
Display	Menu language	-
	Displayed value	Distance
	Backlight	On
Access protection	Bluetooth access code	-
	Protection of the parameterization	Deactivated
False signal suppression	Create new, extend, delete, manual entry	0 m
	Sounded distance to the medium	0 m
Interference behaviour	Last measured value, maintenance message, fault signal	Last measured value
	Time until fault signal	15 s
HART variables	First HART value (PV)	Lin. percent
	Second HART value (SV)	Distance
	Third HART value (TV)	Measurement reliability
	Fourth HART value (QV)	Electronics temperature
	Long TAG	
	Message	
Reset	Delivery status, basic settings	-
Mode of operation	Mode of operation 1: EU, Albania, Andorra, Azerbaijan, Australia, Belarus, Bosnia and Herzegovina, Canada, Egypt, Iceland, Liechtenstein, Moldavia, Monaco, Montenegro, Morocco, New Zealand, Northern Macedonia, Norway, San Marino, Saudi Arabia, Serbia, South-Africa, Switzerland, Turkey, Ukraine, United Kingdom, USA Mode of operation 2: Brazil, Japan, South Korea, Taiwan, Thailand Mode of operation 3: Chile, India, Malaysia, Zimbabwe Mode of operation 4: Russia, Kazakhstan	Mode of operation 1
Status signals	Function check	On
	Maintenance required	Off
	Out of specification	Off

**Diagnostics**

Menu item	Selection	Basic settings
Status	Device status Parameter modification counter Measured value status Status output HART Device Status Status additional measured values	-
Echo curve	Indication of echo curve	-
Peak indicator	Peak indicator distance, measurement reliability, meas. rate, electronic temperature	-
Measured values	Measured values Additional measured values Outputs	-
Sensor information	Device name, serial number, hardware/software version, device revision, factory calibration date	-
Sensor characteristics	Sensor features from order text	-
Simulation	Measured value Simulation value	-
Measured value memory (DTM)	Indication measured value memory from DTM	

## 12 Diagnostics and servicing

### 12.1 Maintenance

#### Maintenance

If the device is used properly, no special maintenance is required in normal operation.

#### Precaution measures against buildup

In some applications, buildup on the antenna system can influence the measuring result. Depending on the sensor and application, take measures to avoid heavy soiling of the antenna system. If necessary, clean the antenna system in certain intervals.

#### Cleaning

The cleaning helps that the type label and markings on the instrument are visible.

Take note of the following:

- Use only cleaning agents which do not corrode the housings, type label and seals
- Use only cleaning methods corresponding to the housing protection rating

### 12.2 Rectify faults

#### Reaction when malfunction occurs

The operator of the system is responsible for taking suitable measures to rectify faults.

#### Causes of malfunction

The device offers maximum reliability. Nevertheless, faults can occur during operation. These may be caused by the following, e.g.:

- Sensor
- Process
- Voltage supply
- Signal processing

#### Fault rectification

The first measures are:

- Evaluation of fault messages
- Checking the output signal
- Treatment of measurement errors

A smartphone/tablet with the adjustment app or a PC/notebook with the software PACTware and the suitable DTM offer you further comprehensive diagnostic possibilities. In many cases, the causes can be determined in this way and the faults eliminated.

#### Reaction after fault rectification

Depending on the reason for the fault and the measures taken, the steps described in chapter "Setup" must be carried out again or must be checked for plausibility and completeness.

#### 24 hour service hotline

Should these measures not be successful, please call in urgent cases the VEGA service hotline under the phone no. **+49 1805 858550**.

The hotline is also available outside normal working hours, seven days a week around the clock.

Since we offer this service worldwide, the support is provided in English. The service itself is free of charge, the only costs involved are the normal call charges.

### 12.3 Diagnosis, fault messages

#### 4 ... 20 mA signal

Connect a multimeter in the suitable measuring range according to the wiring plan. The following table describes possible errors in the current signal and helps to eliminate them:

Error	Cause	Rectification
4 ... 20 mA signal not stable	Fluctuating measured value	Set damping
4 ... 20 mA signal missing	Electrical connection faulty	Check connection, correct, if necessary
	Voltage supply missing	Check cables for breaks; repair if necessary
	Operating voltage too low, load resistance too high	Check, adapt if necessary
Current signal greater than 22 mA, less than 3.6 mA	Sensor electronics defective	Replace device or send in for repair depending on device version

### 12.4 Status messages according to NE 107

The instrument features self-monitoring and diagnostics according to NE 107 and VDI/VDE 2650. In addition to the status messages in the following tables there are more detailed error messages available under the menu item "Diagnostics" via the respective adjustment module.

#### Status messages

The status messages are divided into the following categories:

- Failure
- Function check
- Out of specification
- Maintenance required

and explained by pictographs:

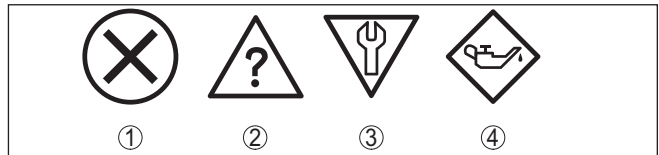


Fig. 32: Pictographs of the status messages

- 1 Failure - red
- 2 Out of specification - yellow
- 3 Function check - orange
- 4 Maintenance required - blue

#### Malfunition (Failure):

Due to a malfunction in the instrument, a fault signal is output.

This status message is always active. It cannot be deactivated by the user.

**Function check:**

The instrument is being worked on, the measured value is temporarily invalid (for example during simulation).

This status message is inactive by default.

**Out of specification:**

The measured value is unreliable because an instrument specification was exceeded (e.g. electronics temperature).

This status message is inactive by default.

**Maintenance required:**

Due to external influences, the instrument function is limited. The measurement is affected, but the measured value is still valid. Plan in maintenance for the instrument because a failure is expected in the near future (e.g. due to buildup).

This status message is inactive by default.

**Failure**

Code Text message	Cause	Rectification	DevSpec State in CMD 48
F013 no measured value available	No measured value in the switch-on phase or during operation	Check or correct installation and/or parameter settings Clean the antenna system	Byte 5, Bit 0 of Byte 0 ... 5
F017 Adjustment span too small	Adjustment not within specification	Change adjustment according to the limit values (difference between min. and max. $\geq 10$ mm)	Byte 5, Bit 1 of Byte 0 ... 5
F025 Error in the linearization table	Index markers are not continuously rising, for example illogical value pairs	Check linearization table Delete table/Create new	Byte 5, Bit 2 of Byte 0 ... 5
F036 No operable software	Checksum error if software update failed or aborted	Repeat software update Send instrument for repair	Byte 5, Bit 3 of Byte 0 ... 5
F040 Error in the electronics	Limit value exceeded in signal processing Hardware error	Restart instrument Send instrument for repair	Byte 5, Byte 5, Bit 4 of Byte 0 ... 5
F080 General software error	General software error	Restart instrument	Byte 5, Byte 5, Bit 5 of Byte 0 ... 5
F105 Determine measured value	The instrument is still in the switch-on phase, the measured value could not yet be determined	Wait for the end of the switch-on phase Duration up to 3 minutes depending on the measurement environment and parameter settings	Byte 5, Byte 5, Bit 6 of Byte 0 ... 5
F260 Error in the calibration	Checksum error in the calibration values Error in the EEPROM	Send instrument for repair	Byte 4, Bit 0 of Byte 0 ... 5

Code Text message	Cause	Rectification	DevSpec State in CMD 48
F261 Error in the instrument settings	Error during setup False signal suppression faulty Error when carrying out a reset	Repeat setup Carry out a reset	Byte 4, Bit 1 of Byte 0 ... 5
F265 Measurement function disturbed	Program sequence of the measuring function disturbed	Device restarts automatically	Byte 4, Bit 3 of Byte 0 ... 5

### Function check

Code Text message	Cause	Rectification	DevSpec State in CMD 48
C700 Simulation active	A simulation is active	Finish simulation Wait for the automatic end after 60 mins.	"Simulation Active" in "Standardized Status 0"

### Out of specification

Code Text message	Cause	Rectification	DevSpec State in CMD 48
S600 Impermissible electronics temperature	Temperature of the electronics in the non-specified range	Check ambient temperature Insulate electronics	Byte 23, Bit 4 of Byte 14 ... 24
S601 Overfilling	Danger of vessel overfilling	Make sure that there is no further filling Check level in the vessel	Byte 23, Bit 5 of Byte 14 ... 24
S603 Impermissible operating voltage	Terminal voltage too small	Check terminal voltage, increase operating voltage	Byte 23, Bit 6 of Byte 14 ... 24

### Maintenance

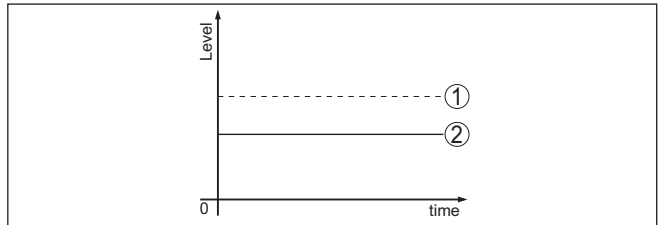
Code Text message	Cause	Rectification	DevSpec State in CMD 48
M500 Error in the delivery status	The data could not be restored during the reset to delivery status	Repeat reset Load XML file with sensor data into the sensor	Bit 0 of Byte 14 ... 24
M501 Error in the non-active linearization table	Hardware error EEPROM	Send instrument for repair	Bit 1 of Byte 14 ... 24
M507 Error in the instrument settings	Error during setup Error when carrying out a reset False signal suppression faulty	Carry out reset and repeat setup	Bit 7 of Byte 14 ... 24
M508 No executable Bluetooth software	Checksum error in Bluetooth software	Carry out software update	Bit 8 of Byte 14 ... 24

Code Text message	Cause	Rectification	DevSpec State in CMD 48
M509 Software update running	Software update running	Wait until software update is finished	Bit 9 of Byte 14 ... 24
M510 No communication with the main controller	Communication between main electronics and display module disturbed	Check the connection cable to the display Send instrument for repair	Bit 10 of Byte 14 ... 24
M511 Inconsistent software configuration	A software unit requires a software update	Carry out software update	Bit 11 of Byte 14 ... 24

### 12.5 Treatment of measurement errors

The tables below give typical examples of application-related measurement errors.

The images in column "Error description" show the actual level as a dashed line and the output level as a solid line.



- 1 Real level
- 2 Level displayed by the sensor



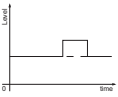
**Note:**

If the output level is constant, the cause could also be the fault setting of the current output to "Hold value".

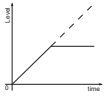
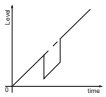
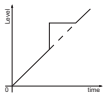
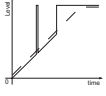

If the level is too low, the reason could be a line resistance that is too high

#### Liquids: Measurement error at constant level



Fault description	Cause	Rectification
Measured value shows a too low or too high level 	Min./max. adjustment not correct	Adapt min./max. adjustment
	Incorrect linearization curve	Adapt linearization curve

Fault description	Cause	Rectification
Measured value jumps towards 100 % 	Due to the process, the amplitude of the level echo sinks  A false signal suppression was not carried out	Carry out a false signal suppression  Determine the reason for the changed false signals, carry out false signal suppression, e.g. with condensation.
	Amplitude or position of a false signal has changed (e.g. condensation, build-up); false signal suppression no longer matches actual conditions	

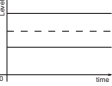
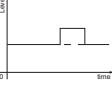
### Liquids: Measurement error during filling

Fault description	Cause	Rectification
Measured value remains unchanged during filling 	False signals in the close range too big or level echo too small  Strong foam or vortex generation  Max. adjustment not correct	Eliminate false signals in the close range  Check measuring point: Antenna should protrude out of the threaded mounting socket, possible false echoes through flange socket?  Remove contamination on the antenna  In case of interferences due to installations in the close range, change polarisation direction  Create a new false signal suppression  Adapt max. adjustment
Measured value jumps towards 0 % during filling 	The level echo cannot be distinguished from the false signal at a false signal position (jumps to multiple echo)	In case of interferences due to installations in the close range: Change polarisation direction  Chose a more suitable installation position
Measured value jumps towards 100 % during filling 	Due to strong turbulence and foam generation during filling, the amplitude of the level echo sinks. Measured value jumps to false signal	Carry out a false signal suppression
Measured value jumps sporadically to 100 % during filling 	Varying condensation or contamination on the antenna	Carry out a false signal suppression or increase false signal suppression with condensation/contamination in the close range by editing
Measured value jumps to $\geq 100$ % or 0 m distance 	Level echo is no longer detected in the close range due to foam generation or false signals in the close range. The sensor goes into overflow protection mode. The max. level (0 m distance) as well as the status message "Overflow protection" are output.	Check measuring point: Antenna should protrude out of the threaded mounting socket, possible false echoes through flange socket?  Remove contamination on the antenna


**Liquids: Measurement error during emptying**

Fault description	Cause	Rectification
<p>Measured value remains unchanged in the close range during emptying</p> 	<p>False signal larger than the level echo Level echo too small</p>	<p>Check measuring point: Antenna should protrude out of the threaded mounting socket, possible false echoes through flange socket?</p> <p>Remove contamination on the antenna</p> <p>In case of interferences due to installations in the close range: Change polarisation direction</p> <p>After eliminating the false signals, the false signal suppression must be deleted. Carry out a new false signal suppression</p>
<p>Measured value jumps sporadically towards 100 % during emptying</p> 	<p>Varying condensation or contamination on the antenna</p>	<p>Carry out false signal suppression or increase false signal suppression in the close range by editing</p> <p>With bulk solids, use radar sensor with purging air connection</p>

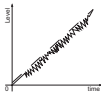
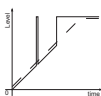
**Bulk solids: Measurement error at constant level**

Fault description	Cause	Rectification
<p>Measured value shows a too low or too high level</p> 	<p>Min./max. adjustment not correct</p> <p>Incorrect linearization curve</p>	<p>Adapt min./max. adjustment</p> <p>Adapt linearization curve</p>
<p>Measured value jumps towards 100 %</p> 	<p>Due to the process, the amplitude of the product echo decreases</p> <p>A false signal suppression was not carried out</p> <p>Amplitude or position of a false signal has changed (e.g. condensation, build-up); false signal suppression no longer matches actual conditions</p>	<p>Carry out a false signal suppression</p> <p>Determine the reason for the changed false signals, carry out false signal suppression, e.g. with condensation.</p>

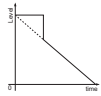
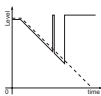
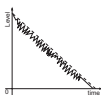
**Bulk solids: Measurement error during filling**

Fault description	Cause	Rectification
<p>Measured value jumps towards 0 % during filling</p> 	<p>The level echo cannot be distinguished from the false signal at a false signal position (jumps to multiple echo)</p> <p>Transverse reflection from an extraction funnel, amplitude of the transverse reflection larger than the level echo</p>	<p>Remove/reduce false signal: minimize interfering installations by changing the polarization direction</p> <p>Chose a more suitable installation position</p> <p>Direct sensor to the opposite funnel wall, avoid crossing with the filling stream</p>

57820-EN-250711

Fault description	Cause	Rectification
Measured value fluctuates around 10 ... 20 % 	Various echoes from an uneven medium surface, e.g. a material cone	Check parameter "Material Type" and adapt, if necessary  Optimize installation position and sensor orientation
	Reflections from the medium surface via the vessel wall (deflection)	Select a more suitable installation position, optimize sensor orientation, e.g. with a swivelling holder
Measured value jumps sporadically to 100 % during filling 	Changing condensation or contamination on the antenna	Carry out a false signal suppression or increase false signal suppression with condensation/contamination in the close range by editing

### Bulk solids: Measurement error during emptying

Fault description	Cause	Rectification
Measured value remains unchanged in the close range during emptying 	False signal greater than level echo or level echo too small	Eliminate false signals in the close range. Check: Antenna must protrude out of the nozzle  Remove contamination on the antenna  Minimize interfering installations in the close range by changing the polarization direction  After eliminating the false signals, the false signal suppression must be deleted. Carry out a new false signal suppression
Measured value jumps sporadically towards 100 % during emptying 	Changing condensation or contamination on the antenna	Carry out false signal suppression or increase false signal suppression in the close range by editing
Measured value fluctuates around 10 ... 20 % 	Various echoes from an uneven medium surface, e.g. an extraction funnel	Check parameter "Material Type" and adapt, if necessary
	Reflections from the medium surface via the vessel wall (deflection)	Optimize installation position and sensor orientation

## 12.6 Software update

The device software can be updated in the following ways:

- HART signal
- Bluetooth

The following components are required:

- Instrument
- Voltage supply
- Interface adapter VEGACONNECT
- PC with PACTware/DTM and Bluetooth USB adapter
- Current instrument software as file

You can find the current instrument software as well as detailed information on the procedure in the download area of our homepage: [www.vega.com](http://www.vega.com).

**Caution:**

Instruments with approvals can be bound to certain software versions. Therefore make sure that the approval is still effective after a software update is carried out.

You can find detailed information in the download area at [www.vega.com](http://www.vega.com).

## 12.7 How to proceed if a repair is necessary

On our homepage you will find detailed information on how to proceed in the event of a repair.

So that we can carry out the repair quickly and without queries, generate a instrument return form there with the data of your device.

The following is required:

- The serial number of the instrument
- A short description of the fault
- Details of the medium, if applicable

Print the generated instrument return form.

Clean the instrument and pack it damage-proof.

Send the printed instrument return form and possibly a safety data sheet together with the device.

You will find the address for the return on the generated instrument return form.

## 13 Dismount

### 13.1 Dismounting steps

To remove the device, carry out the steps in chapters "*Mounting*" and "*Connecting to power supply*" in reverse.



**Warning:**

When dismantling, pay attention to the process conditions in vessels or pipelines. There is a risk of injury, e.g. due to high pressures or temperatures as well as aggressive or toxic media. Avoid this by taking appropriate protective measures.

### 13.2 Disposal



Pass the instrument on to a specialised recycling company and do not use the municipal collecting points.

Remove any batteries in advance, if they can be removed from the device, and dispose of them separately.

If personal data is stored on the old device to be disposed of, delete it before disposal.

If you have no way to dispose of the old instrument properly, please contact us concerning return and disposal.

## 14 Certificates and approvals

### 14.1 Radio licenses

#### Radar

The device has been tested and approved in accordance with the current edition of the applicable country-specific norms or standards.

Regulations for use can be found in the document "*Regulations for radar level measuring instruments with radio licenses*" on our homepage.

#### Bluetooth

The Bluetooth radio module in the device has been tested and approved according to the current edition of the applicable country-specific norms or standards.

The confirmations as well as regulations for use can be found in the document "*Radio licenses*" supplied or on our homepage.

### 14.2 Approvals for Ex areas

Approved versions for use in hazardous areas are available or in preparation for the device or the device series.

You can find the relevant documents on our homepage.

### 14.3 Approvals as overfill protection

Approved versions for use as part of an overfill protection system are available or in preparation for the device or the device series.

The corresponding approvals can be found on our homepage.

### 14.4 Metrological approvals

Approved versions, e.g. as certified measuring system for flow according to MCERTS, are available or in preparation for the device series.

Regulations for use can be found in the corresponding certificate on our homepage.

### 14.5 Food and pharmaceutical certificates

Versions for use in the food and pharmaceutical industries are available or in preparation for the device or the device series.

The corresponding certificates can be found on our homepage.

### 14.6 Conformity

The device complies with the legal requirements of the applicable country-specific directives or technical regulations. We confirm conformity with the corresponding labelling.

The corresponding conformity declarations can be found on our homepage.

### 14.7 NAMUR recommendations

NAMUR is the automation technology user association in the process industry in Germany. The published NAMUR recommendations are accepted as the standard in field instrumentation.

The device fulfils the requirements of the following NAMUR recommendations:

- NE 21 – Electromagnetic compatibility of equipment
- NE 43 – Signal level for fault information from measuring transducers
- NE 53 – Compatibility of field devices and display/adjustment components
- NE 107 – Self-monitoring and diagnosis of field devices

For further information see [www.namur.de](http://www.namur.de).

### 14.8 Environment management system

Protection of the environment is one of our most important duties. That is why we have introduced an environment management system with the goal of continuously improving company environmental protection. The environment management system is certified according to DIN EN ISO 14001.

Help us to meet these requirements and observe the environmental instructions in the chapters "*Packaging, transport and storage*", "*Disposal*" of this instructions manual.

## 15 Supplement

### 15.1 Technical data

#### Note for approved instruments

The technical data in the respective safety instructions which are included in delivery are valid for approved instruments (e.g. with Ex approval). These data can differ from the data listed herein, for example regarding the process conditions or the voltage supply.

All approval documents can be downloaded from our homepage.

#### Materials and weights

##### Materials, wetted parts

- |                              |           |
|------------------------------|-----------|
| – Antenna, process fitting   | PVDF      |
| – Process seal <sup>4)</sup> | FKM, EPDM |

##### Materials, non-wetted parts

- |  |                         |
|--|-------------------------|
| – Housing                              | Plastic PBT (Polyester) |
| – Housing seals                        | O-rings (silicone)      |
| – Cable gland                          | PA                      |
| – Sealing, cable gland                 | EPDM                    |
| – Blind plug, cable gland              | PA                      |
| – Inspection window for the indication | Polycarbonate           |
| Weight                                 | 0.7 kg (1.543 lbs)      |

#### Torques

- |  |                      |
|--|----------------------|
| Max. torque mounting boss                          | 7 Nm (5.163 lbf ft)  |
| Max. torque for NPT cable glands and Conduit tubes | 10 Nm (7.376 lbf ft) |

#### Input variable

- |                   |  |
|-------------------|--|
| Measured variable | The measured variable is the distance between the antenna edge of the sensor and the medium surface. The antenna edge is also the reference plane for the measurement. |
|-------------------|--|

<sup>4)</sup> G type threaded connections only, EPDM for devices with food/pharmaceutical certification

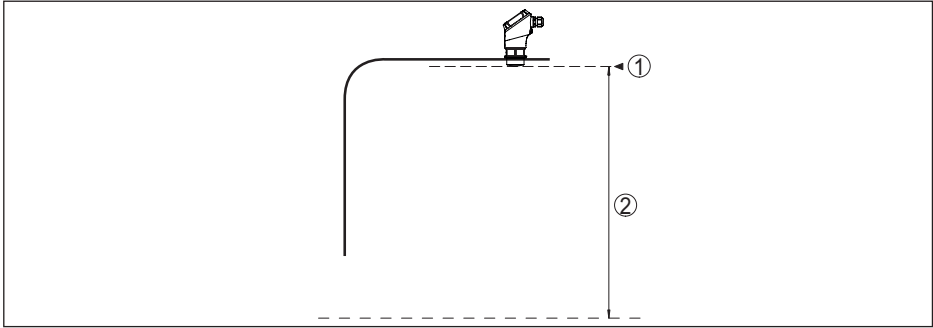


Fig. 33: Data of the input variable

- 1 Reference plane
- 2 Measured variable, max. measuring range

Max. measuring range <sup>5)</sup>	20 m (65.62 ft)
Recommended measuring range <sup>6)</sup>	up to 10 m (32.81 ft)
blocking distance <sup>7)</sup>	
– Modes of operation 1, 2, 4	0 mm (0 in)
– Mode of operation 3	≥ 250 mm (9.843 in)

### Switch-on phase

Run-up time for  $U_B = 12\text{ V DC}, 18\text{ V DC}, < 15\text{ s}$   
 24 V DC

Starting current for run-up time ≤ 3.6 mA

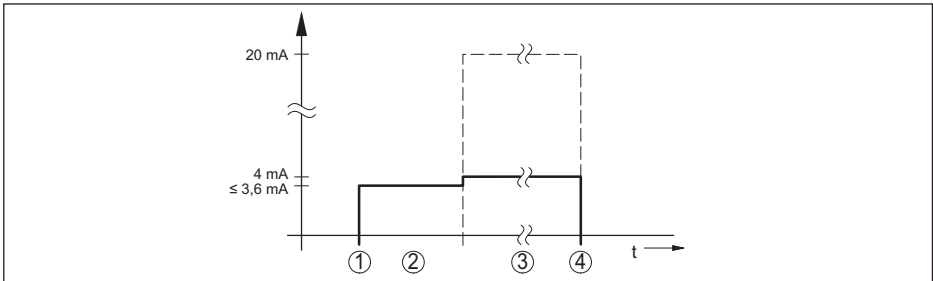


Fig. 34: Run-up time and measured value output

- 1  $U_B$  On
- 2 Run-up time
- 3 Measured value output
- 4  $U_B$  Off

<sup>5)</sup> Depending on application, medium as well as specifications by metrological approvals

<sup>6)</sup> With bulk solids

<sup>7)</sup> Depending on the operating conditions

Power consumption

Sensor current	Operating voltage		
	12 V DC	18 V DC	24 V DC
≤ 3.6 mA	< 45 mW	< 65 mW	< 90 mW
4 mA	< 50 mW	< 75 mW	< 100 mW
20 mA	< 245 mW	< 370 mW	< 485 mW

**Output variable**

Output signal	4 ... 20 mA/HART
Range of the output signal	3.8 ... 20.5 mA/HART (default setting)
Signal resolution	0.3 μA
Resolution, digital	1 mm (0.039 in)
Fault signal, current output (adjustable)	≤ 3.6 mA, ≥ 21 mA, last valid measured value
Max. output current	22 mA
Starting current	≤ 3.6 mA; ≤ 10 mA for 5 ms after switching on
Load	See load resistance under Power supply
Damping (63 % of the input variable), adjustable	0 ... 999 s
HART output values <sup>8)</sup>	
– PV (Primary Value)	Lin. percent
– SV (Secondary Value)	Distance
– TV (Third Value)	Measurement reliability
– QV (Fourth Value)	Electronics temperature
Fulfilled HART specification	7.0
Further information on Manufacturer ID, Device ID, Device Revision	See website of FieldComm Group

**Deviation (according to DIN EN 60770-1)**

Process reference conditions according to DIN EN 61298-1

- Temperature +18 ... +30 °C (+64 ... +86 °F)
- Relative humidity 45 ... 75 %
- Air pressure 860 ... 1060 mbar/86 ... 106 kPa (12.5 ... 15.4 psig)

Installation reference conditions

- Distance to installations > 200 mm (7.874 in)
- Reflector Flat plate reflector
- False reflections Biggest false signal, 20 dB smaller than the useful signal

Deviation with liquids ≤ 2 mm (meas. distance > 0.25 m/0.8202 ft)

Non-repeatability<sup>9)</sup> ≤ 2 mm

<sup>8)</sup> The values for SV, TV and QV can be assigned as required.

<sup>9)</sup> Already included in the meas. deviation

## Deviation with bulk solids

The values depend to a great extent on the application.  
Binding specifications are thus not possible.

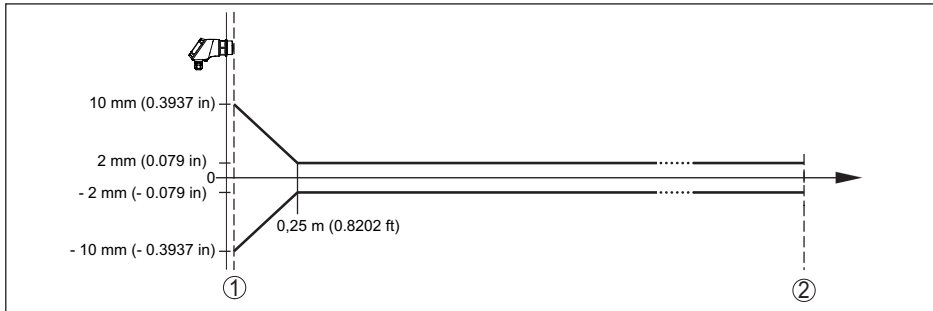


Fig. 35: Deviation under reference conditions<sup>10)</sup>

1 Antenna edge, reference plane

2 Recommended measuring range

### Variables influencing measurement accuracy<sup>11)</sup>

#### Specifications apply to the digital measured value

Temperature drift < 3 mm/10 K, max. 5 mm

Additional deviation through electromagnetic interference < ±10 mm<sup>12)</sup>

#### Specifications apply also to the current output

Temperature drift < 0.03 %/10 K or max. 0.3 % relating to the 16.7 mA span

Deviation in the current output due to digital/analogue conversion < 15 µA

Additional measurement deviation through electromagnetic interference < 80 µA<sup>13)</sup>

– For sensors with ship approval<sup>14)</sup> < 250 µA

### Characteristics and performance data

Radar signal FMCW (Frequency-Modulated-Continuous-Wave)

Measuring frequency W-band (80 GHz technology)

Measuring cycle time<sup>15)</sup> ≤ 250 ms

Step response time<sup>16)</sup> ≤ 3 s

<sup>10)</sup> In case of deviations from reference conditions, the offset due to installation can be up to ± 4 mm. This offset can be compensated by the adjustment.

<sup>11)</sup> Determination of the temperature drift acc. to the limit point method

<sup>12)</sup> The specified measurement deviation of ±10 mm due to electromagnetic interference is used as test criteria for the EMC immunity tests and is therefore to be understood as maximum value.

<sup>13)</sup> The specified measurement deviation of ± 80 µA due to electromagnetic interference is used as test criteria for the EMC immunity tests and is therefore to be understood as maximum value.

<sup>14)</sup> According to IACS E10 (shipbuilding)/IEC 60945

<sup>15)</sup> With operating voltage  $U_b \geq 24$  V DC

<sup>16)</sup> Time span after a sudden distance change from 1 m to 5 m until the output signal reaches 90 % of the final value for the first time (IEC 61298-2). Valid with operating voltage  $U_b \geq 24$  V DC.

Beam angle <sup>17)</sup>	8°
Emitted HF power (depending on the parameter setting) <sup>18)</sup>	
– Average spectral transmission power density	-3 dBm/MHz EIRP
– Max. spectral transmission power density	+34 dBm/50 MHz EIRP
– Max. power density at a distance of 1 m	< 3 μW/cm <sup>2</sup>

---

### Ambient conditions

Ambient temperature device	-40 ... +70 °C (-40 ... +158 °F)
Ambient temperature display	-25 ... +70 °C (-13 ... +158 °F)
Storage and transport temperature	-40 ... +80 °C (-40 ... +176 °F)

---

### Mechanical environmental conditions

Vibrations (oscillations)	Class 4M8 acc. to IEC 60721-3-4 (5 g, 4 ... 200 Hz)
Impacts (mechanical shock)	Class 6M4 acc. to IEC 60721-3-6 (50 g; 2.3 ms)
Impact resistance	IK07 acc. to IEC 62262

---

### Process conditions

For the process conditions, please also note the specifications on the type label. The lowest value (amount) always applies.

Process temperature	-40 ... +80 °C (-40 ... +176 °F)
Process pressure	-1 ... 3 bar (-100 ... 200 kPa/-14.5 ... 43.51 psig)

---

### Electromechanical data

Cable entry	
– Options	M20 x 1.5; ½ NPT
– Cable gland	M20 x 1.5 (cable diameter 5 ... 9 mm)
– Closing cap	½ NPT
Wire cross-section (spring-loaded terminals)	
– Massive wire, stranded wire	0.2 mm <sup>2</sup> (AWG 24) ... 2.5 mm <sup>2</sup> (AWG 14)
– Stranded wire with end sleeve	0.2 mm <sup>2</sup> (AWG 24) ... 1.5 mm <sup>2</sup> (AWG 16)

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### Bluetooth interface

Bluetooth standard	Bluetooth 5.0
Frequency	2.402 ... 2.480 GHz
Max. emitted power	+2.2 dBm
Max. number of participants	1

<sup>17)</sup> Outside the specified beam angle, the energy level of the radar signal is 50% (-3 dB) less.

<sup>18)</sup> EIRP: Equivalent Isotropic Radiated Power

Effective range typically 25 m (82 ft)<sup>19)</sup>

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### Indication

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Measured value and menu display

- Graphic-capable LC display, with lighting digital and quasianalogue indication
- Max. indicating range -99999 ... 99999

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### Adjustment

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- Adjustment elements 3 x keys for menu adjustment
- PC/Notebook PACTware/DTM
- Smartphone/Tablet Adjustment app

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### Voltage supply

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Operating voltage  $U_B$

- at 4 mA 12 ... 35 V DC
- at 20 mA 9 ... 35 V DC

Operating voltage  $U_B$  - illuminated display and adjustment unit 15 ... 35 V DC

Reverse voltage protection Integrated

Permissible residual ripple

- for  $U_N$  12 V DC ( $9 \text{ V} < U_B < 14 \text{ V}$ )  $\leq 0.7 V_{\text{eff}}$  (16 ... 400 Hz)
- for  $U_N$  24 V DC ( $18 \text{ V} < U_B < 35 \text{ V}$ )  $\leq 1.0 V_{\text{eff}}$  (16 ... 400 Hz)

Load resistor

- Calculation  $(U_B - U_{\text{min}})/0.022 \text{ A}$
- Example -  $U_B = 24 \text{ V DC}$   $(24 \text{ V} - 12 \text{ V})/0.022 \text{ A} = 545 \Omega$

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### Overvoltage protection

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Dielectric strength against metallic mounting parts > 10 kV

Overvoltage resistance (test impulse voltages 1.2/50  $\mu\text{s}$  at 42  $\Omega$ ) > 1000 V

Additional overvoltage arrester Due to the floating structure of the electronics and comprehensive insulation measures generally not necessary.

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### Electrical protective measures

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Potential separation Electronics potential free up to 500 V AC

Protection rating IP66/IP67 acc. to IEC 60529  
Type 4X acc. to UL 50

Altitude above sea level 5000 m (16404 ft)

Protection class III

Pollution degree 4

<sup>19)</sup> Depending on the local conditions

15.2 Dimensions

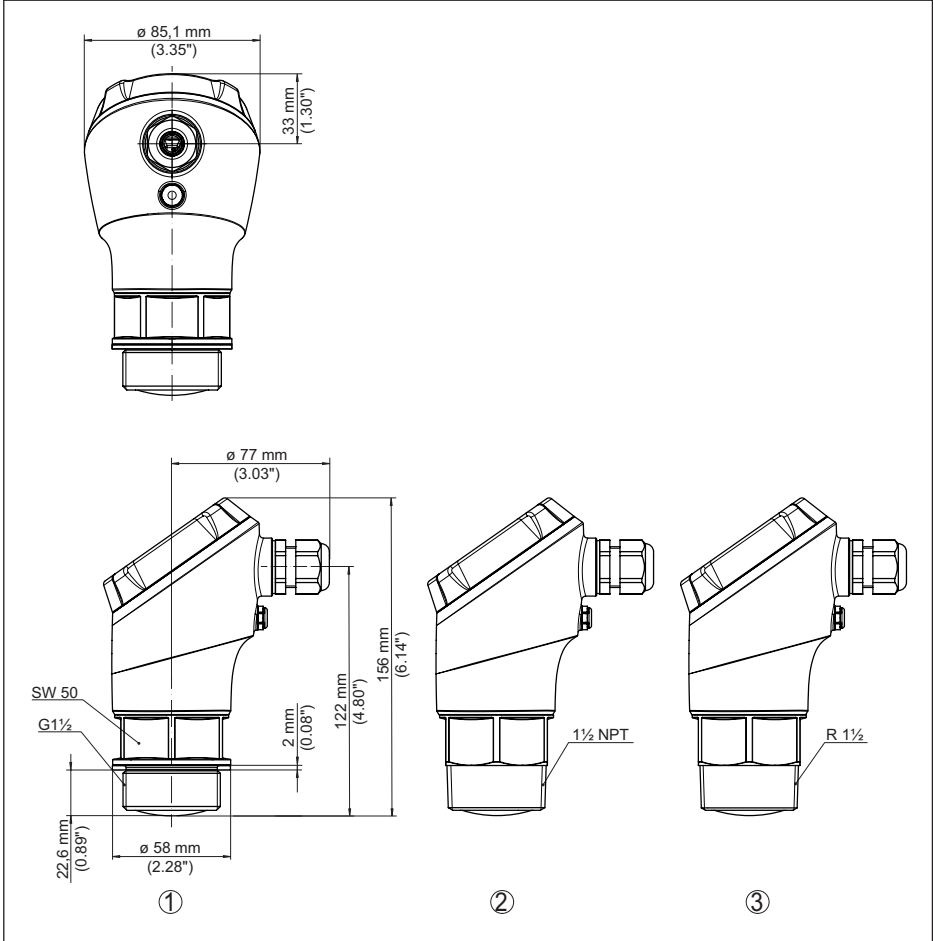


Fig. 36: Dimensions VEGAPULS 31

- 1 Thread G1½
- 2 Thread 1½ NPT
- 3 Thread R1½

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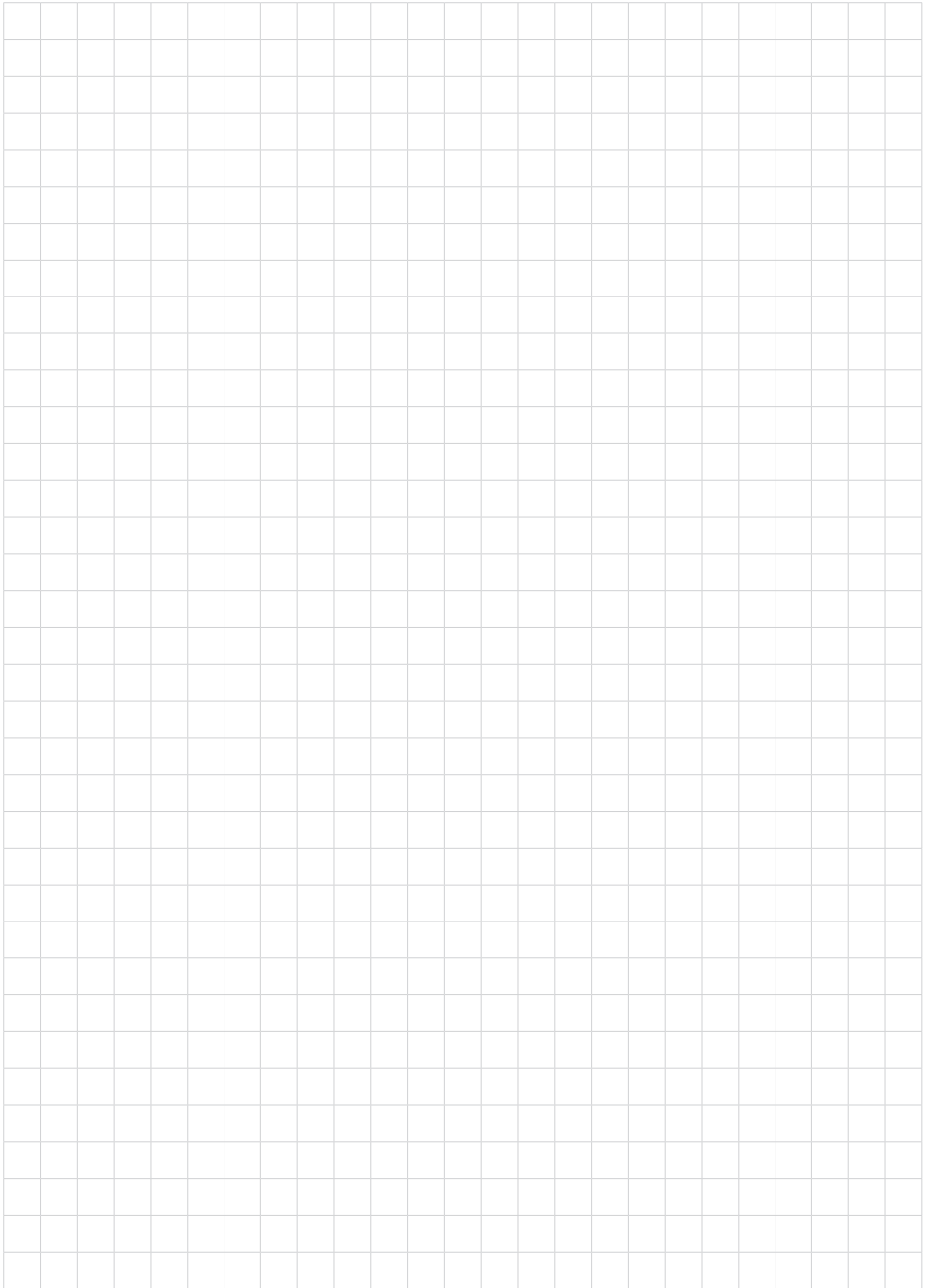
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VEGA Grieshaber KG  
Am Hohenstein 113  
77761 Schiltach  
Germany

Phone +49 7836 50-0  
E-mail: [info.de@vega.com](mailto:info.de@vega.com)  
[www.vega.com](http://www.vega.com)